# On constrained and regularized high-dimensional regression * 

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#### Abstract

High-dimensional feature selection has become increasingly crucial for seeking parsimonious models in estimation. For selection consistency, we derive one necessary and sufficient condition formulated on the notion of degree-of-separation. The minimal degree of separation is necessary for any method to be selection consistent. At a level slightly higher than the minimal degree of separation, selection consistency is achieved by a constrained $L_{0}$-method and its computational surrogate-the constrained truncated $L_{1}$-method. This permits up to exponentially many features in the sample size. In other words, these methods are optimal in feature selection against any selection method. In contrast, their regularization counterparts-the $L_{0}$-regularization and truncated $L_{1}$-regularization methods enable so under slightly stronger assumptions. More importantly, sharper parameter estimation/prediction is realized through such selection, leading to minimax parameter estimation. This, otherwise, is impossible in absence of a good selection method for high-dimensional analysis.


Key Words: Constrained regression, parameter and nonparametric models, nonconvex regularization, difference convex programming, $(p, n)$ versus fixed $p$-asymptotics.

## 1 Introduction

Feature selection is one effective means for sparse modeling in knowledge discovery. Despite progress in low-dimensional analysis, there remain many important issues. One such issue is to what extent informative features can be reconstructed given a limited amount of data at hand. Towards high-dimensional feature selection, we derive one necessary condition for feature selection, which is attainable by the constrained method and is nearly attained by the method of regularization. On this basis, we further explore these methods for parameter estimation as a result of such a selection.

[^0]Consider feature selection based on a random sample $\left(Y_{i}, \boldsymbol{x}_{i}\right)_{i=1}^{n}$ from:

$$
\begin{equation*}
Y_{i}=\mu_{i}+\epsilon_{i} ; \mu_{i}=\boldsymbol{x}_{i}^{T} \boldsymbol{\beta}^{0} ; \epsilon_{i} \sim N\left(0, \sigma^{2}\right) ; \quad i=1, \cdots, n, \tag{1}
\end{equation*}
$$

where $\boldsymbol{\beta}^{0}=\left(\beta_{1}^{0}, \cdots, \beta_{p}^{0}\right)=\left(\boldsymbol{\beta}_{A_{0}}, \mathbf{0}_{A_{0}^{c}}\right)^{T}$ and $\boldsymbol{x}_{i}=\left(x_{i 1}, \cdots, x_{i p}\right)^{T}$ are $p$-dimensional vectors of regression coefficients and features (predictors), and $\boldsymbol{x}_{i}$ is independent of random error $\epsilon_{i}$. In (1), feature selection estimates $A_{0}=\left\{j: \beta_{j}^{0} \neq 0\right\}$ of informative features, together with estimation of true coefficients $\boldsymbol{\beta}^{0}=\left(\boldsymbol{\beta}_{A_{0}}, \mathbf{0}_{A_{0}^{c}}\right)^{T}$, where $\mathbf{0}_{A_{0}^{c}}$ denotes a vector of 0 's over its complement $A_{0}^{c}$ of $A_{0}$, and representation $\mu=\boldsymbol{\beta}^{T} \boldsymbol{x}$ is generic, encompassing, for instance, linear regression and basis pursuit (Chen et al., 2001). Of particular interest is a high-dimensional situation in which $p$ can be much larger than $n$, and $A_{0}$ may depend on ( $p, n$ ) with $p_{0}=\left|A_{0}\right|$, where $|A|$ denotes the size of set $A$. This describes parametric and nonparametric cases, with $A_{0}$ corresponding to a true model as in the parametric case when $A_{0}$ is independent of $(p, n)$, and a best approximation of a true model as in basis pursuit otherwise.

Recently, considerable effort has been devoted to selection consistency under (1) to push feature selection into an ultra-high dimensional situation. In a situation as such, little is known about selection consistency for many methods in terms of $(p, n)$-asymptotics as $n, p \rightarrow \infty$, although some methods such as adaptive Lasso (Zou, 2006; Zou and Li, 2008) have been examined for fixed $p$-asymptotics as $n \rightarrow \infty$. For $(p, n)$-asymptotics, Bayesian information criterion (BIC, Schwarz, 1978), which is derived under a fixed $p$-asymptotic approximation of the posterior model probability, needs to be modified to accommodate a higher-dimension. In Chen and Chen (2008), it is showed that a modified BIC is selection consistent when $p$ is of order of $n^{\kappa}$ for some $\kappa>0$; Liu and Yang (2010) proved that another modified BIC allows $p$ to be an order of $\exp \left(c p_{0} n\right)$ for some $c>0$. It appears that exponentially many features are possible for some methods. For $L_{1}$-regularizationLasso (Tibshirani, 1996), Meinshausen and Buhlmann (2006), Zhao and Yu (2006), Zhang and Huang (2006) and Wainwight (2009) proved that the Lasso is sign consistent and thus selection consistent, under a strong irrepresentable assumption that is nearly necessary. As
pointed in Zhang (2010), this assumption is restrictive because of nonadaptiveness of the Lasso. For the smoothly clipped absolute deviation (SCAD, Fan and Li, 2001) regularization, Kim et al. (2008), and Lv and Fan (2009) showed that some consistent local minimizers exist for SCAD. More recently, Zhang (2010) proved that the minimum concavity penalty (MCP) is selection consistent under a sparse Riesz condition and an information requirement, where the sparse Riesz condition is weaker than the irrepresentable assumption; Shen et al. (2012) showed that a global minimizer of the constrained $L_{0}$-method is selection consistent, under a "degree-of-separation" condition under the Hellinger distance. To understand how a method performs in a high-dimensional situation, it is imperative that we study necessary and sufficient conditions for selection consistency for feature selection, which is a nonconvex problem itself.

This paper establishes results with selection consistency. First, we characterize consistent feature selection for any method through one simple necessary condition in the $L_{2}$-metric, which is sufficient up to a constant factor. Now define a measure of the level of difficulty for feature selection: $C_{\text {min }}=C_{\text {min }}\left(\boldsymbol{\beta}^{0}, \boldsymbol{X}\right) \equiv \min _{\left\{\beta_{A}: A \neq A_{0},|A| \leq p_{0}\right\}} \frac{1}{n \max \left(\left|A_{0} \backslash A\right|, 1\right)} \| \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}-$ $\boldsymbol{X}_{A} \boldsymbol{\beta}_{A} \|^{2}, \boldsymbol{X}_{A}$ and $\boldsymbol{\beta}_{A}$ are the design matrix for subset $A$ of predictors and the regression coefficient vector over $A$, and $\|\cdot\|$ is the usual Euclidean-norm in $\mathcal{R}^{n}$. The measure $C_{\text {min }}$ defines the degree of separation between $A_{0}$ and a least favorable candidate model for feature selection in the $L_{2}$-norm, which occurs among candidate models of sizes $p_{0}$ or less. As indicated in Theorem 1, roughly, a requirement for selection consistency is

$$
\begin{equation*}
C_{\min }\left(\boldsymbol{\beta}^{0}, \boldsymbol{X}\right) \geq d_{1} \sigma^{2} \frac{\log p}{n} \tag{2}
\end{equation*}
$$

for some positive constant $d_{1} \leq 1 / 4$ that may depend on $\boldsymbol{X}$. In short, the minimal degree of separation is required for correct identification of informative features, translating to an upper bound on $p$ that is in an order of $\exp \left(n \frac{C_{\text {min }}}{d_{1} \sigma^{2}}\right)$, for any method and $\left(\boldsymbol{\beta}_{0}, \boldsymbol{X}\right)$. This further sharpens the result of Shen et al. (2012) in (1). In view of (2), the Lasso does not achieve feature selection under (2), and it remains unknown if either the SCAD or MCP does.

This paper addresses an attainment issue of the necessary condition (2) with regard to $\left(p_{0}, p, n\right)$. Specifically, we prove, in Theorems 2 and 3, selection consistency is achieved under (2) by global minimizers of the constrained $L_{0}$-method and its computational surrogate- the truncated $L_{1}$-method for some $d_{1}>0$, respectively defined in (8) and (13). Most importantly, as showed in Theorems 4 and 5 , its regularization counterparts defined in (9) and (16) yield selection consistency under a stronger version of (2):

$$
\begin{equation*}
C_{\min }^{*} \geq d_{1} \sigma^{2} \frac{\log p}{n}, \text { if } \alpha>1, \quad C_{\min }^{*} \geq d_{1} \sigma^{2} \frac{p_{0} \max \left(\log \frac{p}{p_{0}}, 1\right)}{n}, \text { if } \alpha=1 \tag{3}
\end{equation*}
$$

for some $d_{1}>0$, where $C_{\min }^{*} \equiv \min _{\left\{\beta_{A}: A \neq A_{0},|A| \leq \alpha p_{0}\right\}} \frac{1}{n \max \left(\left|A_{0} \backslash A\right|, 1\right)}\left\|\boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}-\boldsymbol{X}_{A} \boldsymbol{\beta}_{A}\right\|^{2}$. This says that the $L_{0}$-regularization and truncated $L_{1}$-regularization methods are optimal when $p_{0}$ is independent of $(p, n)$, as in the parametric case, but may be suboptimal when $p_{0}$ depends on $(p, n)$. In this sense, the constrained method is more preferable because of its theoretical merits. Note that these two methods are not equivalent for a nonconvex problem, which is unlike an $L_{1}$ problem. Moreover, for these methods, selection consistency holds uniformly over $B_{0}(u, l)=\left\{\boldsymbol{\beta}: p_{0}=\sum_{j=1}^{p} I\left(\beta_{j} \neq 0\right) \leq u, C_{\min }(\boldsymbol{\beta}, \boldsymbol{X}) \geq l\right\}$ with $l=d_{1} \sigma^{2} \frac{\log p}{n}$ and constant $d_{1}>0$, which is called an $L_{0}$-band with upper and lower radii $u$ and $l(u>l>0)$, and is a subset of an $L_{0}$-ball that is most relevant to feature selection.

This paper also addresses another issue - parameter estimation involving feature selection. In a low-dimensional situation, it is known that Akaike's information criterion (Akaike, 1973) is optimal in parameter estimation/prediction even if it can be inconsistent in feature selection, c.f., Yang and Barron (1998). In other words, optimal parameter estimation can be achieved without feature selection. In a high-dimensional situation, it is no longer the case. In (1), the minimax rate of convergence in the $L_{2}$-norm over an $L_{0}$-ball $B_{0}(u, 0)$ is $\sqrt{\frac{u \log (p / u)}{n}}$ Raskutti et al. (2009), which is optimal for parameter estimation without feature selection. As to be seen, sharper accuracy of parameter estimation can be achieved through removal of noninformative features by a good selection method. In particular, as showed in Theorems 2-6, a minimax rate $\sqrt{\frac{u}{n}}$ in the $L_{2}$-risk over an $L_{0}$-band $B_{0}(u, l)$ with some $u>l>0$ is achieved by the constrained $L_{0}$-method as well as its regularization counterpart.

Note that excluding a neighborhood of the origin for an $L_{0}$-band $B_{0}(u, l)$ is necessary to assure existence of a good selection method, as suggested by (2). Moreover, the corresponding estimators defined by these methods are asymptotic minimax over $B_{0}(u, l)$, recovering the optimal risk of the oracle estimator, defined as the least squares estimator given $A_{0}$. In short, sharper optimal parameter estimation is achieved by the constrained $L_{0}$-method and $L_{0}$-regularization method. This is impossible without removal of noninformative features (Raskutti et al., 2009). To our knowledge, it remains largely unknown if this property is shared by other methods.

Finally, for constrained truncated $L_{1}$-regression, we derive a constrained difference convex (DC) algorithm that is showed to be equivalent to its unconstrained DC algorithm of Shen et al. (2012) with respect to their solutions, although constrained $L_{0^{-}}$-regression and $L_{0^{-}}$ regularization methods are not generally equivalent with regard to their global minimizers. Importantly, we show that a local minimizer of the regularization criterion does share the desirable properties as a global minimizer under stronger assumptions, c.f., Theorem 6.

The paper is organized in five sections. Section 2 derives the necessary condition (2) for selection consistency. Section 3 constructs an optimal constrained method to address the attainment issue, in addition to optimal parameter estimation. Section 4 derives parallel results for its regularization counterpart. Section 5 establishes equivalence between a constrained DC algorithm and its unconstrained counterpart with regard to their solutions. The appendix contains technical proofs.

## 2 Necessary conditions

This section establishes the necessary condition (2) by estimating the minimal degree of separation required for selection consistency.

Selection consistency requires that $P\left(\hat{A} \neq A_{0}\right) \rightarrow 0$ as $n, p \rightarrow \infty$ under the true probability $P$, for an estimate $\hat{A}=\left\{j: \hat{\beta}_{j} \neq 0 ; j=1, \cdots, p\right\}$ of $A_{0}=\left\{j: \beta_{j}^{0} \neq 0 ; j=1, \cdots, p\right\}$. To derive a lower bound requirement for $C_{\min }\left(\boldsymbol{\beta}^{0}, \boldsymbol{X}\right)$, we construct an approximate least fa-
vorable situation under $P$, over an $L_{0}$-band $B_{0}(u, l)$, as defined in the Introduction, to avoid superefficiency (Ibragimov and Has'minskii, 1981). Then we estimate the smallest possible value of $l>0$ under which selection consistency holds for $\hat{A}$ over $\boldsymbol{\beta}^{0} \in B_{0}(u, l)$, that is

$$
\sup _{\left\{\boldsymbol{\beta}^{0} \in B_{0}(u, l)\right\}} P\left(\hat{A} \neq A_{0}\right) \rightarrow 0, \text { as } n, p \rightarrow 0 .
$$

Let $r\left(p_{0}, \boldsymbol{X}\right)=\frac{\max _{1 \leq j \leq p} n^{-1}\left\|\boldsymbol{x}^{(j)}\right\|^{2}}{\min _{\boldsymbol{\beta}^{0}:\left|\beta_{j}^{0}\right| \geq 1 ; j \in A_{0},\left|A_{0}\right| \leq p_{0}} C_{\text {min }}\left(\boldsymbol{\beta}^{0}, \boldsymbol{X}\right)}$, where $A_{0}=\left\{j: \beta_{j}^{0} \neq 0\right\}$ and $\boldsymbol{x}^{(j)}=$ $\left(x_{1 j}, \cdots, x_{n j}\right)^{T}$. Theorem 1 below gives a good estimate of $l$.

Theorem 1 (Necessity for selection consistency) For any $\hat{A}$ and $(u, l)$ with $u>l>0$, we have

$$
\begin{equation*}
\sup _{\beta^{0} \in B_{0}(u, l)} P\left(\hat{A} \neq A_{0}\right) \rightarrow 0, \quad \text { as } \quad n, p \rightarrow \infty \tag{4}
\end{equation*}
$$

implying that $l>\frac{1}{4 r(u, \boldsymbol{X})} \sigma^{2} \frac{\log p}{n}$. Moreover, if $r(u, \boldsymbol{X}) \leq \frac{1}{4 d_{1}}$, where $d_{1}>0$ is a constant independent of $(n, p)$, then $l>d_{1} \sigma^{2} \frac{\log p}{n}$ with $d_{1} \leq 1 / 4$.

Theorem 1 says that (2) is necessary to achieve selection consistency indeed for any method, as characterized by (4), where the smallest possible $l$ is $\frac{1}{2 r(u, \boldsymbol{X})} \sigma^{2} \frac{\log p}{n}$, depending on a design matrix $\boldsymbol{X}$ through $r(u, \boldsymbol{X})$. Given $\boldsymbol{X}$, an upper bound of $r(u, \boldsymbol{X})$ may be computed. A loose bound, for instance, can be $r(u, \boldsymbol{X}) \leq \frac{\max _{1 \leq j \leq p} n^{-1}\left\|\boldsymbol{x}^{(j)}\right\|^{2}}{\min _{|B| \leq 2 p_{0}, A_{0} \subseteq B} c_{\min }\left(n^{-1} \boldsymbol{X}_{B}^{T} \boldsymbol{X}_{B}\right)}$ by Lemma 1, where $c_{\min }(\cdot)$ denotes the minimum eigenvalue of a matrix. Sufficiently, $r(u, \boldsymbol{X})$ is upper bounded by a constant independent of $(u, n, p)$ when $\boldsymbol{x}^{(j)} ; j=1, \cdots, p$, are standardized, and $\min _{|B| \leq 2 p_{0}, A_{0} \subseteq B} c_{\min }\left(n^{-1} \boldsymbol{X}_{B}^{T} \boldsymbol{X}_{B}\right)$ is bounded away from zero.

Lemma 1 below gives a connection between $C_{\text {min }}$ and the true signal's resolution level $\gamma_{\text {min }}=\gamma_{\text {min }}\left(\boldsymbol{\beta}^{0}\right) \equiv \min \left\{\left|\beta_{k}^{0}\right|: k \in A_{0}\right\}$.

## Lemma 1

$$
\begin{align*}
C_{\min } & =\min _{A_{1} \neq A_{0},\left|A_{1}\right| \leq p_{0}} n^{-1}\left\|\left(I-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}\right\|^{2} \\
& \geq \min _{\left|A_{1}\right| \leq p_{0}} c_{\min }\left(n^{-1} \boldsymbol{X}_{A_{0} \cap A_{1}^{c}}^{T}\left(I-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0} \cap A_{1}^{c}}\right) \gamma_{\min }^{2} \\
& \geq \min _{|B| \leq 2 p_{0}, A_{0} \subseteq B} c_{\min }\left(n^{-1} \boldsymbol{X}_{B}^{T} \boldsymbol{X}_{B}\right) \gamma_{\min }^{2} \geq 0, \tag{5}
\end{align*}
$$

where $\boldsymbol{P}_{A_{1}}$ is the projection matrix for $\boldsymbol{X}_{A_{1}}$ with $A_{1} \subset\left\{1, \cdots, p_{0}\right\}$. In addition,

$$
\begin{equation*}
C_{\min } \leq \max _{j \in A_{0}} n^{-1}\left\|\boldsymbol{x}^{(j)}\right\|^{2} \gamma_{\min }^{2} \leq c_{\max }\left(n^{-1} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right) \gamma_{\min }^{2} \tag{6}
\end{equation*}
$$

where $\boldsymbol{x}^{(j)}=\left(x_{1 j}, \cdots, x_{n j}\right)^{T}$, $c_{\max }(\cdot)$ denotes the maximum eigenvalue of a matrix.

For verification of (2), it can be checked using a stronger but simpler condition according to Lemma 1. That is,

$$
\begin{equation*}
\gamma_{\min }^{2} \min _{|B| \leq 2 p_{0}, A_{0} \subseteq B} c_{\min }\left(n^{-1} \boldsymbol{X}_{B}^{T} \boldsymbol{X}_{B}\right) \geq d_{1} \sigma^{2} \frac{\log p}{n} . \tag{7}
\end{equation*}
$$

One major difference between (7) and (2) is that (7) involves eigenvalues of $\boldsymbol{X}_{B}^{T} \boldsymbol{X}_{B}$ with $|B| \leq$ $2 p_{0}$ instead of those of $\boldsymbol{X}_{B}$ with $|B| \leq p_{0}$ in (2). As a result, (7) may not be tight in that (7) is not satisfied but (2) is. This occurs, for instance, when $\min _{|B| \leq 2 p_{0}, A_{0} \subseteq B} c_{\min }\left(n^{-1} \boldsymbol{X}_{B}^{T} \boldsymbol{X}_{B}\right)=0$ but $C_{\min }>0$. This is so when any $p_{0}$ features are linearly independent but a set of $d$ features are linearly dependent for $d>p_{0}$.

Concerning necessary conditions for selection consistency in the literature, Theorem 1 requires less regularity conditions, which are attainable up to a factor $d_{1}$ as showed in Theorems 2 and 3. To our knowledge, the best available lower bound is roughly $\gamma_{\min }^{2} \geq C_{0} \frac{\log (p-u)}{n}$ in Theorem 3 of Zhang (2010), under the sparse Riesz condition with a dimension restriction $M_{2} u+1 \leq d^{*} \leq p$ for some $M_{2} \geq 16$, and $\gamma_{\text {min }}^{2} \geq C_{0} \frac{\log (p-u)}{n}$. In particular, under the assumptions there, $C_{\min } \geq d_{1}^{*} \sigma^{2} \frac{\log (p-u)}{n}$ by Lemma 1 , for some constant $d_{1}^{*}>0$. Moreover, the assumptions of Theorem 1 may hold even when those of Theorem 3 of Zhang (2010) are not met, which occurs, for instance, in presence of more than $p_{0}$ linearly independent noninformative features.

## 3 Constrained method

This section addresses the issue of attainment under the necessary condition (2). Specifically, we aim at reconstruction of the oracle estimator-the least squares estimate $\hat{\boldsymbol{\beta}}^{o l}=$ $\left(\hat{\boldsymbol{\beta}}_{A_{0}}^{o l}, \mathbf{0}_{A_{0}^{c}}\right)^{T}$ given $A_{0}$ by the constrained method, ultimately leading to reconstruction of $A_{0}$.

### 3.1 Constrained $L_{0}$-method

Consider constrained least squares regression with the $L_{0}$-constraint $\sum_{j=1}^{p} I\left(\beta_{j} \neq 0\right)$. The constrained least squares criterion is

$$
\begin{equation*}
S(\boldsymbol{\beta})=\frac{1}{2} \sum_{i=1}^{n}\left(y_{i}-\boldsymbol{\beta}^{T} \boldsymbol{x}_{i}\right)^{2} \text { subject to } \sum_{j=1}^{p} I\left(\beta_{j} \neq 0\right) \leq K, \tag{8}
\end{equation*}
$$

where $K>0$ is an integer valued tuning parameter. Note that (8) is not equivalent to its unconstrained nonconvex counterpart-the $L_{0}$-regularization:

$$
\begin{equation*}
\frac{1}{2} \sum_{i=1}^{n}\left(y_{i}-\boldsymbol{\beta}^{T} \boldsymbol{x}_{i}\right)^{2}+\lambda \sum_{j=1}^{p} I\left(\left|\beta_{j}\right| \neq 0\right) \tag{9}
\end{equation*}
$$

where $\lambda>0$ is a regularization parameter corresponding to $K$ in (8).
Moreover, tuning involves a discrete parameter $K$ in (8), which is easier than that for (9) with a continuous parameter $\lambda>0$. This phenomenon has been also observed in Gu (1998) for spline estimation.

The next theorem says that a global minimizer of (8) $\hat{\boldsymbol{\beta}}^{L_{0}}=\left(\hat{\boldsymbol{\beta}}_{\hat{A}^{L_{0}}}^{L_{0}}, \mathbf{0}\right)$ consistently reconstructs the oracle estimator at a degree of separation level that is slightly higher than the minimal in (2). Without loss of generality, assume that a global minimizer of (8) exists.

Theorem 2 (Error bound for a global minimizer of (8)) Under (1), when $K=p_{0}$, we have, for any $\left(p_{0}, p, n\right)$

$$
\begin{equation*}
P\left(\hat{\boldsymbol{\beta}}^{L_{0}} \neq \hat{\boldsymbol{\beta}}^{o l}\right) \leq \frac{e+1}{e-1} \exp \left(\frac{n}{18 \sigma^{2}}\left(C_{\min }-36 \frac{\log p}{n} \sigma^{2}\right)\right) . \tag{10}
\end{equation*}
$$

Assume that $u<\min (p, n)$ and constant $d_{1}>36$. Let $l=d_{1} \sigma^{2} \frac{\log p}{n}$. As $n, p \rightarrow \infty$, the following results hold.
(A) Under (2), $\hat{\boldsymbol{\beta}}^{L_{0}}$ consistently reconstructs $\hat{\boldsymbol{\beta}}^{o l}$, implying selection consistency of $\hat{A}^{L_{0}}$ for $A_{0}$. Moreover,

$$
\begin{equation*}
\sup _{\boldsymbol{\beta}^{0} \in B_{0}(u, l)} P\left(\hat{A}^{L_{0}} \neq A_{0}\right) \leq \sup _{\boldsymbol{\beta}^{0} \in B_{0}(u, l)} P\left(\hat{\boldsymbol{\beta}}^{L_{0}} \neq \hat{\boldsymbol{\beta}}^{o l}\right) \rightarrow 0 \tag{11}
\end{equation*}
$$

which agrees with the lower bound (4) in $\left(p_{0}, p, n\right)$ asymptotically, where $B_{0}(u, l)=\left\{\boldsymbol{\beta}: p_{0}=\right.$ $\left.\sum_{j=1}^{p} I\left(\beta_{j} \neq 0\right) \leq u, C_{\min }(\boldsymbol{\beta}, \boldsymbol{X}) \geq l\right\}$.
(B) Under (2), $n^{-1} E\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{L_{0}}-\boldsymbol{\beta}^{0}\right)\right\|^{2}=(1+o(1)) n^{-1} E\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{o l}-\boldsymbol{\beta}^{0}\right)\right\|^{2}=\sigma^{2} \frac{p_{0}}{n}$. In addition, $\hat{\boldsymbol{\beta}}^{L_{0}}$ is risk-minimax in that

$$
\begin{align*}
\sup _{\boldsymbol{\beta}^{0} \in B_{0}(u, l)} n^{-1} E\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{L_{0}}-\boldsymbol{\beta}^{0}\right)\right\|^{2} & =(1+o(1)) n^{-1} E\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{o l}-\boldsymbol{\beta}^{0}\right)\right\|^{2}=\sigma^{2} \frac{u}{n} \\
& =\inf _{T_{n}} \sup _{\boldsymbol{\beta} \in B_{0}(u, l)} n^{-1} E\left\|\boldsymbol{X}\left(T_{n}-\boldsymbol{\beta}^{0}\right)\right\|^{2} . \tag{12}
\end{align*}
$$

Theorem 2 says that $\hat{\boldsymbol{\beta}}^{L_{0}}$ consistently reconstructs the oracle estimator $\hat{\boldsymbol{\beta}}^{o l}$, which suffices to establish the attainment of (2) and its uniform version (4) for selection consistency by $\hat{A}^{L_{0}}$ in $\left(p_{0}, p, n\right)$ except a factor $d_{1}>0$. This permits exponentially many candidate predictors $p \leq p_{0} \exp \left(n \frac{C_{\text {min }}}{d_{1} \sigma^{2}}\right)$ for reconstruction. Moreover, $\hat{\boldsymbol{\beta}}^{L_{0}}$ is risk-minimax optimal for parameter estimation. This is achieved through tuning $K$ over integers ranging from 0 to $\min (n, p)$.

### 3.2 Constrained truncated $L_{1}$-method

We now examine an $L_{0}$ surrogate - the truncated $L_{1}$-constraint, which was suggested for the method of regularization (Shen et al., 2012). Here the surrogate function $J(|z|)$ is $\min ((|z|, \tau)$, approximating the $L_{0}$-function as $\tau \rightarrow 0$. With this surrogate function, the corresponding constrained least squares criterion in (8) becomes:

$$
\begin{equation*}
S(\boldsymbol{\beta})=\frac{1}{2} \sum_{i=1}^{n}\left(y_{i}-\boldsymbol{\beta}^{T} \boldsymbol{x}_{i}\right)^{2} \text { subject to } \frac{1}{\tau} \sum_{j=1}^{p} \min \left(\left|\beta_{j}\right|, \tau\right) \leq K \tag{13}
\end{equation*}
$$

where $K$ and $\tau$ are nonnegative tuning parameters.
The next theorem presents a parallel result for a global minimizer of (13) $\hat{\boldsymbol{\beta}}^{T}=\left(\hat{\boldsymbol{\beta}}_{\hat{\boldsymbol{A}}^{T}}^{T}, \mathbf{0}\right)$ as in Theorem 2.

Theorem 3 (Error bound for a global minimizer of (13)) Under (1), if $K=p_{0}$ and $0<$ $\tau \leq \sigma \sqrt{\frac{6}{(n+2) p c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right)}}$, then

$$
\begin{equation*}
P\left(\hat{\boldsymbol{\beta}}^{T} \neq \hat{\boldsymbol{\beta}}^{o l}\right) \leq \frac{e+1}{e-1} \exp \left(-\frac{n}{20 \sigma^{2}}\left(C_{\min }-40 \sigma^{2} \frac{\log p}{n}\right)\right) . \tag{14}
\end{equation*}
$$

All the results for $\hat{\boldsymbol{\beta}}^{L_{0}}$ in Theorem 2 continue to hold for $\hat{\boldsymbol{\beta}}^{T}$ when $d_{1}>40$.

For parameter estimation in (B), it is known that the minimax rate of convergence in the $L_{2}$-norm is $\sqrt{\frac{u \log (p / u)}{n}}$ over $B_{0}(u, 0)$, c.f. Raskutti et al., (2009). Nevertheless, a sharper rate of $\sqrt{\frac{p_{0}}{n}}$ is achieved by the $L_{0}$-penalty and its computational surrogate under "degree-ofseparation" condition, which can be made uniformly over an $L_{0}$-band $B_{0}(u, l)$ with $l>0$. In other words, these methods are optimal with regard to parameter estimation, because they recover the optimal $L_{2}$-risk of the oracle estimator are asymptotic minimax.

## 4 Regularization-nearly necessary condition

## 4.1 $L_{0}$-regularization

Now consider (9), where we assume, without loss of generality, that a global minimizer exists, because the cost function (9) is bounded by zero almost surely. Denote by $\hat{\boldsymbol{\beta}}^{l_{0}}=\left(\hat{\boldsymbol{\beta}}_{\hat{A}^{l_{0}}}^{l_{0}}, \mathbf{0}\right)$ a global minimizer of (9).

Theorem 4 (Error bound for a global minimizer of (9)) Under (1) and $\alpha>1$,

$$
\begin{align*}
P\left(\hat{\boldsymbol{\beta}}^{l_{0}} \neq \hat{\boldsymbol{\beta}}^{o l}\right) \leq & 4 \exp \left(-\left(\frac{n C_{\min }^{*}}{18 \sigma^{2}}-(\alpha+1) \log (p+1)-\frac{\lambda}{2 \sigma^{2}}\right)\right) \\
& +4 \exp \left(-\left(\frac{(\alpha-1) \lambda}{3 \alpha \sigma^{2}}-\left(1+\frac{1}{\alpha}\right)\left(\log (p+1)-\frac{2}{3}\right)\right) .\right. \tag{15}
\end{align*}
$$

Moreover, if $\sup _{\boldsymbol{\beta}^{0} \in B_{0}(u, l)} \frac{1}{n}\left\|\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2} \leq c_{1} \exp \left(c_{2} p_{0}\right)$ for some constant $c_{j} ; j=1,2$, then all the results in Theorems 2 continue to hold under (3) with $C_{\min }$ replaced by $C_{\min }^{*}$, when $d_{1}>$ $\frac{9\left(\alpha^{2}+3 \alpha+2\right)}{\alpha-1}$, and $\frac{\lambda}{n} \in\left(\frac{3(\alpha+1) \log (p+1) \sigma^{2}}{2(\alpha-1) n}, \frac{1}{9} C_{\min }^{*}\right)$. Similarly, for $\alpha=1$, all the above results hold under (3) with $C_{\min }^{*}$ replaced by $C_{\min }$, when $d_{1}>225$, and $\frac{\lambda}{n} \in\left(18 \sigma^{2} \frac{p_{0} \max \left(\log \frac{p}{p_{0}}, 1\right)}{n}, \frac{1}{9} C_{\min }\right)$.

Theorem 4 derives parallel results of the constrained method under a condition that is slightly stronger. This may be attributed to non-equivalence between these two methods in tuning. Note that the case of $\alpha=1$ is suboptimal as compared to that of $\alpha>1$. This is in contrast of the results in Theorems 2 and 3.

### 4.2 Truncated $L_{1}$-regularization

Next consider a global minimizer $\hat{\boldsymbol{\beta}}^{t l}=\left(\hat{\boldsymbol{\beta}}_{\hat{A}^{t l}}^{t l}, \mathbf{0}\right)$ of the computational surrogate of the $L_{0^{-}}$ regularization:

$$
\begin{equation*}
\frac{1}{2} \sum_{i=1}^{n}\left(y_{i}-\boldsymbol{\beta}^{T} \boldsymbol{x}_{i}\right)^{2}+\frac{\lambda}{\tau} \sum_{j=1}^{p} \min \left(\left|\beta_{j}\right|, \tau\right) . \tag{16}
\end{equation*}
$$

For (16), we describe its global minimizer in a simple case to provide an insight into the truncated $L_{1}$ function as a computational surrogate of the $L_{0}$-function.

Proposition 1 In the orthogonal design case, the truncated $L_{1}$ penalty (TLP) estimate defined by (16) becomes $\hat{\beta}_{j}^{o l} I\left(\left|\hat{\beta}_{j}^{o l}\right| \geq \sqrt{2 \lambda}\right)$ when $\tau \leq \sqrt{\lambda / 2}$, which reduces to the thresholding rule defined by a global minimizer of the cost function of $L_{0}$-regularization (9), and is

$$
\begin{cases}\hat{\beta}_{j}^{o l} & \text { if }\left|\hat{\beta}_{j}^{o l}\right| \geq \frac{\lambda}{2 \tau}+\tau ; \\ \left(\left|\hat{\beta}_{j}^{o l}\right|-\frac{\lambda}{\tau}\right)_{+} \operatorname{sign}\left(\hat{\beta}_{j}^{o l}\right) & \text { if }\left|\hat{\beta}_{j}^{o l}\right| \leq \frac{\lambda}{2 \tau}+\tau\end{cases}
$$

when $\tau>\sqrt{\lambda / 2} ; j=1, \cdots, p$. Here $\hat{\beta}_{j}^{o l}$ is the ordinary least squares estimate for $\beta_{j}$. Note that there are two distinct global minimizers if $\left|\hat{\beta}_{j}^{o l}\right|=\frac{\lambda}{2 \tau}+\tau$.

Proposition 1 suggests that the TLP function yields the thresholding rule of the $L_{0^{-}}$ regularization when the value of $\tau$ is small enough in that $\tau \leq \sqrt{\lambda / 2}$.

Theorem 5 (Error bound for a global minimizer of (16)) Under (1), if $0<\tau \leq \sqrt{\frac{2 \lambda}{(n+1) c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right)}}$ and $\alpha>1$, then $P\left(\hat{\boldsymbol{\beta}}^{t l} \neq \hat{\boldsymbol{\beta}}^{\text {ol }}\right)$ is upper bounded by

$$
\begin{gather*}
\min \left(\frac{\sqrt{2}\left|A_{0}\right| n^{1 / 2} \tau}{\sigma \sqrt{\pi} c_{\min }^{-1 / 2}\left(\frac{1}{n} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right)} \exp \left(-\frac{n\left(\gamma_{\min }-\tau\right)^{2}}{2 \sigma^{2} c_{\min }^{-1}\left(\frac{1}{n} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right)}\right),\left|A_{0}\right| \Phi\left(-\frac{n^{1 / 2}\left(\gamma_{\min }-\tau\right)}{\sigma c_{\min }^{-1 / 2}\left(\frac{1}{n} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right)}\right)\right) \\
+4 \exp \left(-\left(\frac{n C_{\min }^{*}}{20 \sigma^{2}}-(\alpha+1) \log (p+1)-\frac{\lambda}{2 \sigma^{2}}\right)\right) \\
+4 \exp \left(-\left(\frac{(\alpha-1) \lambda}{3 \alpha \sigma^{2}}-\left(1+\frac{1}{\alpha}\right)\left(\log (p+1)-\frac{5}{3}\right)\right) .\right. \tag{17}
\end{gather*}
$$

where $\Phi(\cdot)$ is the cumulative distribution function of $N(0,1)$. If $\sup _{\boldsymbol{\beta}^{0} \in B_{0}(u, l)} \frac{1}{n}\left\|\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}$ $\leq c_{1} \exp \left(c_{2} p_{0}\right)$ for some constant $c_{j} ; j=1,2$, then all the results in Theorem 2 continue to hold under (3) with $C_{\min }^{*}$ replaced by $C_{\min }$, when $d_{1}>\frac{10\left(\alpha^{2}+3 \alpha+2\right)}{\alpha-1}$, and $\frac{\lambda}{n} \in$
$\left(\frac{3(\alpha+1) \log (p+1) \sigma^{2}}{2(\alpha-1) n}, \frac{1}{10} C_{\min }^{*}\right)$ and $\tau \leq \sqrt{\frac{2 \lambda}{(n+1) c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right)}}$. Similarly, if $\alpha=1$, Then all the results continue to hold under (3) with $C_{\min }$ replaced by $C_{\min }^{*}$, when $d_{1}>225$, and $\frac{\lambda}{n} \in$ $\left(18 \sigma^{2} \frac{p_{0} \max \left(\log \frac{p}{p_{0}}, 1\right)}{n}, \frac{1}{10} C_{\text {min }}\right)$.

Theorem 5 says that the computational surrogate shares the desired statistical properties of the $L_{0}$-regularization. This occurs when $\tau$ is chosen to be sufficiently small, or $\tau \leq$ $\sqrt{\frac{2 \lambda}{(n+1) c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right)}}$. This result suggests that tuning should be concentrated more on $\lambda$ whereas $\tau$ does not need a refined search. In practice, $\tau$ should not be too small.

## 5 Nonconvex minimization

To solve (16), we derive a constrained DC method by approximating the constraint function in (16) by a sequence of nonincreasing approximating functions through DC programming. This is a so-called prime approach for unconstrained regularization that is a dual problem of (16), namely,

$$
\begin{equation*}
\frac{1}{2} \sum_{i=1}^{n}\left(y_{i}-\boldsymbol{\beta}^{T} \boldsymbol{x}_{i}\right)^{2}+\frac{\lambda}{\tau} \sum_{j=1}^{p} \min \left(\left(\left|\beta_{j}\right|, \tau\right)\right. \tag{18}
\end{equation*}
$$

where $\lambda \geq 0$ is a regularizer or Lagrange multiplier for (16).
To proceed, we first decompose the nonconvex constraint in (16) into a difference to two convex functions:

$$
\begin{equation*}
\frac{1}{\tau} \sum_{j=1}^{p} \min \left(\left(\left|\beta_{j}\right|, \tau\right)=S_{1}(\boldsymbol{\beta})-S_{2}(\boldsymbol{\beta})\right. \tag{19}
\end{equation*}
$$

where $S_{1}(\boldsymbol{\beta})=\frac{1}{\tau} \sum_{j=1}^{p}\left|\beta_{j}\right|$ and $S_{2}(\boldsymbol{\beta})=\frac{1}{\tau} \sum_{j=1}^{p} \max \left(\left|\beta_{j}\right|-\tau, 0\right)$. Given (19), a sequence of upper approximations of the constraint function is constructed by successively replacing $S_{2}(\boldsymbol{\beta})$ by its minorization at iteration $m$ :

$$
\begin{equation*}
S_{1}(\boldsymbol{\beta})-\left(S_{2}\left(\hat{\boldsymbol{\beta}}^{(m-1)}\right)+\left(|\boldsymbol{\beta}|-\left|\hat{\boldsymbol{\beta}}^{(m-1)}\right|\right)^{T} \nabla S_{2}\left(\left|\hat{\boldsymbol{\beta}}^{(m-1)}\right|\right)\right), \tag{20}
\end{equation*}
$$

where $\nabla S_{2}=\frac{1}{\tau} I\left(\left|\hat{\boldsymbol{\beta}}^{(m-1)}\right|>\tau\right)$ is a subgradient of $S_{2}$ in $|\boldsymbol{\beta}|$, and $|\cdot|$ is used for vectors,
taking the absolute value in each component. At iteration $m$, the $m$ th subproblem becomes

$$
\begin{equation*}
\min _{\boldsymbol{\beta}} S(\boldsymbol{\beta}), \quad \text { subject to } \frac{1}{\tau} \sum_{j=1}^{p}\left|\beta_{j}\right| I\left(\left|\hat{\beta}_{j}^{(m-1)}\right| \leq \tau\right) \leq K-\sum_{j=1}^{p} I\left(\left|\hat{\beta}_{j}^{(m-1)}\right|>\tau\right) \tag{21}
\end{equation*}
$$

Minimizing (21) in $\boldsymbol{\beta}$ yields its minimizer $\hat{\boldsymbol{\beta}}^{(m)}$. The process continues until termination.
A constrained DC algorithm is summarized as follows.

## Algorithm 1:

Step 1. (Initialization) Supply a good initial estimate $\hat{\boldsymbol{\beta}}^{(0)}$, say the Lasso estimate.
Step 2. (Iteration) At iteration $m$, compute $\hat{\boldsymbol{\beta}}^{(m)}$ by solving (21). This can be done through the constrained Lasso algorithm of Osborne et al. (2000), which is implemented in Lasso2 in the R-package.
Step 3. (Stopping rule) Terminate when $S\left(\hat{\boldsymbol{\beta}}^{(m-1)}\right)-S\left(\hat{\boldsymbol{\beta}}^{(m)}\right) \leq 0$. Then the estimate $\hat{\boldsymbol{\beta}}_{T}=\hat{\boldsymbol{\beta}}^{\left(m^{*}-1\right)}$, where $m^{*}$ is the smallest index satisfying the termination criterion.

There is a connection between the prime approach and its dual approach in Shen et al. (2012), although nonconvex problems (16) and (18) are not equivalent, where (18) is solved through DC programming by approximating the cost function in (18) to minimize

$$
\begin{equation*}
S(\boldsymbol{\beta})+\frac{\lambda}{\tau} \sum_{j=1}^{p}\left|\beta_{j}\right| I\left(\left|\hat{\beta}_{j}^{(m-1)}\right| \leq \tau\right) \tag{22}
\end{equation*}
$$

iteratively with respect to $m$. As to be shown in Lemma 2, the prime DC approach as implemented by Algorithm 1 is equivalent to the dual DC approach implemented through Algorithm 1 of Shen et al. (2012). The equivalence is established for their solutions, regardless of the modes of implementation, because a coordinate decent method breaks down for (16) but works for (18). Given the equivalence, no improvement of Algorithm 1 is expected over Algorithm 1 of Shen et al. (2012). We refer to Shen et al. (2012) for simulation comparisons of various methods with regard to accuracy of selection and predictive accuracy.

Lemma 2 (Equivalence) The DC solution for (16), computed through (21) in Algorithm 1 is equivalent to that for (18)x), computed using Algorithm 1 of Shen et al. (2012). Specifically, given any $\lambda, 0 \leq \lambda<\infty$, and initial value of Algorithm 1 for (18), there exist a $K$ and
an initial value of Algorithm 1 of Shen et al. (2012) for (21) such that the DC solution of (22) is also a DC solution of (21), and vice versa. Moreover, Algorithm 1 has the finite termination property and $S\left(\hat{\boldsymbol{\beta}}^{(m)}\right)$ nonincreases in $m$, as its unconstrained counterpart.

Now consider a local minimizer of (16) $\hat{\boldsymbol{\beta}}^{l o}=\left(\hat{\boldsymbol{\beta}}_{\hat{A}^{l o}}^{l o}, \mathbf{0}\right)$ satisfying a local optimality condition of (16):

$$
\begin{equation*}
-\left(\boldsymbol{x}^{(j)}\right)^{T}(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{\beta})+\frac{\lambda}{\tau} b_{j}=0, \quad j=1, \cdots, p \tag{23}
\end{equation*}
$$

where $b_{j}=\operatorname{sign}\left(\beta_{j}\right)$ if $0<\left|\beta_{j}\right|<\tau ; b_{j} \in[-1,1]$ if $\beta_{j}=0 ; b_{j}=0$ if $\left|\beta_{j}\right|>\tau ; b_{j}=\emptyset$ if $\left|\beta_{j}\right|=\tau$, is the regular subdifferential of $J_{T, \tau}\left(\left|\beta_{j}\right|\right)$ at $\beta_{j}$, and $\emptyset$ is the empty set. The reader may consult Rockafellar (2003) for optimal conditions of continuous but nondifferentiable functions.

Theorem 6 (Error bound for a local minimizer of (16)). Under (1), for $\hat{\boldsymbol{\beta}}^{l o}$ satisfying (23), including the solution from Algorithm 1 of Shen et al. (2012), if $\tau^{2} \geq \frac{4 \sqrt{2 K^{*}} \lambda}{n \min _{|B| \leq 2 K^{*}, A_{0} \subseteq B} c_{\min }\left(n^{-1} \boldsymbol{X}_{B}^{T} \boldsymbol{X}_{B}\right)}$ then,

$$
\begin{gather*}
P\left(\hat{\boldsymbol{\beta}}^{l o} \neq \hat{\boldsymbol{\beta}}^{o l}\right) \leq \min \left(\frac{\sqrt{2}\left|A_{0}\right| n^{1 / 2}(3 \tau / 2)}{\sqrt{\pi} \sigma c_{\min }^{-1 / 2}\left(\frac{1}{n} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right)} \exp \left(-\frac{n\left(\gamma_{\min }-3 \tau / 2\right)^{2}}{2 \sigma^{2} c_{\min }^{-1}\left(\frac{1}{n} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right)}\right),\right. \\
\left.\left|A_{0}\right| \Phi\left(-\frac{n^{1 / 2}\left(\gamma_{\min }-3 \tau / 2\right)}{\sigma c_{\min }^{-1 / 2}\left(\frac{1}{n} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right)}\right)\right)+\left(p-\left|A_{0}\right|\right) \Phi\left(-\frac{\lambda / \tau}{\sigma \max _{1 \leq j \leq p}\left\|\boldsymbol{x}^{(j)}\right\|}\right), \tag{24}
\end{gather*}
$$

where $K^{\star}$ is the upper bound of the maximum number of non-zero predictors, with $p_{0} \leq$ $K^{\star} \leq \min \{n / 2, p\}$. If $c_{\max }\left(\frac{\boldsymbol{X}^{T} \boldsymbol{X}}{n}\right) p^{2} \tau^{2} \leq c_{1} \exp \left(c_{2} p_{0}\right)$ for some constant $c_{1}>0$, then all the results in Theorem 4,5 continue to hold if $\tau \leq \frac{\gamma_{\min }}{2}, \frac{\log p_{0}}{n} \leq \frac{c_{\text {min }}\left(n^{-1} \boldsymbol{X}_{A_{0}} \boldsymbol{X}_{A_{0}}\right) \gamma_{\text {min }}^{2}}{5 \sigma^{2}}, \frac{\log p}{n} \leq$ $\frac{\lambda^{2}}{2 \tau^{2} \sigma^{2} n \max _{1 \leq j \leq p}\left\|\boldsymbol{x}^{(j)}\right\|^{2}}$, sufficiently,

$$
\frac{\log p}{n}<\frac{\left(\min _{|B| \leq 2 K^{\star}, A_{0} \subseteq B} c_{\min }\left(n^{-1} \boldsymbol{X}_{B} \boldsymbol{X}_{B}\right)\right)^{2} \gamma_{\min }^{2}}{256 K^{\star} \sigma^{2}} \frac{n}{\max _{j \in A_{0}}\left\|x^{(j)}\right\|^{2}},
$$

where $B_{0}(u, l)$ is replaced by

$$
\left\{\boldsymbol{\beta} \in \mathcal{R}^{p}: \sum_{j=1}^{p} I\left(\beta_{j} \neq 0\right) \leq u, \gamma_{\min }^{2}(\boldsymbol{\beta}) \min _{|B| \leq 2 K^{*}, A_{0} \subseteq B} c_{\min }\left(n^{-1} \boldsymbol{X}_{B} \boldsymbol{X}_{B}\right) \geq l\right\}
$$

with $l=256 \sigma^{2} K^{*} \frac{\log p}{n} \frac{\max _{j \in A_{0}}\left\|\boldsymbol{x}^{(j)}\right\|^{2}}{n}$.

Theorem 6 says that a local minimizer of (16) achieves the objectives of a global minimizer of (16) under stronger assumptions.

Lemma 3 Results in Theorems 1-6 continue to hold for fixed $p$ with $n \rightarrow \infty$ with (2) replaced by $\lim _{n \rightarrow \infty} n C_{\text {min }}=\infty$.

## 6 Appendix

Proof of Theorem 1: Our proof constructs an approximated least favorable situation for feature selection and uses Fano's Lemma. According to Fano's Lemma (Ibragimov and Has'minskii, 1981), for any mapping $T=T\left(Y_{1}, \cdots, Y_{n}\right)$ taking values in $\{1, \cdots, s\}$, $s^{-1} \sum_{j=1}^{s} P_{j}\left(T\left(Y_{1}, \cdots, Y_{n}\right)=j\right) \leq \sum_{1 \leq j, k \leq s} n \frac{K\left(q_{j}, q_{k}\right)+\log 2}{s^{2} \log (s-1)}$, where $K\left(q_{j}, q_{k}\right)=\int q_{j} \log \left(q_{j} / q_{k}\right)$ is the Kullback-Leibler information for densities $q_{j}$ versus $q_{k}$ corresponding $P_{j}$ and $P_{k}$.

Let $S=\left\{\boldsymbol{\beta}_{j}\right\}_{j=0}^{p}$ be a collection of parameters with components equal to $\gamma_{\text {min }}$ or 0 satisfying that for any $1 \leq j, j^{\prime} \leq p+1,\left\|\boldsymbol{\beta}_{j^{\prime}}-\boldsymbol{\beta}_{j}\right\|^{2} \leq 4 \gamma_{\text {min }}^{2}$. For example, we may choose $\boldsymbol{\beta}_{0}=\sum_{k=1}^{p_{0}-1} \gamma_{\min } \boldsymbol{\delta}_{k}, \boldsymbol{\beta}_{j}=\boldsymbol{\beta}_{0}-\gamma_{\min } \boldsymbol{\delta}_{j} ; j=1, \cdots, p_{0}-1$ and $\boldsymbol{\beta}_{j}=\boldsymbol{\beta}_{0}+\gamma_{\min } e_{j} ; j=p_{0}, \cdots, p$, where $\boldsymbol{\delta}_{k}$ is a vector of length $p$ with its kth element being 1 and 0 otherwise. Let $q_{j}$ is the corresponding probability density defined by $\boldsymbol{\beta}_{j}, j=0, \cdots, p$. Then we have, for any $\boldsymbol{\beta}_{j}, \boldsymbol{\beta}_{j^{\prime}} \in S, K\left(q_{j}, q_{j^{\prime}}\right)=\frac{1}{2 \sigma^{2} n}\left\|\boldsymbol{X}\left(\boldsymbol{\beta}_{j}-\boldsymbol{\beta}_{j^{\prime}}\right)\right\|^{2} \leq \frac{2 \max _{1 \leq j \leq p}\left\|\boldsymbol{x}^{(j)}\right\|^{2} \gamma_{\text {min }}^{2}}{n \sigma^{2}} \leq \frac{2 r\left(p_{0}, \boldsymbol{X}\right) C_{\min }\left(\boldsymbol{\beta}^{0}, \boldsymbol{X}\right)}{\sigma^{2}}$ by Lemma 1. It follows from Fano's lemma with $S$ and $s=p+1$ that $s^{-1} \sum_{j \in S} P_{j}(T=j) \leq$ $\frac{2 n r\left(p_{0}, \boldsymbol{X}\right) C_{\min }\left(\boldsymbol{\beta}^{0}, \boldsymbol{X}\right)+\sigma^{2} \log 2}{\sigma^{2} \log p}$, implying that

$$
\begin{equation*}
\sup _{\left\{(\boldsymbol{\beta}, \boldsymbol{X}): C_{\min }\left(\boldsymbol{\beta}^{0}, \boldsymbol{X}\right) \leq R^{*}\left(p_{0}, \boldsymbol{X}\right)\right\}} P\left(\hat{A} \neq A_{0}\right) \geq 1-\frac{2 n r\left(p_{0}, \boldsymbol{X}\right) C_{\min }\left(\boldsymbol{\beta}^{0}, \boldsymbol{X}\right)+\sigma^{2} \log 2}{\sigma^{2} \log p}, \tag{25}
\end{equation*}
$$

which is bounded below by a constant $c_{*}>0$ with $R^{*}\left(p_{0}, \boldsymbol{X}\right)=\frac{\sigma^{2}\left(1-c_{*}\right) \log p}{2 n r\left(p_{0}, \boldsymbol{X}\right)}$. For (4), if $\sup _{\boldsymbol{\beta}^{0} \in B_{0}(u, l)} P\left(\hat{A} \neq A_{0}\right) \rightarrow 0$, then it follows from (25) that $B_{0}(u, l)$ can not interact with a $L_{0}$-ball $B_{0}\left(R^{*}(u, \boldsymbol{X}), 0\right)$, thus $l \geq R^{*}(u, \boldsymbol{X})$ with $l=\frac{1}{4 r(u, \boldsymbol{X})} \sigma^{2} \frac{\log p}{n}$, and $d_{0}=\frac{1}{4 r(u, \boldsymbol{X})}$, for any $\boldsymbol{\beta}^{0} \in B_{0}(u, l)$. By (6), $r(u, \boldsymbol{X}) \geq 1$. Hence $d_{1} \leq 1 / 4$. This completes the proof.
Proof of Lemma 1: The first inequality follows from Lemma 3 of Shen et al. (2012). For
the second, note that

$$
\begin{aligned}
C_{\min } & =n^{-1} \min _{A \neq A_{0},|A| \leq p_{0}} \frac{1}{\max \left(\left|A_{0} \backslash A\right|, 1\right)}\left\|\left(I-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}\right\|^{2} \\
& \leq \min _{j \in A_{0}} n^{-1}\left\|\left(I-\boldsymbol{P}_{A_{0} \backslash\{j\}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}\right\|^{2} \leq \min _{j \in A_{0}}\left(n^{-1}\left\|\boldsymbol{x}^{(j)}\right\|^{2} \beta_{j}^{2}\right) \\
& \leq \gamma_{\min }^{2} \max _{j \in A_{0}} n^{-1}\left\|\boldsymbol{x}^{(j)}\right\|^{2} .
\end{aligned}
$$

This together with $\max _{j \in A_{0}} n^{-1}\left\|\boldsymbol{x}^{(j)}\right\|^{2} \leq c_{\max }\left(n^{-1} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right)$ implies that the desired result. This completes the proof.

Next we present a technical lemma to be used below.

Lemma 4 Let $\boldsymbol{P}_{A}$ and $\boldsymbol{P}_{B}$ be two projection matrices onto the column space of $\boldsymbol{X}_{A}$ and $\boldsymbol{X}_{B}$, respectively. For any integer $r \geq 2$,

$$
\begin{equation*}
\operatorname{Tr}\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{r}\right) \leq \operatorname{Tr}\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2}\right) \leq|A|+|B|-2|A \cap B| \tag{26}
\end{equation*}
$$

where $\operatorname{Tr}$ denotes the trace of a matrix.

Proof: Before proceeding, we prove that $0 \leq \lambda_{\max }\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2}\right) \leq 1$. Note that $\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2}$ is non-negative definite. Then, for any $\boldsymbol{x}, 0 \leq\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right) \boldsymbol{x}\right)^{T}\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right) \boldsymbol{x}\right)=\boldsymbol{x}^{T}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2} \boldsymbol{x}$, implying that $\lambda_{\max }\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2}\right)=\sup _{\boldsymbol{x} \neq 0} \frac{\boldsymbol{x}^{T}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2} \boldsymbol{x}}{\|\boldsymbol{x}\|^{2}} \geq 0$, where $|A|$ denotes size of set $A$, and $\|\cdot\|$ is the usual $L_{2}$-norm. Moreover, $\boldsymbol{x}^{T}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2} \boldsymbol{x}=\left(\left(I-\boldsymbol{P}_{A}\right) \boldsymbol{x}\right)^{T}\left(\boldsymbol{P}_{B} \boldsymbol{x}\right)+((I-$ $\left.\left.\boldsymbol{P}_{B}\right) \boldsymbol{x}\right)^{T}\left(\boldsymbol{P}_{A} \boldsymbol{x}\right)$. By inequality that $2 a b \leq a^{2}+b^{2}$ for any real numbers $a, b$, and the fact that $\left(I-\boldsymbol{P}_{A}\right)^{2}=\left(I-\boldsymbol{P}_{A}\right)$ and $\boldsymbol{P}_{B}^{2}=\boldsymbol{P}_{B},\left(\left(I-\boldsymbol{P}_{A}\right) \boldsymbol{x}\right)^{T}\left(\boldsymbol{P}_{B} \boldsymbol{x}\right) \leq \frac{1}{2}\left(\boldsymbol{x}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right)^{2} \boldsymbol{x}+\boldsymbol{x}^{T} \boldsymbol{P}_{B}^{2} \boldsymbol{x}\right)=$ $\frac{1}{2}\left(\boldsymbol{x}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{x}+\boldsymbol{x}^{T} \boldsymbol{P}_{B} \boldsymbol{x}\right)$. Thus $\boldsymbol{x}^{T}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2} \boldsymbol{x} \leq \frac{1}{2}\left(\boldsymbol{x}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{x}+\boldsymbol{x}^{T} \boldsymbol{P}_{B} \boldsymbol{x}+\boldsymbol{x}^{T}(\boldsymbol{I}-\right.$ $\left.\left.\boldsymbol{P}_{B}\right) \boldsymbol{x}+\boldsymbol{x}^{T} \boldsymbol{P}_{A} \boldsymbol{x}\right)=\|\boldsymbol{x}\|^{2}$. Hence $\lambda_{\max }\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2}\right) \leq 1$.

For the first inequality in (26), first consider the case of even $r$. In this case, $\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{r}$ is non-negative definite. By Lemma 6.5 of Zhou et al. (1998), $\operatorname{Tr}\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{r}\right) \leq \operatorname{Tr}\left(\left(\boldsymbol{P}_{A}-\right.\right.$ $\left.\left.\boldsymbol{P}_{B}\right)^{2}\right)\left(\lambda_{\max }\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2}\right)^{r / 2-1} \leq \operatorname{Tr}\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2}\right)$, for any integer $r \geq 3$. Next consider the case of odd valued $r$. Now $\operatorname{Tr}\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{r}\right) \leq \operatorname{Tr}\left(P_{A}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{r-1}\right) \leq \operatorname{Tr}\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{r-1}\right)$, which reduces to the case of even valued $r$.

To prove the second inequality in (26), note that $\operatorname{Tr}\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{B}\right)^{2}\right)=|A|+|B|-$ $2 \operatorname{Tr}\left(\boldsymbol{P}_{A} \boldsymbol{P}_{B}\right)$. If $A \cap B=\emptyset, \operatorname{Tr}\left(\boldsymbol{P}_{A} \boldsymbol{P}_{B}\right) \geq \operatorname{Tr}\left(\boldsymbol{P}_{A}\right) \lambda_{\min }\left(\boldsymbol{P}_{B}\right)=0$ by Lemma 6.5 of Zhou et al. (1998), implying the second inequality in (26). If $A \cap B \neq \emptyset$, we write, without loss of generality, $\boldsymbol{X}_{A}=\left(\boldsymbol{x}_{1}, \cdots, \boldsymbol{x}_{|A|-s}, \cdots, \boldsymbol{x}_{|A|}\right)$ and $\boldsymbol{X}_{B}=\left(\boldsymbol{x}_{|A|-s+1}, \cdots, \boldsymbol{x}_{|A|}, \cdots, \boldsymbol{x}_{|A|+|B|-s}\right)$ with $s \leq|A| \leq|B|$ and $s=|A \cap B|$. Now we construct an orthonormal basis for the column space of $\boldsymbol{X}_{A \cap B}: \boldsymbol{e}_{|A|-s+1}, \cdots, \boldsymbol{e}_{|A|}$, followed by two orthonormal bases that are orthogonal to it through the Gram-Schmidt orthogonalization. These are $\boldsymbol{e}_{1}, \cdots, \boldsymbol{e}_{|A|-s}$ and $\boldsymbol{e}_{|A|+1}, \cdots, \boldsymbol{e}_{|A|+|B|-s}$, in the column spaces of $\boldsymbol{X}_{A}$ and $\boldsymbol{X}_{B}$, respectively. As a result of the construction, $\boldsymbol{P}_{A}=\sum_{i=1}^{|A|} \boldsymbol{e}_{i} \boldsymbol{e}_{i}^{T}$ and $\boldsymbol{P}_{B}=\sum_{j=|A|-s+1}^{|A|+|B|-s} \boldsymbol{e}_{j} \boldsymbol{e}_{j}^{T}$. Consequently,

$$
\begin{aligned}
\operatorname{Tr}\left(\boldsymbol{P}_{A} \boldsymbol{P}_{B}\right) & =\sum_{i=1}^{|A|} \sum_{j=|A|-s+1}^{|A|+|B|-s} \operatorname{Tr}\left(\boldsymbol{e}_{i} \boldsymbol{e}_{i}^{T} \boldsymbol{e}_{j} \boldsymbol{e}_{j}^{T}\right)=\sum_{i=1}^{|A|} \sum_{j=|A|-s+1}^{|A|+|B|-s}\left(\boldsymbol{e}_{i}^{T} \boldsymbol{e}_{j}\right)^{2} \\
& =\sum_{j=|A|-s+1}^{|A|}\left(\boldsymbol{e}_{j}^{T} \boldsymbol{e}_{j}\right)^{2}+\sum_{i=1}^{|A|-s} \sum_{j=|A|+1}^{|A|+|B|-s}\left(\boldsymbol{e}_{i}^{T} \boldsymbol{e}_{j}\right)^{2} \geq \sum_{j=|A|-s+1}^{|A|} 1=s,
\end{aligned}
$$

yielding the second inequality in (26). This completes the proof.
Proof of Theorem 2: We bound the reconstruction error directly. Note that $\left|\hat{A}^{L_{0}}\right| \leq p_{0}$ when $K=p_{0}$. If $\hat{A}^{L_{0}}=A_{0}$ then $\hat{\boldsymbol{\beta}}^{L_{0}}=\hat{\boldsymbol{\beta}}^{o l}$. Let $S(\boldsymbol{\beta}) \equiv \frac{1}{2}\left\|\boldsymbol{Y}-\boldsymbol{X}_{A} \boldsymbol{\beta}_{A}\right\|^{2}$. Note that $A \subset\{1, \cdots, p\}$ can be partitioned into $\left(A \backslash A_{0}\right) \cup\left(A_{0} \cap A\right)$. Then

$$
\begin{align*}
I & \equiv P\left(\hat{\boldsymbol{\beta}}^{L_{0}} \neq \hat{\boldsymbol{\beta}}^{o l}\right) \leq \sum_{A \subset\{1, \cdots, p\}, A \neq A_{0},|A| \leq p_{0}} P\left(S\left(\hat{\boldsymbol{\beta}}_{\hat{A}^{L_{0}}}^{L_{0}}\right)-S\left(\hat{\boldsymbol{\beta}}_{A_{0}}^{o l}\right) \leq 0, \hat{A}^{L_{0}}=A\right) \\
& \leq \sum_{k=0}^{p_{0}-1} \sum_{j=0}^{p_{0}-k}\binom{p-p_{0}}{j}\binom{p_{0}}{k} P\left(S\left(\hat{\boldsymbol{\beta}}^{L_{0}}\right)-S\left(\hat{\boldsymbol{\beta}}^{o l}\right) \leq 0, B_{k j}\right), \tag{27}
\end{align*}
$$

where $B_{k j}=\left\{\hat{A}^{L_{0}}=A,\left|A_{0} \cap A\right|=k,\left|A \backslash A_{0}\right|=j\right\}$, and $\binom{n}{k}$ is the binomial coefficient indexed by $n$ and $k$. On event $B_{k j},\left\|\boldsymbol{Y}-\boldsymbol{X}_{A} \hat{\boldsymbol{\beta}}^{L_{0}}\right\|^{2} \geq\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{Y}\right\|^{2}$. Hence

$$
\begin{aligned}
& 2\left(S\left(\hat{\boldsymbol{\beta}}^{L_{0}}\right)-S\left(\hat{\boldsymbol{\beta}}^{o l}\right)\right) \geq\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right)\left(\boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}+\boldsymbol{\epsilon}\right)\right\|^{2}-\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon}\right\|^{2} \\
& =2 \boldsymbol{\epsilon}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}+\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}-\boldsymbol{\epsilon}^{T}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon} .
\end{aligned}
$$

For any $\delta$ with $0<\delta<1$, and any $A$ with $\left|A_{0} \cap A\right|=k$ and $\left|A \backslash A_{0}\right|=j ; k=0, \cdots, p_{0}-1$,
$j=1, \cdots, p_{0}-k, P\left(S\left(\hat{\boldsymbol{\beta}}_{A}^{L_{0}}\right)-S\left(\hat{\boldsymbol{\beta}}_{A_{0}}^{\text {ol }}\right) \leq 0, B_{k j}\right)$ is upper bounded by

$$
\begin{aligned}
& P\left(\delta\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}+2 \boldsymbol{\epsilon}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}} \leq 0\right) \\
& +P\left((1-\delta)\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}-\boldsymbol{\epsilon}^{T}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon} \leq 0\right) \equiv I_{1}\left(B_{k j}\right)+I_{2}\left(B_{k j}\right) .
\end{aligned}
$$

Let $L_{1}(A) \equiv-2 \boldsymbol{\epsilon}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}$ and $L_{2}(A) \equiv \boldsymbol{\epsilon}^{T}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon}$, which follow $N\left(0,4 \sigma^{2} \|(\boldsymbol{I}-\right.$ $\left.\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}} \|^{2}$ ) and a weighted $\chi^{2}$-distribution, respectively. Let $b(A)=\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}$. An application of Markov's inequality with the normal moment generating function yields that

$$
I_{1}\left(B_{k j}\right) \leq E \exp \left(\frac{t_{1} L_{1}(A)}{\sigma^{2}}\right) \exp \left(-\frac{\delta t_{1} b(A)}{\sigma^{2}}\right) \leq \exp \left(\frac{2 t_{1}^{2}-\delta t_{1}}{\sigma^{2}} n i C_{\min }\right)
$$

for any $0<t_{1}<1 / 2$, where $i \equiv p_{0}-k$, and $n C_{\min } \leq \frac{b(A)}{\max \left(\left|A_{0} \backslash A\right|, 1\right)}=\frac{b(A)}{i}$ has been used in the last inequality with $\left|A_{0} \backslash A\right|=p_{0}-\left|A_{0} \cap A\right|=p_{0}-k$. For $I_{2}\left(B_{k j}\right)$, it follows from Lemma 4 that the moment generating function $M(t)$ of $\boldsymbol{\epsilon}^{T}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon} / \sigma^{2}$ satisfies: $\log M(t)=$ $\left.\sum_{r=1}^{\infty}\left(2^{r-1} t^{r} / r\right) \operatorname{Tr}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{A_{0}}\right)^{r}\right) \leq t\left(|A|-\left|A_{0}\right|\right)+\operatorname{Tr}\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{A_{0}}\right)^{2}\right) \sum_{r=2}^{\infty}\left(2^{r-1} t^{r} / r\right) \leq t(|A|-$ $\left.\left|A_{0}\right|\right)+t^{2} /(1-2 t) \operatorname{Tr}\left(\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{A_{0}}\right)^{2} \leq t\left(|A|-\left|A_{0}\right|+|A|+\left|A_{0}\right|-2\left|A \cap A_{0}\right|\right)=2 t\left|A \backslash A_{0}\right|\right.$, for $0<t<1 / 2$. Similarly, for any $0<t_{1}<1 / 2$,

$$
I_{2}\left(B_{k j}\right) \leq E \exp \left(\frac{t_{1} L_{2}(A)}{\sigma^{2}}\right) \exp \left(-\frac{b(A)(1-\delta) t_{1}}{\sigma^{2}}\right) \leq \exp \left(-\frac{(1-\delta) t_{2} n i C_{\min }}{\sigma^{2}}+2 t_{1} j\right)
$$

Consequently, from (27) and bounds for $I_{1}\left(B_{k j}\right)$ and $I_{2}\left(B_{k j}\right)$,

$$
\begin{aligned}
I \leq & \sum_{k=0}^{p_{0}-1} \sum_{j=0}^{p_{0}-k}\left(I_{1}\left(B_{k j}\right)+I_{2}\left(B_{k j}\right)\right) \leq \sum_{i=1}^{p_{0}} \sum_{j=0}^{i}\binom{p-p_{0}}{j}\binom{p_{0}}{p_{0}-i} \\
& \left(\exp \left(\frac{2 t_{1}^{2}-\delta t_{1}}{\sigma^{2}} n i C_{\min }\right)+\exp \left(-\frac{(1-\delta) t_{2}}{\sigma^{2}} n i C_{\min }+2 t_{2} j\right)\right) .
\end{aligned}
$$

For simplification, choose $t_{1}=\frac{1}{3}$ and $\delta=\frac{2 t_{1}+1}{2}=\frac{5}{6}$ such that $\delta t_{1}-2 t_{1}^{2}=(1-\delta) t_{1}=\frac{1}{18}$. Note that $\binom{a}{b} \leq a^{b}$ and $\log \left(p-p_{0}\right)+\log p_{0} \leq \log \left(\frac{p^{2}}{4}\right) \leq 2 \log p-1$. Then

$$
\begin{aligned}
I & \leq 2 \sum_{i=1}^{p_{0}} \sum_{j=0}^{i}\left(p-p_{0}\right)^{j} p_{0}^{i} \exp \left(-\frac{i}{18 \sigma^{2}} n C_{\min }+\frac{2}{3} j\right) \\
& \left.=2 \sum_{i=1}^{p_{0}} \exp \left(-i\left(\frac{n C_{\min }}{18 \sigma^{2}}-\log p_{0}\right)\right) \sum_{j=0}^{i} \exp \left(j\left(\frac{2}{3}+\log \left(p-p_{0}\right)\right)\right)\right) \\
& \leq \frac{2}{1-e^{-1}} R\left(\exp \left(-\frac{n}{18 \sigma^{2}}\left(C_{\min }-36 \frac{\log p}{n} \sigma^{2}\right)\right)\right)
\end{aligned}
$$

where $R(x)=x /(1-x)$ is the exponentiated logit function. Using the fact that $I \leq 1$, we obtain that $I \leq\left(\frac{2}{1-e^{-1}}+1\right) \exp \left(-\frac{n}{18 \sigma^{2}}\left(C_{\min }-36 \frac{\log p}{n} \sigma^{2}\right)\right)$, leading to (10). Finally an application of the pointwise bound in (10) to $\boldsymbol{\beta}^{0} \in B_{0}(u, l)$ yields (11), implying consistency by $P\left(\hat{A}^{L_{0}} \neq A_{0}\right) \leq P\left(\hat{\boldsymbol{\beta}}^{L_{0}} \neq \hat{\boldsymbol{\beta}}^{o l}\right)$. The result in (A) is established.

For (B), we note that $n^{-1} E\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{o l}-\boldsymbol{\beta}^{0}\right)\right\|^{2}=\frac{p_{0}}{2 n}$. Let $D=25 \sigma^{2}$ and $G=\left\{\frac{1}{n} \| \boldsymbol{X} \hat{\boldsymbol{\beta}}-\right.$ $\left.\boldsymbol{X} \boldsymbol{\beta}^{0} \|^{2} \geq D\right\}$. Then

$$
\frac{1}{n} E\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{L_{0}}-\boldsymbol{\beta}^{0}\right)\right\|^{2}=\frac{1}{n} E\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{L_{0}}-\boldsymbol{\beta}^{0}\right)\right\|^{2}\left(I(G)+I\left(G^{c}\right)\right) \equiv T_{1}+T_{2}
$$

For $T_{1}$, note that $\frac{1}{4 n}\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{L_{0}}-\boldsymbol{\beta}^{0}\right)\right\|^{2}-\frac{1}{2 n}\|\boldsymbol{\epsilon}\|^{2} \leq \frac{1}{2 n}\left\|\boldsymbol{Y}-\boldsymbol{X} \hat{\boldsymbol{\beta}}^{L_{0}}\right\|^{2} \leq \frac{1}{2 n}\|\boldsymbol{\epsilon}\|^{2}$, and $T_{1}=$ $D P\left(\frac{1}{n}\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{L_{0}}-\boldsymbol{\beta}^{0}\right)\right\|^{2} \geq D\right)+\int_{D}^{\infty} P\left(\frac{1}{n}\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{L_{0}}-\boldsymbol{\beta}^{0}\right)\right\|^{2} \geq x\right) d x$. For any $x>0$, by Markov's inequality with $t=\frac{1}{3}$,

$$
\begin{aligned}
& \int_{D}^{\infty} P\left(\frac{1}{n}\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{L_{0}}-\boldsymbol{\beta}^{0}\right)\right\|^{2} \geq x\right) d x \\
\leq & \int_{D}^{\infty} P\left(\frac{1}{n}\|\boldsymbol{\epsilon}\|^{2} \geq \frac{x}{4}\right) d x \leq \int_{D}^{\infty} E \exp \left(\frac{t\|\boldsymbol{\epsilon}\|^{2}}{\sigma^{2}}\right) \exp \left(-n t \frac{x}{4 \sigma^{2}}\right) d x \\
\leq & \int_{D}^{\infty} \exp \left(-\frac{n t}{12 \sigma^{2}}\left(x-24 \sigma^{2}\right)\right) d x=\frac{12 \sigma^{2}}{n t} \exp \left(-\frac{n}{12}\right)=o\left(\frac{p_{0}}{2 n}\right) .
\end{aligned}
$$

Similarly, $D P\left(\frac{1}{n}\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}^{L_{0}}-\boldsymbol{\beta}^{0}\right)\right\|^{2} \geq D\right) \leq 25 \sigma^{2} \exp \left(-\frac{n t}{12 \sigma^{2}}\left(D-24 \sigma^{2}\right)\right)=o\left(\frac{p_{0}}{2 n}\right)$. Hence, $T_{1}=o\left(\frac{p_{0}}{2 n}\right)$. For $T_{2}$, note that

$$
\begin{aligned}
T_{2} & \leq D P\left(\hat{\boldsymbol{\beta}}^{L_{0}} \neq \hat{\boldsymbol{\beta}}^{o l}\right)+\frac{1}{n} E\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{o l}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2} \\
& =25 \sigma^{2} P\left(\hat{\boldsymbol{\beta}}^{L_{0}} \neq \hat{\boldsymbol{\beta}}^{o l}\right)+\frac{p_{0}}{2 n}=(o(1)+1) \frac{p_{0}}{2 n}
\end{aligned}
$$

implying the risk result.
For minimaxity, note that

$$
\inf _{\hat{\boldsymbol{\beta}}} \sup _{\boldsymbol{\beta}^{0} \in B_{0}(u, l)} n^{-1} E\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}-\boldsymbol{\beta}^{0}\right)\right\|^{2} \geq \inf _{\hat{\boldsymbol{\beta}}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0} \in \mathcal{B}} \sup n^{-1} E\left\|\boldsymbol{X}_{A_{0}}\left(\hat{\boldsymbol{\beta}}_{A_{0}}-\boldsymbol{\beta}_{A_{0}}^{0}\right)\right\|^{2}
$$

where $\mathcal{B}=\left\{\boldsymbol{\beta}_{A_{0}}:\left|A_{0}\right|=u, n^{-1}\left\|\boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}-\boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}\right\|^{2} \geq l\right\}$. The result follows from the same argument as that for the least squares estimate to be minimax, c.f., Judge and Bock (1978). This completes the proof.

Proof of Theorem 3: Our strategy is similar to that in the proof of Theorem 2. Let $S\left(\hat{\boldsymbol{\beta}}^{T}\right) \equiv \frac{1}{2}\left\|\boldsymbol{Y}-\boldsymbol{X}_{A_{1}} \hat{\boldsymbol{\beta}}_{A_{1}}^{T}-\boldsymbol{X}_{A_{2}} \hat{\boldsymbol{\beta}}_{A_{2}}^{T}\right\|^{2}, A=A_{1} \cup A_{2}, A_{1}=\left\{j \in A:\left|\hat{\beta}_{j}^{T}\right|>\tau\right\}, A_{2}=\{j \in A:$ $\left.\left|\hat{\beta}_{j}^{T}\right| \leq \tau\right\}$ and $\left\|\boldsymbol{X}_{A_{2}} \hat{\boldsymbol{\beta}}_{A_{2}}^{T}\right\|^{2} \leq c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right) \tau \sum_{j \in A_{2}}\left|\hat{\beta}_{j}^{T}\right|$. Note that $\left|A_{1}\right|+\frac{1}{\tau} \sum_{j \in\left|A_{2}\right|}\left|\hat{\beta}_{j}^{T}\right| \leq p_{0}$. Thus if $A_{1}=A_{0}$ then $\hat{\beta}_{j}^{T}=0$ for all $j \in A_{2}$, implying that $\hat{\boldsymbol{\beta}}^{T}=\hat{\boldsymbol{\beta}}^{o l}$. Therefore, we only consider the case of $A_{1} \neq A_{0}$.

Similarly, let $B_{k j}=\left\{\hat{A}=A:\left|A_{0} \cap A_{1}\right|=k,\left|A_{1} \backslash A_{0}\right|=j\right\}$, then $I \equiv P\left(\hat{\boldsymbol{\beta}}_{\hat{A}}^{T} \neq\right.$ $\left.\hat{\boldsymbol{\beta}}_{A_{0}}^{o l}\right) \leq \sum_{k=0}^{p_{0}-1} \sum_{j=0}^{p_{0}-k} P\left(S\left(\hat{\boldsymbol{\beta}}_{A}^{T}\right)-S\left(\hat{\boldsymbol{\beta}}_{A_{0}}^{o l}\right) \leq 0, B_{k j}\right)$. On $B_{k j}$, we simplify $S\left(\hat{\boldsymbol{\beta}}_{A}^{T}\right)-S\left(\hat{\boldsymbol{\beta}}_{A_{0}}^{o l}\right)$. An application of inequality $\|\boldsymbol{U}-\boldsymbol{V}\|^{2} \geq \frac{a-1}{a}\|\boldsymbol{U}\|^{2}-(a-1)\|\boldsymbol{V}\|^{2}$ for $\boldsymbol{U}, \boldsymbol{V} \in \mathbb{R}^{p}$ and some $a>1$, together with the fact that $\left\|\boldsymbol{Y}-\boldsymbol{X}_{A_{1}} \hat{\boldsymbol{\beta}}_{A_{1}}^{T}\right\|^{2} \geq\left\|\boldsymbol{Y}-\boldsymbol{X}_{A_{1}} \hat{\boldsymbol{\beta}}_{A_{1}}^{o l}\right\|^{2}$ yields that

$$
\begin{aligned}
S\left(\hat{\boldsymbol{\beta}}^{T}\right) \geq & \frac{a-1}{2 a}\left\|\boldsymbol{Y}-\boldsymbol{X}_{A_{1}} \hat{\boldsymbol{\beta}}_{A_{1}}^{T}\right\|^{2}-\frac{a-1}{2}\left\|\boldsymbol{X}_{A_{2}} \hat{\boldsymbol{\beta}}_{A_{2}}^{T}\right\|^{2} \\
\geq & \frac{a-1}{2 a}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}+\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{\epsilon}\right\|^{2}-\frac{a-1}{2} p c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right) \tau^{2} \\
\geq & \frac{a-1}{a} \boldsymbol{\epsilon}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}+\frac{a-1}{2 a}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2} \\
& +\frac{a-1}{2 a}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{\epsilon}\right\|^{2}-\frac{a-1}{2} p c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right) \tau^{2}
\end{aligned}
$$

Let $\lambda=\frac{a-1}{2} p c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right) \tau^{2}$. Then

$$
\begin{aligned}
& 2\left(S\left(\hat{\boldsymbol{\beta}}^{T}\right)-S\left(\hat{\boldsymbol{\beta}}^{o l}\right)\right) \geq 2\left(S\left(\hat{\boldsymbol{\beta}}^{T}\right)-\frac{1}{2}\left\|\left(I-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon}\right\|^{2}\right) \\
= & 2((a-1) / a) \boldsymbol{\epsilon}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}+((a-1) / a)\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2} \\
& -\boldsymbol{\epsilon}^{T}\left(\boldsymbol{I}+(a-1) \boldsymbol{P}_{A_{1}}-a \boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon} / a-2 \lambda \\
= & -\frac{1}{a}\left(\boldsymbol{\epsilon}-(a-1)\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right)^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right)\left(\boldsymbol{\epsilon}-(a-1)\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right) \\
& +(a-1)\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}-\boldsymbol{\epsilon}^{T}\left(\boldsymbol{P}_{A_{1}}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon}-2 \lambda
\end{aligned}
$$

For any $0<\delta<1$, let $b_{1}\left(A_{1}\right)=(a-1-\delta)\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}, b_{2}\left(A_{1}\right)=\delta \|(\boldsymbol{I}-$ $\left.\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}} \|^{2}-2 \lambda, L_{1}\left(A_{1}\right)=\frac{1}{a}\left(\boldsymbol{\epsilon}-(a-1)\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right)^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right)(\boldsymbol{\epsilon}-(a-1)(\boldsymbol{I}-$ $\left.\left.\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right), L_{2}\left(A_{1}\right)=\boldsymbol{\epsilon}^{T}\left(\boldsymbol{P}_{A_{1}}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon}$. Note that $a L_{1}\left(A_{1}\right)$ follows $\sigma^{2} \chi_{k}^{2}$, where the noncentral $\chi_{k}^{2}$ distribution has degrees of freedom $n-\min \left(r\left(A_{1}\right), n\right)$ with $r\left(A_{1}\right) \leq\left|A_{1}\right|$ being the
rank of $A_{1}$, and a non-central parameter $(a-1)^{2} \sigma^{-2}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}$. Hence,

$$
\begin{aligned}
& P\left(S\left(\hat{\boldsymbol{\beta}}_{A}^{T}\right)-S\left(\hat{\boldsymbol{\beta}}_{A_{0}}^{o l}\right) \leq 0, B_{k j}\right) \\
\leq & P\left(L_{1}\left(A_{1}\right) \geq b_{1}\left(A_{1}\right)\right)+P\left(L_{2}\left(A_{1}\right) \geq b_{2}\left(A_{1}\right)\right) \equiv I_{1}\left(B_{k j}\right)+I_{2}\left(B_{k j}\right),
\end{aligned}
$$

where

$$
\begin{aligned}
I_{1}\left(B_{k j}\right) & \leq E \exp \left(\frac{t_{1}}{\sigma^{2}} L_{1}\left(A_{1}\right)\right) \exp \left(-\frac{t_{1}}{\sigma^{2}} b_{1}\left(A_{1}\right)\right) \\
& =\frac{1}{\left(1-2 t_{1} / a\right)^{\frac{n-r\left(A_{1}\right)}{2}}} \exp \left(-\frac{t_{1}\left(1-2 t_{1}-\delta\right)}{\sigma^{2}\left(1+\left(1-2 t_{1}\right) /(a-1)\right)} n i C_{\min }\right) \\
I_{2}\left(B_{k j}\right) & \leq E \exp \left(\frac{t_{1}}{\sigma^{2}} L_{2}\left(A_{1}\right)\right) \exp \left(-\frac{t_{1}}{\sigma^{2}} b_{2}\left(A_{1}\right)\right) \\
& \leq \exp \left(-\frac{\delta t_{1}}{\sigma^{2}} n i C_{\min }+2 t_{1} j+2 t_{1} \lambda / \sigma^{2}\right),
\end{aligned}
$$

for any $0<t_{1}<1 / 2$, where the last inequality uses $n C_{\text {min }} \leq \frac{b(A)}{\left|A_{0} \backslash A\right|}$ with $\left|A_{0} \backslash A\right|=$ $p_{0}-\left|A_{0} \cap A\right|=p_{0}-k \equiv i$. Consequently,

$$
\begin{aligned}
I & \leq \sum_{i=1}^{p_{0}} \sum_{j=0}^{i}\binom{p-p_{0}}{j}\binom{p_{0}}{p_{0}-i}\left(\exp \left(-\frac{\delta t_{1}}{\sigma^{2}} n i C_{\min }+2 t_{1} j+t_{1} \lambda / \sigma^{2}\right)\right. \\
& \left.+\frac{1}{\left(1-2 t_{1} / a\right)^{\frac{n-r\left(A_{1}\right)}{2}}} \exp \left(-\frac{t_{1}\left(1-2 t_{1}-\delta\right)}{\sigma^{2}\left(1+\left(1-2 t_{1}\right) /(a-1)\right)} n i C_{\min }\right)\right)
\end{aligned}
$$

To simplify this bound, choose $t_{1}=\frac{1}{3}, \delta=\frac{1}{6}, a=n+1$ and $\lambda \leq \sigma^{2}$. Similarly,

$$
\begin{aligned}
I & \leq 2 \sum_{i=1}^{p_{0}} \sum_{j=0}^{i}\left(p-p_{0}\right)^{j} p_{0}^{i} \exp \left(-\frac{i}{20 \sigma^{2}} n C_{\min }+\frac{2}{3} j+\frac{1}{3}\right) \\
& \left.=2 \sum_{i=1}^{p_{0}} \exp \left(-i\left(\frac{n C_{\min }}{20 \sigma^{2}}-\log p_{0}\right)\right) \sum_{j=0}^{i} \exp \left(j\left(1+\log \left(p-p_{0}\right)\right)\right)\right) \\
& \leq\left(\frac{2}{e-1}+1\right) R\left(\exp \left(-\frac{n}{20 \sigma^{2}}\left(C_{\min }-40 \frac{\log p}{n} \sigma^{2}\right)\right)\right)
\end{aligned}
$$

yielding (14). The rest of the results follow similarly as in the proof of Theorem 2. This completes the proof.

Proof of Lemma 2: The finite termination property of Algorithm 1 follows from nonincreasingness of $S^{(m)}\left(\hat{\boldsymbol{\beta}}^{(m)}\right)$ in $m$, as in the proof of Theorem 1 of Shen et al. (2012).

Now consider the DC solution of (22) $\hat{\boldsymbol{\beta}}^{(m)}$ at iteration $m$ for given $K>0$. Let the termination index be $m^{*}$. Then Karush-Kuhn-Tucker conditions imply that there exists a Lagrange multiplier $\lambda \geq 0$ such that the DC solution of (22) $\hat{\boldsymbol{\beta}}^{\left(m^{*}\right)}$ minimizes the Lagrange function $L(\boldsymbol{\beta}, \lambda)=S(\boldsymbol{\beta})-\lambda\left(K-\sum_{j=1}^{p}\left|\beta_{j}\right| I\left(\hat{\beta}_{j}^{\left(m^{*}-1\right)} \mid>\tau\right)\right.$, or equivalently. $\bar{S}(\boldsymbol{\beta})=S(\boldsymbol{\beta})+$ $\lambda \sum_{j=1}^{p}\left|\beta_{j}\right| I\left(\hat{\beta}_{j}^{\left(m^{*}-1\right)} \mid>\tau\right)$, with respect to $\boldsymbol{\beta}$. By Theorem 1 of Shen et al. (2012), $\hat{\boldsymbol{\beta}}^{\left(m^{*}\right)}=$ $\hat{\boldsymbol{\beta}}^{\left(m^{*}-1\right)}$ at termination. Consequently, $\bar{S}\left(\hat{\boldsymbol{\beta}}^{\left(m^{*}\right)}\right)=\bar{S}\left(\hat{\boldsymbol{\beta}}^{\left(m^{*}-1\right)}\right)$. This means that if Algorithm 1 of Shen et al. (2012) is initialized with $\hat{\boldsymbol{\beta}}^{\left(m^{*}\right)}$ then $\hat{\boldsymbol{\beta}}^{\left(m^{*}\right)}$ is also a DC solution of (21) with respect to $\lambda$.

Conversely, for the solution of (22), the case of $\lambda=0$ is trivial and is thus omitted. Now for given $\lambda>0$ and a DC solution of (22) $\hat{\boldsymbol{\beta}}^{\left(m_{0}\right)}$ at iteration $m$, define $K^{\left(m_{0}\right)}=$ $\frac{1}{\tau} \sum_{j=1}^{p}\left|\hat{\beta}_{j}^{\left(m_{0}\right)}\right| I\left(\left|\hat{\beta}_{j}^{\left(m_{0}-1\right)}\right| \leq \tau\right)$, where $m_{0}$ the termination index of the unconstrained Algorithm 1 of Shen et al. (2012), which is assured by Theorem 1 of Shen et al. (2012). Hence a DC solution $\hat{\boldsymbol{\beta}}^{\left(m_{0}\right)}$ of (22) is also a solution of (21) by checking Karush-Kuhn-Tucker conditions for the constrained problem with $K^{\left(m_{0}\right)}$. Similarly, if Algorithm 1 is initialized by $\hat{\boldsymbol{\beta}}^{\left(m_{0}\right)}$, then $\hat{\boldsymbol{\beta}}^{\left(m_{0}\right)}$ is also a DC solution of (21). This is because $\hat{\boldsymbol{\beta}}^{(m)}=\hat{\boldsymbol{\beta}}^{\left(m_{0}\right)}$ for $m \geq m_{0}$. This completes the proof.
Proof of Proposition 1: It suffices to minimize componentwisely: $\hat{\beta}_{j}=\arg \min _{\beta_{j}} f_{j}\left(\beta_{j}\right)$, with $f\left(\beta_{j}\right)=\frac{1}{2}\left(\beta_{j}-\hat{\beta}_{j}^{o l}\right)^{2}+\lambda \min \left(\frac{\left|\beta_{j}\right|}{\tau}, 1\right) ; j=1, \cdots, p$. If $\left|\beta_{j}\right| \leq \tau, \hat{\beta}_{j}=\left(\left|\hat{\beta}_{j}^{o l}\right|-\frac{\lambda}{\tau}\right)_{+} \operatorname{sign}\left(\hat{\beta}_{j}^{o l}\right)$, otherwise, $\min _{\left|\beta_{j}\right|>\tau} f\left(\beta_{j}\right)=\lambda$ if $\beta_{j}=\hat{\beta}_{j}^{o l}$. Moreover, $\min _{\left\{\beta_{j}:\left|\beta_{j}\right| \leq \tau\right\}} f\left(\beta_{j}\right)$ is

$$
\begin{cases}f(0)=\frac{1}{2}\left(\hat{\beta}_{j}^{o l}\right)^{2} & \text { when }\left|\hat{\beta}_{j}^{o l}\right| \leq \frac{\lambda}{\tau} \\ f\left(\operatorname{sign}\left(\hat{\beta}_{j}^{o l}\right) \tau\right)=\frac{1}{2}\left(\tau-\left|\hat{\beta}_{j}^{o l}\right|\right)^{2}+\lambda & \text { when }\left|\hat{\beta}_{j}^{o l}\right| \geq \frac{\lambda}{\tau}+\tau ; \\ f\left(\left(\left|\hat{\beta}_{j}^{o l}\right|-\frac{\lambda}{\tau}\right) \operatorname{sign}\left(\hat{\beta}_{j}^{o l}\right)\right)=\frac{\lambda}{\tau}\left|\hat{\beta}_{j}^{o l}\right|-\frac{\lambda^{2}}{2 \tau^{2}} & \text { when } \frac{\lambda}{\tau}<\left|\hat{\beta}_{j}^{o l}\right|<\frac{\lambda}{\tau}+\tau\end{cases}
$$

Then comparing $f$ at $0, \tau,\left(\left|\hat{\beta}_{j}^{o l}\right|-\frac{\lambda}{\tau}\right)_{+} \operatorname{sign}\left(\hat{\beta}_{j}^{o l}\right)$ against $f$ at $\lambda$, the TLP estimate is

$$
\begin{cases}\hat{\beta}_{j}^{o l} & \text { if }\left|\hat{\beta}_{j}^{o l}\right| \geq \max \left(\frac{\lambda}{2 \tau}+\tau, \frac{\lambda}{\tau}\right), \text { or } \frac{\lambda}{\tau} \geq\left|\hat{\beta}_{j}^{o l}\right| \geq \max (\sqrt{2 \lambda}, \tau) ; \\ \left(\left|\hat{\beta}_{j}^{o l}\right|-\frac{\lambda}{\tau}\right) \operatorname{sign}\left(\hat{\beta}_{j}^{o l}\right) & \text { if } \frac{\lambda}{2 \tau}+\tau \geq\left|\hat{\beta}_{j}^{o l}\right| \geq \max \left(\frac{\lambda}{\tau}, \tau\right), \text { or } \tau \geq\left|\hat{\beta}_{j}^{o l}\right| \geq \frac{\lambda}{\tau} ; \\ 0 & \text { if } \min \left(\frac{\lambda}{\tau}, \tau\right) \geq\left|\hat{\beta}_{j}^{o l}\right|, \text { or } \min \left(\sqrt{2 \lambda}, \frac{\lambda}{\tau}\right) \geq\left|\hat{\beta}_{j}^{o l}\right| \geq \tau\end{cases}
$$

$j=1, \cdots, p$, leading to the desired result. This completes the proof.
Proof of Theorem 5: We only present the proof for the case where $\alpha>1$. The proof for the case $\alpha=1$ is similar, thus omitted. Write $\hat{A}^{t l}=\hat{A}_{1} \cup \hat{A}_{2}, \hat{A}_{1}=\left\{j \in \hat{A}^{t l}:\left|\hat{\beta}_{j}^{t l}\right|>\tau\right\}$ and
$\hat{A}_{2}=\left\{j \in \hat{A}^{t l}:\left|\hat{\beta}_{j}^{t l}\right| \leq \tau\right\}$. Then $P\left(\hat{\boldsymbol{\beta}}^{t l} \neq \hat{\boldsymbol{\beta}}^{o l}\right) \leq I_{1}+I_{2}+P\left(\hat{\boldsymbol{\beta}}^{o l}\right.$ is not a solution of (23)), where the last term in this inequality is bounded by $I_{6}$ in the proof of Theorem 4. Thus it suffices to bound $I_{1}=P\left(\cup_{A_{1} \subseteq\{1, \cdots, p\}: A_{1} \neq A_{0}}\left(S\left(\hat{\boldsymbol{\beta}}^{t l}\right)-S\left(\tilde{\boldsymbol{\beta}}^{o l}\right) \leq 0, \hat{A}_{1}=A_{1}\right) ; I_{2}=P\left(\hat{A}_{1}=\right.\right.$ $A_{0}, \hat{\boldsymbol{\beta}}^{t l} \neq \hat{\boldsymbol{\beta}}^{o l}, \hat{\boldsymbol{\beta}}^{o l}$ is a solution of (23)).

For $I_{1}$, on $\hat{A}_{1}=A_{1}$ with $A_{1} \neq A_{0}$, write $S\left(\hat{\boldsymbol{\beta}}^{t l}\right)$ as $\frac{1}{2}\left\|\boldsymbol{Y}-\boldsymbol{X}_{A_{1}} \hat{\boldsymbol{\beta}}_{A_{1}}^{t l}-\boldsymbol{X}_{\hat{A}_{2}} \hat{\boldsymbol{\beta}}_{A_{2}}^{t l}\right\|^{2}+$ $\frac{\lambda}{\tau} \sum_{j \in \hat{A}_{2}}\left|\hat{\beta}_{j}^{t l}\right|+\lambda\left|A_{1}\right|$. Note that $\left\|\boldsymbol{Y}-\boldsymbol{X}_{A_{1}} \hat{\boldsymbol{\beta}}_{A_{1}}^{t l}\right\|^{2} \geq\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{Y}\right\|^{2}$, and $\left\|\boldsymbol{X}_{\hat{A}_{2}} \hat{\boldsymbol{\beta}}_{\hat{A}_{2}}^{t l}\right\|^{2} \leq$ $c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right) \tau \sum_{j \in \hat{A}_{2}}\left|\hat{\beta}_{j}^{t l}\right|$, and $\frac{\lambda}{\tau}-\frac{a}{2} c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right) \tau \geq 0$ (by assumption) with real $a>1$ to be chosen. Using $\|U-V\|^{2} \geq \frac{a-1}{a}\|U\|^{2}-(a-1)\|V\|^{2}$ for any vectors $U, V \in \mathcal{R}^{n}$,

$$
\begin{aligned}
& S\left(\hat{\boldsymbol{\beta}}^{t l}\right)-\lambda\left|A_{1}\right| \geq \frac{a-1}{2 a}\left\|\boldsymbol{Y}-\boldsymbol{X}_{A_{1}} \hat{\boldsymbol{\beta}}_{A_{1}}^{t l}\right\|^{2}-\frac{a-1}{2}\left\|\boldsymbol{X}_{\hat{A}_{2}} \hat{\boldsymbol{\beta}}_{\hat{A}_{2}}^{t l}\right\|^{2}+\frac{\lambda}{\tau} \sum_{j \in \hat{A}_{2}}\left|\hat{\beta}_{j}^{t l}\right| \\
\geq & \left(\frac{a-1}{2 a}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{Y}\right\|^{2}\right)+\left(\frac{\lambda}{\tau}-\frac{a-1}{2} c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right) \tau\right) \sum_{j \in \hat{A}_{2}}\left|\hat{\beta}_{j}^{t l}\right| \\
\geq & \left(\frac{a-1}{2 a}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}+\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{\epsilon}\right\|^{2}\right) .
\end{aligned}
$$

So $2\left(S\left(\hat{\boldsymbol{\beta}}^{t l}\right)-S\left(\hat{\boldsymbol{\beta}}^{o l}\right)\right) \geq-\frac{1}{a}\left(\boldsymbol{\epsilon}-(a-1)\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right)^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right)(\boldsymbol{\epsilon}-(a-1)(\boldsymbol{I}-$ $\left.\left.\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right)+(a-1)\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}-\boldsymbol{\epsilon}^{T}\left(\boldsymbol{P}_{A_{1}}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon}+2 \lambda\left(\left|A_{1}\right|-p_{0}\right)$.

Note that $I_{1} \leq \sum_{k=0}^{p_{0}-1} \sum_{j=0}^{p-k}\binom{p_{0}}{k}\binom{p-p_{0}}{j} P\left(S\left(\hat{\boldsymbol{\beta}}^{t l}\right)-S\left(\hat{\boldsymbol{\beta}}^{o l}\right) \leq 0, B_{k j}\right)$, where $B_{k j}=\left\{\hat{A}_{1}=\right.$ $\left.A_{1} \neq A_{0}:\left|A_{1} \backslash A_{0}\right|=j,\left|A_{1} \cap A_{0}\right|=k\right\}$. For any $0<\delta<1$, let $b_{A_{1}}^{1}=(a-1-$ $\delta)\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}+\lambda\left(\left|A_{1}\right|-p_{0}\right), b_{A_{1}}^{2}=\delta\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}+\lambda\left(\left|A_{1}\right|-p_{0}\right), L_{A_{1}}^{1}=$ $\frac{1}{a}\left(\boldsymbol{\epsilon}-(a-1)\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right)^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right)\left(\boldsymbol{\epsilon}-(a-1)\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right), L_{A_{1}}^{2}=\boldsymbol{\epsilon}^{T}\left(\boldsymbol{P}_{A_{1}}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon}$. Note that $a L_{A_{1}}^{1}$ follows $\sigma^{2} \chi_{k}^{2}$, where the non-central $\chi_{k}^{2}$ distribution has degrees of freedom $n-\min \left(r\left(A_{1}\right), n\right)$ with $r\left(A_{1}\right) \leq\left|A_{1}\right|$ being the rank of $A_{1}$, and a non-central parameter $(a-1)^{2} \sigma^{-2}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}$. For $L_{A_{1}}^{2}$, it follows from Lemma 4 that the moment generating function $M(t)$ of $L_{A_{1}}^{2}$ satisfies: $\left.\log M(t)=\sum_{r=1}^{\infty}\left(2^{r-1} t^{r} / r\right) \operatorname{Tr}\left(\boldsymbol{P}_{A_{1}}-\boldsymbol{P}_{A_{0}}\right)^{r}\right) \leq$ $t\left(\left|A_{1}\right|-\left|A_{0}\right|\right)+\operatorname{Tr}\left(\left(\boldsymbol{P}_{A_{1}}-\boldsymbol{P}_{A_{0}}\right)^{2}\right) \sum_{r=2}^{\infty}\left(2^{r-1} t^{r} / r\right) \leq t\left(\left|A_{1}\right|-\left|A_{0}\right|\right)+t^{2} /(1-2 t) \operatorname{Tr}\left(\left(\boldsymbol{P}_{A_{1}}-\right.\right.$ $\left.\boldsymbol{P}_{A_{0}}\right)^{2} \leq t\left(|A|-\left|A_{0}\right|+\left|A_{1}\right|+\left|A_{0}\right|-2\left|A_{1} \cap A_{0}\right|\right)=2 t\left|A_{1} \backslash A_{0}\right|$, for $0<t<1 / 2$. Let $I_{k j}^{1}=$ $P\left(L_{A_{1}}^{1} \geq b_{A_{1}}^{1}\right)$ and $I_{k j}^{2}=P\left(L_{A_{1}}^{2} \geq b_{A_{1}}^{2}\right)$. Hence $P\left(S\left(\hat{\boldsymbol{\beta}}^{t l}\right)-S\left(\hat{\boldsymbol{\beta}}^{o l}\right) \leq 0, B_{k j}\right) \leq I_{k j}^{1}+I_{k j}^{2}$.

For $I_{k j}^{l} ; l=1,2$, note that $\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}\right\|^{2} \geq n i C_{\text {min }}$ if $j \leq[\alpha i] \equiv \alpha\left(p_{0}-k\right)$ by definition of $C_{\min }$ or if $\left|A_{1} \backslash A_{0}\right| \leq \alpha\left|A_{0} \backslash A_{1}\right|\left(\left|A_{1}\right|+(\alpha-1)\left|A_{1} \cap A_{0}\right| \leq \alpha p_{0}\right)$ with
$\left|A_{0} \backslash A_{1}\right|=p_{0}-\left|A_{0} \cap A_{1}\right|=i$; or 0 if $[\alpha i]<j \leq p$. By Markov's inequality,

$$
\begin{aligned}
I_{k j}^{1} & \leq E \exp \left(\frac{t_{1}}{\sigma^{2}} L_{1}\left(A_{1}\right)\right) \exp \left(-\frac{t_{1}}{\sigma^{2}} b_{1}\left(A_{1}\right)\right) \\
& =\frac{1}{\left(1-2 t_{1} / a\right)^{\frac{n-r\left(A_{1}\right)}{2}}} \exp \left(-\frac{t_{1}\left(1-2 t_{1}-\delta\right)}{\sigma^{2}\left(1+\left(1-2 t_{1}\right) /(a-1)\right)} n i C_{\min }+t_{1} \lambda(i-j) / \sigma^{2}\right) \\
I_{k j}^{2} & \leq E \exp \left(\frac{t_{1}}{\sigma^{2}} L_{2}\left(A_{1}\right)\right) \exp \left(-\frac{t_{1}}{\sigma^{2}} b_{2}\left(A_{1}\right)\right) \\
& \leq \exp \left(-\frac{\delta t_{1}}{\sigma^{2}} n i C_{\min }+2 t_{1} j+t_{1} \lambda(i-j) / \sigma^{2}\right),
\end{aligned}
$$

for any $0<t_{1}<1 / 2$. Therefore $I_{1} \leq \sum_{k=0}^{p_{0}-1} \sum_{j=0}^{p-k}\binom{p-p_{0}}{j}\binom{p_{0}}{k}\left(I_{k j}^{1}+I_{k j}^{2}\right)$, which is bounded by

$$
\begin{aligned}
& \sum_{i=1}^{p_{0}} \sum_{j=0}^{[\alpha i]}\binom{p-p_{0}}{j}\binom{p_{0}}{p_{0}-i}\left(\exp \left(-\frac{\delta t_{1}}{\sigma^{2}} n i C_{\min }+2 t_{1} j+t_{1} \lambda(i-j) / \sigma^{2}\right)\right. \\
& \left.+\frac{1}{\left(1-2 t_{1} / a\right)^{\frac{n-r\left(A_{1}\right)}{2}}} \exp \left(-\frac{t_{1}\left(1-2 t_{1}-\delta\right)}{\sigma^{2}\left(1+\left(1-2 t_{1}\right) /(a-1)\right)} n i C_{\min }+t_{1} \lambda(i-j) / \sigma^{2}\right)\right) \\
& \quad+\sum_{i=1}^{p_{0}} \sum_{j=[\alpha i]+1}^{p}\binom{p-p_{0}}{j}\binom{p_{0}}{p_{0}-i}\left(\exp \left(2 t_{1} j+t_{1} \lambda(i-j) / \sigma^{2}\right)\right. \\
& \left.\quad+\frac{1}{\left(1-2 t_{1} / a\right)^{\frac{n-r\left(A_{1}\right)}{2}}} \exp \left(t_{1} \lambda(i-j) / \sigma^{2}\right)\right)
\end{aligned}
$$

To simplify this bound, choose $t_{1}=\frac{1}{3}, \delta=\frac{1}{6}, a=n+1$. Note that $\sum_{j=0}^{b}\binom{a}{j} \leq(a+1)^{b}$, and $\binom{a}{b} \leq a^{b}$, for any integers $a, b>0$. Then

$$
\begin{aligned}
I_{1} & \leq 2 \sum_{i=1}^{p_{0}} p_{0}^{i} \sum_{j=0}^{[\alpha i]}\binom{p-p_{0}}{j} \exp \left(-\frac{i n C_{\min }}{20 \sigma^{2}}+\frac{2 j}{3}+\frac{(i-j) \lambda}{2 \sigma^{2}}\right) \\
& +2 \sum_{j=[\alpha i]+1}^{p}\left(p-p_{0}\right)^{j} \exp \left(\frac{-(\alpha-1) j \lambda}{3 \alpha \sigma^{2}}+\frac{2 j}{3}\right) \sum_{i=0}^{[j / \alpha]}\binom{p_{0}}{i} \\
& \leq 2 \sum_{i=1}^{p_{0}} \exp \left(-i\left(\frac{n C_{\min }}{20 \sigma^{2}}-\log p_{0}-\alpha \log \left(p-p_{0}+1\right)-\frac{\lambda}{2 \sigma^{2}}\right)\right) \\
& +2 \sum_{j=[\alpha i]+1}^{p} \exp \left(-j\left(\frac{(\alpha-1) \lambda}{3 \alpha \sigma^{2}}-\log \left(p-p_{0}\right)-\frac{1}{\alpha} \log \left(p_{0}+1\right)-\frac{2}{3}\right)\right)
\end{aligned}
$$

Using the fact that $I_{1} \leq 1, \log p_{0}+\alpha \log \left(p-p_{0}+1\right) \leq(\alpha+1)\left(\log (p+1)-\log (\alpha+1)+\frac{\alpha}{\alpha+1} \log \alpha\right)$ and $\frac{1}{\alpha} \log \left(p_{0}+1\right)+\log \left(p-p_{0}\right) \leq\left(1+\frac{1}{\alpha}\right)\left(\log (p+1)-\frac{1}{\alpha+1} \log (\alpha+1)-\frac{\alpha}{\alpha+1} \log \left(1+\frac{1}{\alpha}\right)\right)$, we obtain the second and third terms in the bound of (17).

For $I_{2}$, let $E=\left\{\min _{j \in A_{0}}\left|\hat{\beta}_{j}^{o l}\right|>\tau\right\}$. As in the proof of Theorem 6, $P\left(E^{c}\right) \leq\left|A_{0}\right|(\Phi(-$ $\left.\left.\frac{n^{1 / 2}\left(\gamma_{\min }-\tau\right)}{\sigma c_{\min }^{1 / 2}\left(\frac{1}{n} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right)}\right)-\Phi\left(-\frac{n^{1 / 2}\left(\gamma_{\min }+\tau\right)}{\sigma c_{\min }^{-1 / 2}\left(\frac{1}{n} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right)}\right)\right)$ On event $E, \hat{\boldsymbol{\beta}}_{A}^{o l}$ and $\hat{\boldsymbol{\beta}}_{A}^{t l}$ must be local minimizers of $\min _{\boldsymbol{\beta}_{A}} \frac{1}{2}\left\|\boldsymbol{Y}-\boldsymbol{X}_{A} \boldsymbol{\beta}_{A}\right\|^{2}+\frac{\lambda}{\tau} \sum_{j \in \hat{A}_{2}}\left|\beta_{j}\right|$. Note that for any local solution $\hat{\boldsymbol{\beta}}_{A}$ satisfying $\left|\hat{\boldsymbol{\beta}}_{\bar{A}_{0}}\right|>$ $\tau$ with $A_{0} \subset \bar{A}_{0} \subset A$ and $\left|\hat{\boldsymbol{\beta}}_{A_{2}}\right| \leq \tau$ with $A_{2}=A \backslash \bar{A}_{0}$, the local optimality condition for $\boldsymbol{\beta}_{\bar{A}_{0}}^{t l}$ is $\left(x^{(j)}\right)^{T}\left(\boldsymbol{Y}-\boldsymbol{X}_{\bar{A}_{0}} \hat{\boldsymbol{\beta}}_{\bar{A}_{0}}^{t l}-\boldsymbol{X}_{A_{2}} \hat{\boldsymbol{\beta}}_{A_{2}}^{t l}\right)=0$ for $j \in \bar{A}_{0}$, implying $\hat{\boldsymbol{\beta}}_{\bar{A}_{0}}^{t l}=\left(\boldsymbol{X}_{\bar{A}_{0}}^{T} \boldsymbol{X}_{\bar{A}_{0}}\right)^{-1} \boldsymbol{X}_{\bar{A}_{0}}^{T}(\boldsymbol{Y}-$ $\left.\boldsymbol{X}_{A_{2}} \hat{\boldsymbol{\beta}}_{A_{2}}^{t l}\right)$. This together with that for $\boldsymbol{\beta}_{A_{2}}:-\left(\boldsymbol{x}^{(j)}\right)^{T}\left(\boldsymbol{Y}-\boldsymbol{X}_{\bar{A}_{0}} \hat{\boldsymbol{\beta}}_{\bar{A}_{0}}^{t l}-\boldsymbol{X}_{A_{2}} \hat{\boldsymbol{\beta}}_{A_{2}}^{t l}\right)+\frac{\lambda}{\tau} \operatorname{sign}\left(\hat{\beta}_{j}^{t l}\right)=0$ for $j \in A_{2}$, implies that $-\boldsymbol{X}_{A_{2}}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{\bar{A}_{0}}\right)\left(\boldsymbol{Y}-\boldsymbol{X}_{A_{2}} \hat{\boldsymbol{\beta}}_{A_{2}}^{t l}\right)+\frac{\lambda}{\tau} \operatorname{sign}\left(\hat{\boldsymbol{\beta}}_{A_{2}}^{t l}\right)=0$ that is the local optimality for (28). Hence both $\hat{\boldsymbol{\beta}}_{A_{2}}^{o l}$ and $\hat{\boldsymbol{\beta}}_{A_{2}}^{t l}$ are local minimizers of

$$
\begin{equation*}
\min _{\beta_{A_{2}}} \frac{1}{2}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{\bar{A}_{0}}\right) \boldsymbol{Y}-\left(\boldsymbol{I}-\boldsymbol{P}_{\bar{A}_{0}}\right) \boldsymbol{X}_{A_{2}} \boldsymbol{\beta}_{A_{2}}\right\|^{2}+\frac{\lambda}{\tau} \sum_{j \in A_{2}}\left|\beta_{j}\right| . \tag{28}
\end{equation*}
$$

By Rinaldo (2007), $\left(\boldsymbol{I}-\boldsymbol{P}_{\bar{A}_{0}}\right) \boldsymbol{X}_{A_{2}} \hat{\boldsymbol{\beta}}_{A_{2}}^{t l}=\left(\boldsymbol{I}-\boldsymbol{P}_{\bar{A}_{0}}\right) \boldsymbol{X}_{A_{2}} \hat{\boldsymbol{\beta}}_{A_{2}}^{o l}$ and $\left\|\hat{\boldsymbol{\beta}}_{A_{2}}^{t l}\right\|_{1}=\left\|\hat{\boldsymbol{\beta}}_{A_{2}}^{o l}\right\|_{1}=0$. Thus $\hat{\boldsymbol{\beta}}^{t l}=\hat{\boldsymbol{\beta}}^{o l}$ on $E$, implying that $I_{2} \leq P\left(E^{c}\right)$. Combining the above bounds yields (17).

For (B), let $D=2 C_{m i n}+4 \sigma^{2}$ and $G=\left\{\frac{1}{n}\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{t l}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2} \geq D\right\}$. Then

$$
\frac{1}{n} E\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{t l}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}=\frac{1}{n} E\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{t l}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}\left(I(G)+I\left(G^{c}\right)\right) \equiv T_{1}+T_{2}
$$

For $T_{1}$, note that $\frac{1}{4 n}\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{t l}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}-\frac{1}{2 n}\|\boldsymbol{\epsilon}\|^{2} \leq \frac{1}{2 n}\left\|\boldsymbol{Y}-\boldsymbol{X} \hat{\boldsymbol{\beta}}^{t l}\right\|^{2} \leq \frac{1}{2 n}\|\boldsymbol{\epsilon}\|^{2}+\frac{\lambda}{n} p_{0}$. Then for any $x>0,\left\{\frac{1}{n}\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{t l}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2} \geq x\right\} \subseteq\left\{\frac{x}{4}-\frac{\lambda}{n} p_{0} \leq \frac{1}{n}\|\boldsymbol{\epsilon}\|^{2}\right\} \subseteq\left\{\frac{x}{4}-\frac{C_{\text {min }}}{8} \leq \frac{1}{n}\|\boldsymbol{\epsilon}\|^{2}\right\}$. By Markov's inequality with $t=\frac{1}{3}, T_{1}=D P\left(\frac{1}{n}\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{t l}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2} \geq D\right)+\int_{D}^{\infty} P\left(\frac{1}{n}\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{t l}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2} \geq x\right) d x$.
Note that the second term there is upper bounded by

$$
\begin{gathered}
\int_{D}^{\infty} P\left(\frac{1}{n}\|\boldsymbol{\epsilon}\|^{2} \geq \frac{x}{4}-\frac{C_{\min }}{8}\right) d x \leq \int_{D}^{\infty} E \exp \left(\frac{t\|\boldsymbol{\epsilon}\|^{2}}{\sigma^{2}}\right) \exp \left(-n t \frac{\left(x-2 C_{\min )}\right.}{8 \sigma^{2}}\right) d x \\
\leq \int_{D}^{\infty} \exp \left(-\frac{n t}{\sigma^{2}}\left(x-2 C_{\min }-\frac{\sigma^{2}}{1-2 t}\right)\right) d x=o\left(\frac{p_{0}}{n} \sigma^{2}\right)
\end{gathered}
$$

so is $D P\left(\frac{1}{n}\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{t l}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2} \geq D\right)$, implying that $T_{1}=o\left(\frac{p_{0}}{n} \sigma^{2}\right)$. For $T_{2}$, note that $C_{\min } \leq$ $\frac{1}{n}\left\|\boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}\right\|^{2}$. Then $T_{2} \leq D P\left(\hat{\boldsymbol{\beta}}^{t l} \neq \hat{\boldsymbol{\beta}}^{o l}\right)+\frac{1}{n} E\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{o l}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}$.

$$
=\left(\frac{2}{n}\left\|\boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}\right\|^{2}+4 \sigma^{2}\right) P\left(\hat{\boldsymbol{\beta}}^{t l} \neq \hat{\boldsymbol{\beta}}^{o l}\right)+\frac{p_{0}}{n} \sigma^{2}=(o(1)+1) \frac{p_{0}}{n} \sigma^{2} .
$$

The desired result follows from the assumption on $\frac{1}{n}\left\|\boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}\right\|^{2}$, (17) and (3).

For minimaxity, note that

$$
\inf _{\hat{\boldsymbol{\beta}}} \sup _{\boldsymbol{\beta}^{0} \in B_{0}(u, l)} n^{-1} E\left\|\boldsymbol{X}\left(\hat{\boldsymbol{\beta}}-\boldsymbol{\beta}^{0}\right)\right\|^{2} \geq \inf _{\hat{\boldsymbol{\beta}}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0} \in \mathcal{B}} \sup n^{-1} E\left\|\boldsymbol{X}_{A_{0}}\left(\hat{\boldsymbol{\beta}}_{A_{0}}-\boldsymbol{\beta}_{A_{0}}^{0}\right)\right\|^{2}
$$

where $\mathcal{B}=\left\{\boldsymbol{\beta}_{A_{0}}:\left|A_{0}\right|=u, n^{-1}\left\|\boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}-\boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}\right\|^{2} \geq l\right\}$. The result follows from the same argument as that for the least squares estimate to be minimax, c.f., Judge and Bock (1978). The proof for the case when $\alpha=1$ is similar, thus omitted.

Proof of Theorem 4: The proof is similar to that of Theorem 5 with some minor modifications. In the present case, no decomposition of $\hat{A}$ is necessary.

Note that $S\left(\hat{\boldsymbol{\beta}}^{l_{0}}\right)-\lambda|A| \geq \boldsymbol{\epsilon}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}+\frac{1}{2}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}\right\|^{2}+\frac{1}{2}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{\epsilon}\right\|^{2}$. So $2\left(S\left(\hat{\boldsymbol{\beta}}^{l_{0}}\right)-S\left(\hat{\boldsymbol{\beta}}^{o l}\right)\right) \geq 2 \boldsymbol{\epsilon}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}+\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0}\right\|^{2}-\boldsymbol{\epsilon}^{T}\left(\boldsymbol{P}_{A_{1}}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon}+$ $2 \lambda\left(|A|-p_{0}\right)$. Let $b_{A}^{1}=\delta\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}-\lambda\left(|A|-p_{0}\right), b_{A}^{2}=(1-\delta)\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}-$ $\lambda\left(|A|-p_{0}\right), L_{A}^{1}=-2 \boldsymbol{\epsilon}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}$ and $L_{A}^{2}=\boldsymbol{\epsilon}^{T}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon}$. Note that $L_{A}^{1}$ follows $N\left(0,4 \sigma^{2}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}\right)$. Hence, for any $\delta$ with $0<\delta<1$,

$$
\begin{gathered}
P\left(S\left(\hat{\boldsymbol{\beta}}^{l_{0}}\right)-S\left(\hat{\boldsymbol{\beta}}^{o l}\right) \leq 0, B_{k j}\right) \\
\leq P\left(\delta\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}+2 \boldsymbol{\epsilon}^{T}\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}+\lambda\left(|A|-p_{0}\right) \leq 0\right)+ \\
P\left((1-\delta)\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}\right\|^{2}-\boldsymbol{\epsilon}^{T}\left(\boldsymbol{P}_{A}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{\epsilon}+\lambda\left(|A|-p_{0}\right) \leq 0\right) \equiv I_{k j}^{1}+I_{k j}^{2},
\end{gathered}
$$

where $I_{k j}^{l} \leq E \exp \left(\frac{t_{l}}{\sigma^{2}} L_{A}^{l}\right) \exp \left(-\frac{t_{l}}{\sigma^{2}} b_{A}^{l}\right) ; 0<t_{l}<1 / 2, l=1,2$. Note that $\|(\boldsymbol{I}-$ $\left.\boldsymbol{P}_{A_{1}}\right) \boldsymbol{X}_{A_{0}} \boldsymbol{\beta}_{A_{0}}^{0} \|^{2} \geq n i C_{m i n}$ if $j \leq 2 i \equiv 2\left(p_{0}-k\right)$ by definition of $C_{\text {min }}$ or if $\left|A_{1}\right|+\left|A_{1} \cap A_{0}\right| \leq 2 p_{0}$ with $\left|A_{0} \backslash A_{1}\right|=p_{0}-\left|A_{0} \cap A_{1}\right|=i$; or $\geq 0$ if $\alpha i<j \leq p$. Then

$$
\begin{gathered}
I_{1} \leq \sum_{i=1}^{p_{0}} \sum_{j=0}^{[\alpha i]}\binom{p-p_{0}}{j}\binom{p_{0}}{p_{0}-i}\left(\exp \left(\frac{2 t_{1}^{2}-\delta t_{1}}{\sigma^{2}} n i C_{\min }+\frac{t_{1}}{\sigma^{2}} \lambda(i-j)\right)\right. \\
\left.+\exp \left(-\frac{(1-\delta) t_{2}}{\sigma^{2}} n i C_{\min }+\frac{t_{2}}{\sigma^{2}} \lambda(i-j)+2 t_{2} j\right)\right) \\
+\sum_{i=1}^{p_{0}} \sum_{j=[\alpha i]+1}^{p}\binom{p-p_{0}}{j}\binom{p_{0}}{p_{0}-i}\left(\exp \left(\frac{t_{2} \lambda}{\sigma^{2}}(i-j)\right)+\exp \left(\frac{t_{4} \lambda}{\sigma^{2}}(i-j)\right)\right) .
\end{gathered}
$$

To simplify this bound, choose $t_{1}=\frac{1}{3}$ and $\delta=\frac{2 t_{1}+1}{2}=\frac{5}{6}$ such that $\delta t_{1}-2 t_{1}^{2}=(1-$ $\delta) t_{1}=\frac{1}{18}$. Note that $\binom{a}{b} \leq a^{b}$ and $\log \left(p-p_{0}\right)+\log p_{0} \leq \log \left(\frac{p^{2}}{4}\right) \leq 2 \log p-1$. Note that
$\sum_{j=0}^{b}\binom{a}{j} \leq(a+1)^{b}$, and $\binom{a}{b} \leq a^{b}$, for any integers $a, b>0$. Then

$$
\begin{aligned}
I_{1} & \leq 2 \sum_{i=1}^{p_{0}} p_{0}^{i} \sum_{j=0}^{[\alpha i]}\binom{p-p_{0}}{j} \exp \left(-\frac{i n C_{\min }}{28 \sigma^{2}}+\frac{2 j}{3}+\frac{(i-j) \lambda}{2 \sigma^{2}}\right) \\
& +2 \sum_{j=[\alpha i]+1}^{p}\left(p-p_{0}\right)^{j} \exp \left(\frac{-(\alpha-1) j \lambda}{3 \alpha \sigma^{2}}+\frac{2 j}{3}\right) \sum_{i=0}^{[j / \alpha]}\binom{p_{0}}{i} \\
& \leq 2 \sum_{i=1}^{p_{0}} \exp \left(-i\left(\frac{n C_{\min }}{18 \sigma^{2}}-\log p_{0}-\alpha \log \left(p-p_{0}+1\right)-\frac{\lambda}{2 \sigma^{2}}\right)\right) \\
& +2 \sum_{j=|\alpha i|+1}^{p} \exp \left(-j\left(\frac{(\alpha-1) \lambda}{3 \alpha \sigma^{2}}-\log \left(p-p_{0}\right)-\frac{1}{\alpha} \log \left(p_{0}+1\right)-\frac{2}{3}\right)\right)
\end{aligned}
$$

This, together with the fact that $I_{1} \leq 1, \log p_{0}+\alpha \log \left(p-p_{0}+1\right) \leq(\alpha+1)(\log (p+1)-$ $\left.\log (\alpha+1)+\frac{\alpha}{\alpha+1} \log \alpha\right)$ and $\frac{1}{\alpha} \log \left(p_{0}+1\right)+\log \left(p-p_{0}\right) \leq\left(1+\frac{1}{\alpha}\right)\left(\log (p+1)-\frac{1}{\alpha+1} \log (\alpha+\right.$ $\left.1)-\frac{\alpha}{\alpha+1} \log \left(1+\frac{1}{\alpha}\right)\right)$, leads to (15). The risk and minimaxity results follows similarly as in the proof of Theorem 5. This completes the proof.
Proof of Theorem 6: Let $H=\left\{\min _{j \in A_{0}}\left|\hat{\beta}_{j}^{o l}\right|>3 \tau / 2\right\} \cap\left\{\max _{j \notin A_{0}}\left|\left(\boldsymbol{x}^{(j)}\right)^{T}\left(\boldsymbol{Y}-\boldsymbol{X} \hat{\boldsymbol{\beta}}^{o l}\right)\right| \leq\right.$ $\left.\frac{\lambda}{\tau}\right\}$. Rewrite (23), for any subset $A$ of non-zero coefficients and $\boldsymbol{\beta}$,

$$
\begin{cases}-\left(\boldsymbol{x}^{(j)}\right)^{T}(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{\beta})+\frac{\lambda}{\tau} \operatorname{sign}\left(\beta_{j}\right) I\left(\left|\beta_{j}\right|<\tau\right)=0, & j \in A,  \tag{29}\\ \left|\left(\boldsymbol{x}^{(j)}\right)^{T}(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{\beta})\right| \leq \frac{\lambda}{\tau}, & j \notin A .\end{cases}
$$

Next we prove that $\hat{\boldsymbol{\beta}}^{o l}$ satisfies (29) on $H$. Note that the first event in $H$ implies that $\nabla_{j} S_{2}\left(\hat{\boldsymbol{\beta}}^{o l}\right)-\frac{\lambda}{\tau} \operatorname{sign}\left(\hat{\beta}_{j}^{o l}\right)=0 ; j=1, \cdots, p_{0}$. This, together with the property that $\left(\boldsymbol{x}^{(j)}\right)^{T}\left(\boldsymbol{Y}-\boldsymbol{X} \hat{\boldsymbol{\beta}}^{o l}\right)=0 ; j=1, \cdots, p_{0}$ yields the first equation of (29). The second event in $H$ implies the second equation of (29) by $\hat{\boldsymbol{\beta}}^{o l}$.

For a unique minimum of (29) on $H$, suppose $\hat{\boldsymbol{\beta}}_{\hat{A}}^{l o} \neq \hat{\boldsymbol{\beta}}_{A_{0}}^{o l}$. Let $A *=\hat{A} \cup A_{0}$. Define $g\left(\boldsymbol{\beta}_{A *}\right)=S(\boldsymbol{\beta})$, where $\boldsymbol{\beta}=\left(\boldsymbol{\beta}_{A *}, \mathbf{0}_{A *^{c}}\right)$ and $\boldsymbol{\beta}_{A *}=\left(\beta_{1}, \ldots, \beta_{|A *|}\right)^{T}$. Then

$$
\begin{aligned}
& \left|\left(\frac{\partial}{\partial \boldsymbol{\beta}_{A *}} g\left(\hat{\boldsymbol{\beta}}_{A *}^{l o}\right)-\frac{\partial}{\partial \boldsymbol{\beta}_{A *}} g\left(\hat{\boldsymbol{\beta}}_{A *}^{o l}\right)\right)^{T} \frac{\left(\hat{\boldsymbol{\beta}}_{A *}^{l o}-\hat{\boldsymbol{\beta}}_{A *}^{o l}\right)}{\left\|\hat{\boldsymbol{\beta}}_{A *}^{l o}-\hat{\boldsymbol{\beta}}_{A *}^{o l}\right\|}\right|=\mid\left(X_{A *}^{T} X_{A *}\left(\hat{\boldsymbol{\beta}}_{A *}^{l o}-\hat{\boldsymbol{\beta}}_{A *}^{o l}\right)\right. \\
& \left.+\frac{\lambda}{\tau} \operatorname{sign}\left(\hat{\boldsymbol{\beta}}_{A *}^{l o}\right) I\left(\left|\hat{\boldsymbol{\beta}}_{A *}^{l o}\right| \leq \tau\right)-\frac{\lambda}{\tau} \operatorname{sign}\left(\hat{\boldsymbol{\beta}}_{A *}^{o l}\right) I\left(\left|\hat{\boldsymbol{\beta}}_{A *}^{o l}\right| \leq \tau\right)\right) \left.^{T} \frac{\left(\hat{\boldsymbol{\beta}}_{A *}^{l o}-\hat{\boldsymbol{\beta}}_{A *}^{o l}\right)}{\left\|\hat{\boldsymbol{\beta}}_{A *}^{l o}-\hat{\boldsymbol{\beta}}_{A *}^{o l}\right\|} \right\rvert\,,
\end{aligned}
$$

where $\hat{\boldsymbol{\beta}}_{A *}^{o l}$ and $\hat{\boldsymbol{\beta}}_{A *}^{l o}$ can not attain at non-differentiable concave points of the penalty by Lemma 1. Without loss of generality, assume that $\left\|\hat{\boldsymbol{\beta}}_{A *}^{l o}-\hat{\boldsymbol{\beta}}_{A *}^{o l}\right\| \geq \tau / 2$. Otherwise, for any
$j \in A_{0}\left|\hat{\beta}_{j}^{l o}\right|>\tau$, and for $j \in A_{0}^{c} \cap A *\left|\hat{\beta}_{j}^{l o}\right| \leq \tau$, implying $\hat{\boldsymbol{\beta}}_{A *}^{l o}=\hat{\boldsymbol{\beta}}_{A *}^{o l}$ on $H$, as shown from (28), which is impossible by assumption that $\hat{\boldsymbol{\beta}}_{A *}^{l o} \neq \hat{\boldsymbol{\beta}}_{A *}^{o l}$. By the Cauchy-Schwarz inequality $\left|\left(\frac{\lambda}{\tau} \operatorname{sign}\left(\hat{\boldsymbol{\beta}}_{A *}^{l o}\right) I\left(\left|\hat{\boldsymbol{\beta}}_{A *}^{l o}\right| \leq \tau\right)-\frac{\lambda}{\tau} \operatorname{sign}\left(\hat{\boldsymbol{\beta}}_{A *}^{o l}\right) I\left(\left|\hat{\boldsymbol{\beta}}_{A *}^{o l}\right| \leq \tau\right)\right)^{T}\left(\hat{\boldsymbol{\beta}}_{A *}^{l o}-\hat{\boldsymbol{\beta}}_{A *}^{o l}\right)\right| \leq \frac{2 \lambda}{\tau} \sqrt{K^{*}}\left\|\hat{\boldsymbol{\beta}}_{A *}^{l o}-\hat{\boldsymbol{\beta}}_{A *}^{o l}\right\|$ that is bounded below by $\min _{|B| \leq 2 K^{*}, A_{0} \subseteq B} n c_{\min }\left(n^{-1} \boldsymbol{X}_{B}^{T} \boldsymbol{X}_{B}\right) \frac{\tau}{2}-\frac{2 \lambda}{\tau} \sqrt{K^{*}}>0$, contradicting to the fact that $\mathbf{0} \in\left(\frac{\partial}{\partial \boldsymbol{\beta}_{A *}} g\left(\hat{\boldsymbol{\beta}}_{A *}^{l o}\right)-\frac{\partial}{\partial \boldsymbol{\beta}_{A *}^{l o}} g\left(\hat{\boldsymbol{\beta}}_{A *}^{o l}\right)\right)^{T} \frac{\left(\hat{\boldsymbol{\beta}}_{\boldsymbol{A}}^{l o}-\hat{\boldsymbol{\beta}}_{A *}^{o l}\right)}{\left\|\hat{\boldsymbol{\beta}}_{A *}^{o}-\hat{\boldsymbol{\beta}}_{A *}^{o l}\right\|}$ on $H$ if $\hat{\boldsymbol{\beta}}^{l o} \neq \hat{\boldsymbol{\beta}}^{o l}$ is a local minimizer of $S(\cdot)$ thus $g(\cdot)$. Hence $g\left(\boldsymbol{\beta}_{A *}^{l o}\right)$ has a unique local minimizer on $H$, implying $\hat{\boldsymbol{\beta}}^{o l}=\hat{\boldsymbol{\beta}}^{l o}$.

Note that $\left(\boldsymbol{x}^{(j)}\right)^{T}\left(\boldsymbol{Y}-\boldsymbol{X}^{T} \hat{\boldsymbol{\beta}}^{o l}\right) \sim N\left(0, \sigma^{2}\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{x}^{(j)}\right\|^{2}\right),\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{A_{0}}\right) \boldsymbol{x}^{(j)}\right\|^{2} \leq\left\|\boldsymbol{x}^{(j)}\right\|^{2}$, $\hat{\beta}_{j}^{o l} \sim N\left(\beta_{j}^{0}, \operatorname{Var}\left(\hat{\beta}_{j}^{o l}\right)\right)$, and $\operatorname{Var}\left(\hat{\beta}_{j}^{o l}\right) \geq c_{\min }^{-1}\left(n^{-1} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right) \sigma^{2} / n$. Then $P\left(\hat{\boldsymbol{\beta}}_{\hat{A}^{l o}}^{l o} \neq \hat{\boldsymbol{\beta}}_{A_{0}}^{o l}\right) \leq$ $P\left(H^{c}\right) \leq \sum_{j \in A_{0}} P\left(\left|\hat{\beta}_{j}^{o l}\right| \leq 3 \tau / 2\right)+\sum_{j \notin A_{0}} P\left(\left|\left(\boldsymbol{x}^{(j)}\right)^{T}\left(\boldsymbol{Y}-\boldsymbol{X}^{T} \hat{\boldsymbol{\beta}}^{o l}\right)\right|>\frac{\lambda}{\tau}\right) \equiv I_{6}+I_{7}$, where $I_{6} \leq\left|A_{0}\right|\left(\Phi\left(-\frac{n^{1 / 2}\left(\gamma_{\min }-3 \tau / 2\right)}{\sigma c_{\min }^{-1 / 2}\left(\frac{1}{n} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right)}\right)-\Phi\left(-\frac{n^{1 / 2}\left(\gamma_{\min }+3 \tau / 2\right)}{\sigma c_{\min }^{-1 / 2}\left(\frac{1}{n} \boldsymbol{X}_{A_{0}}^{T} \boldsymbol{X}_{A_{0}}\right)}\right)\right)$, and $I_{7} \leq\left(p-\left|A_{0}\right|\right) \Phi(-$ $\left.\frac{\lambda / \tau}{\sigma \max _{1 \leq j \leq p}\left\|\boldsymbol{x}^{(j)}\right\|}\right)$. This yields (24).

For the risk property, let $\hat{A}=\left\{j:\left|\hat{\beta}_{j}^{l o}\right| \geq \tau\right\}$. By (29), $\hat{\boldsymbol{\beta}}_{\hat{A}}^{l o}=\left(\boldsymbol{X}_{\hat{A}}^{T} \boldsymbol{X}_{\hat{A}}\right)^{-1} \boldsymbol{X}_{\hat{A}}^{T}(\boldsymbol{Y}-$ $\left.\boldsymbol{X}_{\hat{A}^{c}} \hat{\boldsymbol{\beta}}_{\hat{A}^{c}}\right)$. As in the proof of Theorem 5 for the global minimizer, we rewrite the risk as the sum of $T_{1}$ and $T_{2}$. For $T_{1}=\int_{C}^{\infty} P\left(\frac{1}{n}\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{l o}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2} \geq x\right) d x$, by the triangular inequality, $\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{l o}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}=\left\|\left(\boldsymbol{I}-\boldsymbol{P}_{\hat{A}}\right)\left(\boldsymbol{X}_{\hat{A}^{c}} \hat{\boldsymbol{\beta}}_{\hat{A}^{c}}^{l o}+\boldsymbol{X} \boldsymbol{\beta}^{0}\right)+\boldsymbol{P}_{\hat{A}} \boldsymbol{\epsilon}\right\|^{2} \leq 4\left(c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right) p^{2} \tau^{2}+\left\|\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}\right)+$ $2\|\boldsymbol{\epsilon}\|^{2}$. Let $C=7 \sigma^{2}+2 c_{\max }\left(\frac{\boldsymbol{X}^{T} \boldsymbol{X}}{n}\right) p^{2} \tau^{2}+\frac{4}{n}\left\|\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}$ and $t=1 / 3$. By Markov's inequality,

$$
\begin{aligned}
T_{1} & \leq \int_{C}^{\infty} P\left(\|\boldsymbol{\epsilon}\|^{2} \geq \frac{x n}{2}-2 c_{\max }\left(\boldsymbol{X}^{T} \boldsymbol{X}\right) p^{2} \tau^{2}-2\left\|\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}\right) d x \\
& \leq \int_{C}^{\infty} E\left(\exp \left(t\|\boldsymbol{\epsilon}\|^{2} / \sigma^{2}\right)\right) \exp \left(-n t \frac{x-2 c_{\max }\left(\frac{\boldsymbol{X}^{T} \boldsymbol{X}}{n}\right) p^{2} \tau^{2}-\frac{4}{n}\left\|\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}}{2 \sigma^{2}}\right) d x \\
& \leq \int_{C}^{\infty} \exp \left(-n t \frac{x-6 \sigma^{2}-2 c_{\max }\left(\frac{\boldsymbol{X}^{T} \boldsymbol{X}}{n}\right) p^{2} \tau^{2}-\frac{4}{n}\left\|\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}}{2 \sigma^{2}}\right) d x=o\left(\frac{p_{0}}{n} \sigma^{2}\right)
\end{aligned}
$$

For $T_{2}$, by the probability error bound, $T_{2} \leq C P\left(\hat{\boldsymbol{\beta}}^{l o} \neq \hat{\boldsymbol{\beta}}^{o l}\right)+\frac{1}{n} E\left\|\boldsymbol{X} \hat{\boldsymbol{\beta}}^{o l}-\boldsymbol{X} \boldsymbol{\beta}^{0}\right\|^{2}=$ $(1+o(1)) \frac{p_{0}}{n} \sigma^{2}$, leading to the desired result.

Finally, it remains to show that $\hat{\boldsymbol{\beta}}^{l o}$ satisfies (23). Note that the local optimality (21) is satisfied by $\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}^{(m)}:-\left(\boldsymbol{x}^{(j)}\right)^{T}(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{\beta})+\frac{\lambda}{\tau} \operatorname{sign}\left(\beta_{j}\right) I\left(\left|\boldsymbol{\beta}^{(m-1)}\right|<\tau\right)=0 j=1, \cdots, p$. By construction, $\hat{\beta}_{j}^{(m)}=\hat{\beta}_{j}^{\left(m^{*}-1\right)} \neq \pm \tau$; for $m \geq m^{*}$ and $j=1, \cdots, p$, implying (23). This completes the proof.

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