Does Modeling Lead to More Accurate Classification?: A Study of Relative Efficiency in Linear Classification

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Abstract

Classification arises in a wide range of applications. A variety of statistical tools have been developed for learning classification rules from data. Understanding of their relative merits and comparisons help users to choose a proper method in practice. This paper focuses on theoretical comparison of model-based classification methods in statistics with algorithmic methods in machine learning in terms of the error rate. Extending Efron’s comparison of logistic regression with the LDA under the normal setting, we contrast such algorithmic methods as the support vector machine and boosting with the LDA and logistic regression and study their relative efficiencies in reducing the error rate based on the limiting behavior of the classification boundary of each method. In addition to the theoretical study, we present results from numerical experiments under various settings for comparisons of finite-sample performance and robustness to mislabeling and model misspecification.

Key words: Boosting; Classification; Efficiency; Error Rate; LDA; Logistic Regression; Mislabeled; Robustness; SVM

1 Introduction

Classification arises in applications from diverse domains, for example, speech recognition, spam filtering, fraud detection, and medical diagnosis. A variety of statistical tools have been developed for learning a classification (or discrimination) rule with low error rates over novel cases. To name a few, Fisher’s linear discriminant analysis (LDA) and quadratic discriminant analysis (QDA) are classical examples of a discriminant rule in the statistics literature, and modern statistical tools include classification trees, logistic regression, neural networks, and kernel density based methods. For reference to classification in general, see Hastie et al. (2001); Duda et al. (2000); McLachlan (2004) and Devroye et al. (1996). More recent additions to the data analyst’s toolbox for classification are the support vector machine (SVM) (Vapnik 1998; Cristianini and Shawe-Taylor 2000; Schölkopf and Smola 2002),
boosting (Freund and Schapire 1997), and other margin-based methods generally dubbed large-margin classifiers. They have drawn considerable attention in machine learning for the last decade or so, and been successfully used in many applications of data mining, engineering, and bioinformatics; for instance, hand-written digit recognition, text categorization, and cancer diagnosis with genomic biomarkers.

Traditionally, in statistics, modeling approach to classification has been prevalent, where the underlying probability model that generates data is estimated first, and then a discrimination rule is derived from the estimated model. Logistic regression, LDA, QDA and other density based methods exemplify the approach. In contrast, in machine learning, algorithmic approach is more common, where one aims at direct minimization of the error rate without estimating a probability model explicitly by employing a convex surrogate criterion of the misclassification count (0-1). The latter yields non-probability model based methods such as SVM, boosting and other large margin classifiers.

In modern data analysis where typically high dimensional attributes are involved, refined statistical modeling may not be as tractable as in the classical setting. Also, in parallel, computational efficiency has become an ever more important factor in the applicability of a method. The contrast between the model-based methods and algorithmic methods has brought many interesting theoretical questions. For instance, the discrepancy of the 0-1 loss from the surrogate loss that is actually used for training a classifier in the latter approach has generated an array of theoretical questions regarding the Bayes risk consistency of the resulting rules under convex surrogate loss functions. Zhang (2004); Bartlett et al. (2006); Lin (2002) and Steinwart (2005) delve into the issues and provide proper conditions for the surrogate loss to ensure the risk consistency. It is shown that only minimal conditions are necessary in the binary classification problem. In particular, the hinge loss for SVM and the exponential loss for boosting are properly calibrated for the Bayes risk consistency. These results suggest that at least in terms of risk consistency, there is no difference between the two approaches theoretically. They also confirm the common belief in machine learning that formal modeling may not be necessary as less is required in pattern recognition.

As a practical question, whether the ‘soft’ classification approach in statistics is more appropriate than the ‘hard’ classification approach in machine learning depends largely on the context of applications. Certainly, in some applications, accurate estimation of the class conditional probability given the attributes is required for making better decisions than just prediction of a likely outcome.

However, as a theoretical question, comparison of the two approaches remains open to investigation. To the best of our knowledge, their relative merits and efficiency have not been rigorously examined on the theoretical basis. Given the differences in the two paradigms of modeling versus prediction, a basic question we pose here is whether probability modeling leads to more efficient use of data in reducing the classification error rate than the algorithmic approach, and if so, how much efficiency is gained by modeling.

To simplify the question, we examine the effect of modeling on the error rate analytically in the normal distribution setting by computing the asymptotic relative efficiency (ARE) of various classification methods ranging from the full modeling approach of the LDA to the purely algorithmic procedure of the SVM in reducing the classification error rate. Drawing on Efron’s classical framework for comparison of the LDA with logistic regression (Efron 1975), we present similar analysis and large-sample comparison for some of popular machine
learning methods. In doing so, we use the asymptotic theory of M-estimators to characterize
the limiting distribution of a discriminant function and the associated error rate for methods
that are defined through convex loss criteria.

Under the normal setting, it is shown that the SVM is two fifths to two thirds as effective
as the LDA when the mean separation between two classes is substantially large with the
Bayes error rate of 4% to 10%. Boosting is shown to be one fifth to one half as effective
as the LDA in the same situation. Generally, the relative efficiency of algorithmic approach
to modeling increases in the direction of growing overlap between classes and diminishes
quickly as the two classes become sufficiently apart. However, we find that certain convex
loss criteria work favorably for the normal setting. For instance, a smooth variant of the
SVM with squared hinge loss is shown to be even more efficient than logistic regression.

To broaden the scope of the comparison, we also examine the first-order difference be-
tween the Bayes risk and the limiting minimal error of the classifiers un-
der consideration, when the underlying model (or the class of discriminant functions) is incorrectly specified
and thus the Bayes risk consistency is not guaranteed. In addition, we carry out a simula-
tion study under the settings not covered by the theoretical analysis to touch on the issue
of robustness to mislabeling error in the data.

The remainder of this paper is organized as follows. Section 2 describes the theoretical
framework for comparisons of classification methods. Section 3 states general result about
the limiting distribution of discriminant coefficients as M-estimators under some regularity
conditions and its applications for various classification methods. As the main result, the
ARE comparisons based on the limiting distributions are presented in Section 4 along with
finite-sample comparisons of excess error rates. Section 5 provides further comparisons of the
methods in terms of robustness to model-misspecification or data contamination. Concluding
remarks are in Section 6.

2 Background and Framework for Comparison

Consider a classification problem where multivariate attributes are measured for each subject
and for a number of subjects, their class memberships are observed. Let $X = (X_1, \ldots, X_p) \in \mathcal{X} = \mathbb{R}^p$ denote the attributes or predictors and $Y$ be the class label which takes one of, say, $k$ nominal values, $\mathcal{Y} = \{1, \ldots, k\}$. Training data consist of a set of $n$ observation pairs, $\mathcal{D}_n = \{(x_i, y_i), i = 1, \ldots, n\}$, where $(x_i, y_i)$’s are viewed as independent and identically distributed random outcomes of $(X, Y)$ from some unknown distribution $P_{X,Y}$. Given the training data, we want to find a classification rule, $\phi : \mathcal{X} \to \mathcal{Y}$, which can be generalized to
future cases from the same distribution $P_{X,Y}$ with a small error rate. Typically, the error of
the rule $\phi$ over an individual case $(x, y)$ is measured by the 0-1 loss $\rho(y, \phi(x)) = I(y \neq \phi(x))$, and its overall error rate is given by the probability of error $R(\phi) = P(Y \neq \phi(X))$. Then the theoretically optimal rule with the minimum error rate, which is also known as the Bayes
decision rule $\phi_B$, can be characterized as $\phi_B(x) = \text{arg max}_{j \in \mathcal{Y}} P(Y = j \mid X = x)$.

For simplicity, we focus on classification with binary outcomes only ($k = 2$) in this paper
and use symmetric class labels $\mathcal{Y} = \{-1, 1\}$ whenever convenient. With the symmetric
labels, the optimal rule is expressed succinctly as $\phi_B(x) = \text{sgn}(p(x) - 1/2)$, where $p(x) = P(Y = 1 \mid X = x)$. Many classification procedures in consideration can be viewed as a
way of obtaining a real-valued discriminant function $f : \mathbb{R}^p \rightarrow \mathbb{R}$, which induces a rule $\phi_f(x) = \text{sgn}(f(x))$, by minimizing the risk under a convex surrogate loss of the 0-1 loss. Generally, a class of functions $\mathcal{F}$ is specified a priori for the discriminant function $f$, for example, a linear space spanned by a set of basis functions or a reproducing kernel Hilbert space with a kernel function $K$. As we mainly consider the setting where $\phi_B$ is linear in $x$, we will restrict $\mathcal{F}$ to linear discriminant functions only in this paper.

2.1 Normal Distribution Setting

Suppose that the attributes $X$ arise from one of two $p$-dimensional normal populations with different means but the same covariance:

$$X \sim N_p(\mu_+, \Sigma) \text{ with probability } \pi_+ \text{ and } X \sim N_p(\mu_-, \Sigma) \text{ with probability } \pi_-,$$

(1)

where $\pi_+ = P(Y = 1)$, $\pi_- = P(Y = -1)$, and $\pi_+ + \pi_- = 1$. Fisher’s linear discriminant analysis (LDA) is a standard example of linear classifiers in statistics, which is proven to be optimal in minimizing the misclassification rate under the normality and equal covariance assumptions. The optimal classification boundary is determined by Fisher’s linear discriminant function $f^*(x) = \beta_0^* + \beta^* x$, where $\beta_0^* = \log(\pi_+/\pi_-) - (1/2)(\mu_+ - \mu_-)\Sigma^{-1}(\mu_+ - \mu_-)$ and $\beta^* = (\beta_1, \ldots, \beta_p)' = \Sigma^{-1}(\mu_+ - \mu_-)$.

Since this general LDA setting can be transformed to the canonical setting by means of a linear transformation, without loss of generality we will assume the following canonical LDA setting:

$$X \mid Y = 1 \sim N_p \left( \frac{\Delta}{2} e_1, I \right) \quad \text{and} \quad X \mid Y = -1 \sim N_p \left( -\frac{\Delta}{2} e_1, I \right),$$

(2)

where $e_1 = (1, 0, \ldots, 0)'$, $I$ is the $p \times p$ identity matrix, and $\Delta = \{(\mu_+ - \mu_-)\Sigma^{-1}(\mu_+ - \mu_-)\}^{1/2}$ (known as the Mahalanobis distance between the two normal distributions). For the canonical setting, Fisher’s linear discriminant coefficients are simplified to $\beta_0^* = \log(\pi_+/\pi_-)$ and $\beta^* = \Delta e_1$. The Bayes decision rule induced by $f^*$ is then $\phi_B(x) = \text{sgn}(f^*(x))$, and its error rate is $\Phi(-\Delta/2)$, where $\Phi$ is the standard normal cdf.

2.2 Classification Methods

To make comparison of classification methods simple, we restrict the space of discriminant functions to linear functions of $x$ only. Now consider deriving a linear discriminant rule based on the training data. A host of classification methods can be applied to derive a linear discriminant rule.

If we model the data fully under the true LDA setting, we get the plug-in LDA discriminant function $\hat{f}_{LDA}$ with estimated means $\mu_+$ and $\mu_-$ and covariance $\Sigma$. As an intermediate method sitting half-way between the full modeling approach of the LDA and purely algorithmic approach, logistic regression models the conditional distribution of $Y$ given $x$ with
the distribution of $\mathbf{x}$ unspecified. Also, it can be viewed as an $M$-estimator with deviance loss. The discriminant function of logistic regression $\hat{f}_{LR}$ is an estimate of the logit function,

$$f(\mathbf{x}) = \log(P(Y = 1|\mathbf{X} = \mathbf{x})/P(Y = -1|\mathbf{X} = \mathbf{x})) = \beta_0 + \beta'\mathbf{x},$$

which is determined by maximizing the conditional log likelihood or minimizing the negative log likelihood of $(\beta_0, \beta')' \in \mathbb{R}^{p+1}$:

$$L_n(\beta_0, \beta) = \sum_{i=1}^{n} \log (1 + \exp(-y_i(\beta_0 + \beta'\mathbf{x}_i))).$$

(3)

In contrast to the LDA and logistic regression, discriminant functions for algorithmic methods are obtained directly through consideration of the classification boundary itself, not the probability model underlying the data. For example, the linear support vector machine finds the optimal hyperplane $\beta_0 + \beta'\mathbf{x} = 0$ with a large margin between two classes by minimizing

$$\frac{1}{n} \sum_{i=1}^{n} (1 - y_i(\beta_0 + \beta'\mathbf{x}_i))_+ + \frac{\lambda}{2} \|\beta\|^2,$$

(4)

where $\lambda$ is a positive tuning parameter that controls the trade-off between the empirical risk under the hinge loss (the first term) and the inverse of the margin as a penalty (the second term). It attempts to minimize the error rate directly by using a convex surrogate loss of the misclassification count. The optimal hyperplane $\hat{\beta}_0 + \hat{\beta}'\mathbf{x} = 0$ found as a solution to (4) then yields the discriminant function for the SVM, $\hat{f}_{SVM}(\mathbf{x}) = \hat{\beta}_0 + \hat{\beta}'\mathbf{x}$. There are other variants of the SVM for large-margin classification as well. For instance, the smooth SVM (Lee and Mangasarian 2001) uses squared hinge loss as a loss criterion.

As another convex risk minimization method in machine learning, boosting (Freund and Schapire 1997) finds a discriminant function by sequentially updating the current fitted function to a weighted version of data to minimize

$$L_n(\beta_0, \beta) = \sum_{i=1}^{n} \exp(-y_i(\beta_0 + \beta'\mathbf{x}_i))$$

(5)

and combining the sequence of fitted functions. Although the discriminant function from boosting in general is taken as a weighted sum of weak learners obtained stagewise, we take the simple view of boosting as an $M$-estimator minimizing (5) in this paper, borrowing the perspective on boosting in Friedman et al. (2000).

Consequently, the loss criterion employed to determine the discriminant function characterizes the difference among logistic regression, the SVM, and boosting in terms of their statistical behavior and classification accuracy. Each of the three methods can be described as an $M$-estimator under the loss of binomial deviance $l(s) = \log(1+\exp(-s))$, hinge $(1-s)_+$, and exponential $\exp(-s)$, respectively, where $s \equiv yf(\mathbf{x})$ for $f(\mathbf{x}) = \beta_0 + \beta'\mathbf{x}$.

The main focus of this paper is to theoretically examine the effect of bypassing probability modeling of data on the error rate. We investigate the issue by comparing the LDA, logistic regression, the SVM, and boosting, which represent a wide spectrum of classification procedures spanning from full model-based to algorithmic approaches.
2.3 Error Rates and Relative Efficiency

For a discriminant function \( \hat{f} \) from training data, let \( R(\hat{f}) \equiv R(\phi_{\hat{f}}) \) be the error rate of the associated discriminant rule, \( \phi_{\hat{f}}(x) = \text{sgn}(\hat{f}(x)) \). That is, for \((X, Y)\) independent of the data used to determine \( \hat{f} \), \( R(\hat{f}) \equiv P(Y \neq \text{sgn}(\hat{f}(X))) = P(Y \hat{f}(X) < 0) \). Note that \( R(\hat{f}) \) is a random variable due to the fact that \( \hat{f} \) depends on the training data. \( R(\hat{f}) - R(\phi_B) \) represents the excess error rate of \( \hat{f} \) compared to the Bayes decision rule \( \phi_B \) with the minimum error rate.

Efron (1975) compared logistic regression to the LDA in terms of the excess error rate by examining the asymptotic relative efficiency (ARE) of logistic regression (LR) to normal discrimination (LDA), which is defined as

\[
\lim_{n \to \infty} \frac{E(R(\hat{f}_{LDA}) - R(\phi_B))}{E(R(\hat{f}_{LR}) - R(\phi_B))}.
\]

In his analysis, logistic regression is shown to be between one half and two thirds as effective as normal discrimination typically. The key fact in the analysis is that for a linear discriminant method \( \hat{f}(x) = \hat{\beta}_0 + \hat{\beta}'x \), if \( \sqrt{n}(\hat{\beta} - \beta^*) \overset{d}{\to} N_{p+1}(0, \Sigma_{\beta}) \) under the canonical setting, the expected excess error rate, \( E(R(\hat{f}) - R(\phi_B)) \) is given by

\[
\frac{\pi_+ \phi(D_1)}{2 \Delta n} \left[ \sigma_{00} - \frac{2\beta_0^*}{\Delta} \sigma_{01} + \frac{(\beta_0^*)^2}{\Delta^2} \sigma_{11} + \sigma_{22} + \cdots + \sigma_{pp} \right] + o\left(\frac{1}{n}\right),
\]

where \( \hat{\beta} = (\hat{\beta}_0, \hat{\beta}')', \beta^* = (\beta_0^*, \beta'^*), D_1 = \Delta/2 + (1/\Delta) \log(\pi_+/\pi_-) \), \( \phi \) is the pdf of standard normal distribution, and \( \sigma_{ij} \) is the \( ij \)-th entry of \( \Sigma_{\beta} \) \((i, j = 0, \ldots, p)\). In other words, (6) shows that the mean increased error rate of \( \hat{f} \) relative to \( \phi_B \) can be expressed in terms of the variance of \( \hat{\beta} \) in the limiting distribution. It indicates how the accuracy of the estimator \( \hat{\beta} \) of \( \beta^* \) affects the excess error rate of the discriminant rule with \( \hat{\beta} \) as its coefficients. When two procedures are consistent in getting the Bayes decision rule, their asymptotic relative efficiency can be measured by the rate at which the expected excess error goes to zero as the sample size \( n \) grows. With the same parametric rate of \( 1/n \) in (6), we see that the efficiency of a procedure is determined by its leading coefficient of \( 1/n \) in the expression of the excess error. Borrowing Efron’s theoretical framework, we extend the analysis to include those prediction-oriented modern classification tools.

3 Asymptotic Distribution of Discriminant Coefficients

To compare the relative efficiency of different ways to determine a linear discrimination rule, we need to identify the asymptotic distribution of the coefficient vector for each method first. For the LDA and logistic regression, Efron used large sample theory of the maximum likelihood estimators in exponential family distributions. Under the canonical setting, it was
shown that the limit distribution of \( \sqrt{n}(\hat{\beta} - \beta^*) \) for the LDA is \( N_{p+1}(0, \Sigma_{\beta}) \) with

\[
\Sigma_{\beta} = \frac{1}{\pi_+ \pi_-} \begin{pmatrix}
1 + \Delta^2 & \Delta^2 (\pi_+ - \pi_-) & 0 & \cdots & 0 \\
\frac{\Delta^2}{2} (\pi_+ - \pi_-) & 1 + 2\Delta^2 \pi_+ \pi_- & 0 & \cdots & 0 \\
0 & 0 & 1 + \Delta^2 \pi_+ \pi_- & \cdots & \cdots \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
0 & 0 & 0 & \cdots & 1 + \Delta^2 \pi_+ \pi_- 
\end{pmatrix}.
\]

Since the coefficient vectors for logistic regression, the SVM and its variants, and boosting are defined as a minimizer of a convex loss criterion, asymptotic theories for M-estimators in van der Vaart (2000) and Hjort and Pollard (1993), for example, can be used to identify their limiting distributions. See also Pollard (1991), Geyer (1994), Knight and Fu (2000) and Rocha et al. (2009).

For general description of the asymptotics of M-estimators, let \( L_n(\beta_0, \beta) \equiv \sum_{i=1}^{n} \rho(y_i, x_i; \beta_0, \beta) \) for a convex loss \( \rho \) (with respect to \( \beta_0 \) and \( \beta \)). Using \( \hat{\beta} \) for short notation of \(( \hat{\beta}_0, \hat{\beta}'\)'), define \( \hat{\beta} \) as the minimizer of \( L_n(\beta_0, \beta) \). Let \( L(\beta) = E\rho(Y, X; \beta) \) be the true risk under \( \rho \), and \( \beta^* \) be the population risk minimizer, \( \text{arg min} \ L(\beta) \).

Under the following regularity conditions (adapted from Rocha et al. (2009)) that \( C1. \) \( \beta^* \) is bounded and unique,

\( C2. \) \( L(\beta) \) is bounded for each \( \beta \),

\( C3. \) \( \rho(y, x; \beta) \) is differentiable with respect to \( \beta \) at \( \beta = \beta^* \) for almost every \((x, y)\) in \( P_{X,Y} \) with derivative \( \frac{\partial \rho(y, x; \beta)}{\partial \beta} \) and \( G(\beta^*) \equiv E \left( \frac{\partial \rho(Y, X; \beta^*)}{\partial \beta} \right) \left( \frac{\partial \rho(Y, X; \beta^*)}{\partial \beta} \right)' \),

\( C4. \) \( L(\beta) \) is twice differentiable with respect to \( \beta \) at \( \beta = \beta^* \) with positive definite Hessian matrix

\[
H(\beta^*) \equiv \frac{\partial^2 L(\beta)}{\partial \beta \cdot \partial \beta'} \bigg|_{\beta = \beta^*},
\]

we can establish asymptotic normality of \( \hat{\beta} \) as an M-estimator and its consistency. The convexity of the loss \( \rho \) is a key condition in establishing the asymptotic normality of \( \hat{\beta} \). Although it can be replaced with any set of conditions yielding uniform convergence of the risk functions over compact sets, the convexity condition would suffice for our discussion.

**Theorem 1.** Under the regularity conditions \( C1-C4 \),

\[
\sqrt{n}(\hat{\beta} - \beta^*) \overset{d}{\rightarrow} N_{p+1}(0, H(\beta^*)^{-1}G(\beta^*)H(\beta^*)^{-1}).
\]

Note that the population minimizer \( \beta^* \) depends on \( \rho \), and under the canonical setting, \( \beta^* \) may have a different scale than the optimal coefficients in the theoretical LDA, depending on the method used. The difference is to be discussed shortly.
3.1 Support Vector Machine

Koo et al. (2008) examined the limiting distribution of the linear SVM in general setting. Technically, the analysis exploits a close link between the SVM and median regression yet with categorical responses, and applies the results on absolute deviation regression estimators in Pollard (1991) to the linear SVM. Due to the penalty in (4) and a slightly different set of regularity conditions considered, the result in Koo et al. (2008) is not a direct application of Theorem 1. However, in a nutshell, it shows that when the effect of the penalty gradually diminishes with \( \lambda = o(n^{-1/2}) \), the penalized coefficients of the linear SVM behave in the same way as what Theorem 1 would predict asymptotically. In particular, it was shown in the paper that under the LDA setting with equal proportions for the two classes, the classification boundary of the linear SVM coincides with that of the LDA in the limit, ensuring classification consistency.

To extend the result to general case of arbitrary class proportions of \( \pi_+ \) and \( \pi_- \), we first identify the optimal discriminant coefficients \( \beta^* \) under the hinge loss by minimizing the risk \( L(\beta) = E(1 - Y \cdot \beta' X) \) or equivalently finding the root of the equation \( S(\beta) = \frac{\partial}{\partial \beta} L(\beta) = 0 \).

Here we show the derivation of \( \beta^* \) for the SVM in detail for illustration and take similar steps for other methods. Under the LDA setting, the equation \( S(\beta) = 0 \) becomes

\[
\pi_+ \Phi(a_p) = \pi_- \Phi(a_m)
\]

and

\[
\pi_+ \phi(a_p) + \pi_- \phi(a_m) \Sigma^{\frac{1}{2}} \omega^* = \pi_+ \Phi(a_p) \mu_+ - \pi_- \Phi(a_m) \mu_-.
\]

where

\[
a_p = \frac{1 - \beta_0^* - \mu_0^* \beta^*}{\| \Sigma^{\frac{1}{2}} \beta^* \|}, \quad a_m = \frac{1 + \beta_0^* + \mu_0^* \beta^*}{\| \Sigma^{\frac{1}{2}} \beta^* \|}, \quad \text{and} \quad \omega^* = \frac{\Sigma^{\frac{1}{2}} \beta^*}{\| \Sigma^{\frac{1}{2}} \beta^* \|}.
\]

\( \phi(\cdot) \) and \( \Phi(\cdot) \) are the pdf and cdf of standard normal distribution, respectively.

Plugging (7) into (8) and solving for \( \omega^* \), we have

\[
\omega^* = \frac{\pi_- \Phi(a_m)}{\pi_+ \phi(a_p) + \pi_- \phi(a_m)} \Sigma^{-\frac{1}{2}} (\mu_+ - \mu_-).
\]

Since the norm of \( \omega^* \) must be 1, taking the norm of both sides of the above equation yields

\[
\frac{\pi_- \Phi(a_m)}{\pi_+ \phi(a_p) + \pi_- \phi(a_m)} \Delta = 1.
\]

Further simplifying the equation using (7), we arrive at the following relation for \( a_p \) and \( a_m \):

\[
\frac{\phi(a_p)}{\Phi(a_p)} + \frac{\phi(a_m)}{\Phi(a_m)} = \Delta.
\]

Then we can solve the equations (7) and (11) for \( a_p \) and \( a_m \) numerically. Once \( a_p \) and \( a_m \) are obtained, from the relation \( a_p + a_m = \{2 - (\mu_+ - \mu_-)^T \beta^* \}/\| \Sigma^{\frac{1}{2}} \beta^* \| \) and (10), we can get the optimal coefficients

\[
\beta^* = \frac{2}{|a_p + a_m + \Delta| \Delta} \Sigma^{-1} (\mu_+ - \mu_-).
\]
and the intercept
\[ \beta_0^* = \frac{a_m - a_p}{a_p + a_m + \Delta} - \frac{1}{2}(\mu_+ + \mu_-)'\beta^*. \] (13)

Clearly from (7), if \( \pi_+ = \pi_- \), then \( a_p = a_m \) (call it \( a^* \)), and \( a^* \) solves \( \phi(a^*)/\Phi(a^*) = \Delta/2 \). The values of \( a^* \) can be tabulated when \( \Delta \) varies. See Table 1 for some \( a^* \) values given a range of \( \Delta \). In the balanced case, the optimal parameters become

\[ \beta^* = \frac{2}{(2a^* + \Delta)} \Sigma^{-1}(\mu_+ - \mu_-), \quad \text{and} \quad \beta_0^* = -\frac{1}{2}(\mu_+ + \mu_-)'\beta^*. \]

Under the canonical LDA setting in particular, they are further simplified to

\[ \beta^* = \frac{2}{(2a^* + \Delta)}e_1, \quad \text{and} \quad \beta_0^* = 0. \]

Note that the optimal parameters for linear SVM have the scale factor of \( c_{\text{SVM}} \equiv 2/(2a^* \Delta + \Delta^2) \) when compared with the counterparts in Fisher’s linear discriminant function, that is, \( \frac{\beta^*_{\text{SVM}}}{\beta^*_{\text{LDA}}} = c_{\text{SVM}} \cdot \beta^*_{\text{LDA}} \).

From the results in Koo et al. (2008) with equal probabilities, we get

\[ H(\beta^*) = \frac{\phi(a^*)(2a^* + \Delta)}{2} \left( \begin{array}{cccc} 1 & 0 & \cdots & 0 \\ 0 & \frac{1}{4}(\Delta + 2a^*)^2 & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & & \cdots & 1 \end{array} \right) \]

and

\[ G(\beta^*) = \Phi(a^*) \left( \begin{array}{cccc} 1 & 0 & \cdots & 0 \\ 0 & -\frac{1}{4}(\Delta^2 + a^* \Delta - 4) & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & & \cdots & 1 \end{array} \right). \]

Hence the variance matrix in the limiting distribution of \( \hat{\beta} \) is given by

\[ H(\beta^*)^{-1}G(\beta^*)H(\beta^*)^{-1} = \frac{4}{\Phi(a^*)}c_{\text{SVM}}^2 \left( \begin{array}{cccc} 1 & 0 & \cdots & 0 \\ 0 & \frac{-4(\Delta^2 + a^* \Delta - 4)}{(\Delta + 2a^*)^4} & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & & \cdots & 1 \end{array} \right). \]

From the expression of the excess error in (6) and consideration of the scale factor \( c_{\text{SVM}} \), we can verify that the asymptotic relative efficiency of the linear SVM to LDA is given by

\[ \text{ARE}_{\text{SVM}} = \Phi(a^*)(1 + \frac{\Delta^2}{4}) = \frac{2\phi(a^*)}{\Delta}(1 + \frac{\Delta^2}{4}), \]
where \( a^* \) is the constant satisfying \( \phi(a^*)/\Phi(a^*) = \Delta/2 \). Some values of the relative efficiency corresponding to a range of class separation \( \Delta \) will be given later for more concrete comparisons.

It is important to observe that when \( \pi_+ \neq \pi_- \) in general, only the optimal coefficients \( \beta^* \) (without the intercept) of linear SVM in (12) are proportional to those of LDA, which results in inconsistency. Remedies for the inconsistency would require alternative ways to estimate the intercept given \( \beta \).

### 3.2 Variants of Support Vector Machine

There are variants of the SVM built around smooth versions of the hinge loss motivated mainly for computational ease. However, changes in the loss criterion lead to different asymptotic behavior of the resulting discriminant functions.

#### 3.2.1 Smooth SVM

Smooth SVM (Lee and Mangasarian 2001) refers to a variant of the SVM where the hinge loss criterion is replaced with its square version \( l(s) = [(1 - s)_+]^2 \). The discriminant coefficients \( \hat{\beta}_0 \) and \( \hat{\beta} \) are found by minimizing

\[
\frac{1}{n} \sum_{i=1}^{n} [(1 - y_i(\beta_0 + \beta'x_i))_+]^2 + \frac{\lambda}{2} \|\beta\|^2. \tag{14}
\]

In contrast to the hinge loss, the squared hinge loss is differentiable everywhere.

Following similar steps taken for the SVM, we can identify the optimal parameters \( \overline{\beta}^* \) under squared hinge loss as

\[
\beta^*_0 = \frac{a_m - a_p}{a_p + a_m + \Delta} - \frac{1}{2} (\mu_+ + \mu_-)'\overline{\beta}^* \quad \text{and} \quad \beta^* = \frac{2}{[a_p + a_m + \Delta] \Delta} \Sigma^{-1}(\mu_+ - \mu_-),
\]

where \( a_p \) and \( a_m \) are the constants that solve the following equations with \( \Theta(z) \equiv z\Phi(z) + \phi(z) \):

\[
\begin{align*}
\pi_+ \Theta(a_p) &= \pi_- \Theta(a_m) \tag{15} \\
\pi_+ \Theta(a_p) \Delta &= \pi_+ \Phi(a_p) + \pi_- \Phi(a_m). \tag{16}
\end{align*}
\]

As in the standard SVM, the optimal parameters for the smooth SVM are not proportional to those for the LDA in general if the probabilities of the two classes are not equal. If \( \pi_+ = \pi_- \), the equation (15) becomes \( \Theta(a_p) = \Theta(a_m) \). Since \( \Theta(z) = z\Phi(z) + \phi(z) \) is an increasing function of \( z \), we conclude \( a_p = a_m \). From the equation (16), the common value \( a^* \) is given as the constant that solves \( [a\Phi(a) + \phi(a)]\Delta = 2\Phi(a) \). The third column in Table 1 shows the values of \( a^* \) for the smooth SVM corresponding to the given values of \( \Delta \).

Under the canonical LDA setting with equal probabilities, the optimal parameters reduce to \( \beta^*_0 = 0 \) and \( \beta^* = \frac{2}{2a^* + \Delta} e_1 \). Thus \( \overline{\beta}^*_{SSVM} = c_{SSVM} \cdot \overline{\beta}^*_{LDA} \) with \( c_{SSVM} \equiv 2/(2a^*\Delta + \Delta^2) \).

When \( \lambda = o(n^{-1/2}) \), the smooth SVM in (14) provides a consistent estimator of \( c_{SSVM} \cdot \overline{\beta}^*_{LDA} \).
Further with the Hessian matrix \( H(\beta^*) \) and \( G(\beta^*) \) for squared hinge loss, we can find the limiting covariance matrix and verify that the ARE of the smooth SVM to LDA is given by

\[
\text{ARE}_{SSVM} = \frac{4\Phi(a^*)(1 + \Delta^2/4)}{\Delta(2a^* + \Delta)} = 2c_{SSVM}\Phi(a^*)(1 + \Delta^2/4).
\]

Details of the derivation of \( \beta^* \) and the asymptotic distribution of discriminant coefficients for the smooth SVM are given in Appendix.

3.2.2 Huberized SVM

The Huberized SVM (Rosset and Zhu 2007) is another variant of the SVM inspired by Huber’s loss for robust regression. It retains the robustness of the SVM for large margin classification yet with differentiability in the loss. It replaces the hinge loss in (4) with

\[
\rho_k(y, x; \beta_0, \beta) = \begin{cases} 
2(k-1)y(\beta_0 + \beta'x) + (1 - k^2) & \text{if } y(\beta_0 + \beta'x) < k, \\
[1 - y(\beta_0 + \beta'x)]^2 & \text{if } k \leq y(\beta_0 + \beta'x) < 1, \\
0 & \text{if } y(\beta_0 + \beta'x) \geq 1,
\end{cases}
\]

where \( k < 1 \) and as a bending constant, it demarcates the quadratic part of the loss. When \( k \) tends to \(-\infty\), \( \rho_k \) approaches the squared hinge loss in the smooth SVM.

The expressions of the optimal parameters under Huberized hinge loss are shown to be the same as those of the smooth SVM:

\[
\beta_0^* = \frac{a_m - a_p}{a_p + a_m + \Delta} - \frac{1}{2}(\mu_+ + \mu_-)'\beta^* \quad \text{and} \quad \beta^* = \frac{2}{[a_p + a_m + \Delta]\Sigma^{-1}(\mu_+ - \mu_-)},
\]

except that \( a_p \) and \( a_m \) are now defined as the constants that solve slightly different equations:

\[
\pi_+[\Theta(a_p) - \Theta(a_p^k)] = \pi_-[\Theta(a_m) - \Theta(a_m^k)] \quad (17)
\]
\[
\pi_+[\Theta(a_p) - \Theta(a_p^k)]\Delta = \pi_+[\Phi(a_p) - \Phi(a_p^k)] + \pi_-[\Phi(a_m) - \Phi(a_m^k)]. \quad (18)
\]
Here \( a^k_p \) and \( a^k_m \) are the additional constants depending on \( k \) that are defined as

\[
a^k_p = a_p - \frac{1 - k}{\|\Sigma^1/2 \beta^*\|}, \quad a^k_m = a_m - \frac{1 - k}{\|\Sigma^1/2 \beta^*\|}, \quad \text{and} \quad \|\Sigma^1/2 \beta^*\| = \frac{2}{a_p + a_m + \Delta}.
\]

Similar to other SVM type methods, except for the balanced case of \( \pi_+ = \pi_- \), only the optimal parameters \( \beta^* \) of the Huberized SVM are parallel to those of the LDA in general. For the balanced case, we can show that \( a^k_p = a^k_m (\equiv a^k) \), and \( \|\Sigma^1/2 \beta^*\| = \frac{2}{a_p + a_m + \Delta} \).

\[
(19)
\]

Given \( \Delta \) and fixed \( k \), we can solve the equation for \( a^* \). The last three columns in Table 1 show the values of \( a^* \) corresponding to the given values of \( \Delta \) when \( k = -1.5, -1, \) and \( 0 \), respectively.

In particular, under the balanced canonical LDA setting, the optimal parameters of the Huberized SVM are given by \( \beta_0^* = 0 \) and \( \beta^* = \frac{2}{(2a^* + \Delta)} e_1 \), where \( a^* \) is the constant satisfying (19). This yields \( \frac{\beta^*_\text{HSVM}}{\beta^*_\text{LDA}} = c_{\text{HSVM}} \cdot \frac{\beta^*_\text{LDA}}{\beta^*_\text{LDA}} \) with \( c_{\text{HSVM}} \equiv 2/(2a^* + \Delta^2) \) taking the same form as in the smooth SVM. With the limiting covariance matrix given in Appendix, we can show that the ARE of the Huberized SVM to LDA is given by

\[
\text{ARE}_{\text{HSVM}} = 2c_{\text{HSVM}} \left(1 + \frac{\Delta^2}{4}\right) \frac{[\Phi(a^*) - \Phi(a_k^*)]^2}{\Phi(a^*) - \Phi(a_k^*) + \frac{\Delta^2}{2}(k - 1)\Theta(a_k^*)}.
\]

### 3.3 Boosting

Similarly, the limiting distribution of the discriminant coefficients for boosting can be found, and its efficiency relative to the LDA in terms of the excess error rate can be evaluated. Without diminishing the merit of boosting in expanding a model space with weak learners in the LDA setting, we simply define the boosting estimator \( \hat{\beta} \) as the minimizer of (5) under the exponential loss criterion \( \rho(y, x; \beta_0, \beta) = \exp(-y(\beta_0 + \beta^T x)) \).

In the general LDA setting, the optimal discriminant coefficients under the exponential loss is given as

\[
\beta_0^* = \frac{1}{2} \left( \log \frac{\pi_+}{\pi_-} - \frac{1}{2}(\mu_+ - \mu_-)^T \Sigma^{-1}(\mu_+ + \mu_-) \right) \quad \text{and} \quad \beta^* = \frac{1}{2} \Sigma^{-1}(\mu_+ - \mu_-).
\]

First, we see that for every \( \pi_+ \) and \( \pi_- \), the optimal coefficient vector \( \beta^* \) for boosting is proportional to that of LDA, with the proportional constant \( c_{\text{boost}} = 1/2 \). Thus \( \hat{\beta} \) is a consistent estimator of \( (1/2)\beta^*_\text{LDA} \) in general. This ensures the Bayes risk consistency of boosting. See Appendix for the derivation of \( \hat{\beta} \) and the asymptotic distribution of discriminant coefficients.

Under the canonical LDA setting (2) with equal class proportions, the asymptotic relative efficiency of boosting to LDA is given by

\[
\text{ARE}_{\text{boost}} = \frac{1 + \Delta^2/4}{\exp(\Delta^2/4)}.
\]
Notice that the denominator is an exponential function of \( \Delta \), which implies that the relative efficiency of boosting drops very quickly as \( \Delta \) grows. This is attributed to the characteristic of boosting that it tends to focus heavily on misclassified cases or outliers in contrast to the LDA, which is based on the average pattern of the cases.

4 Comparisons Under Normal Setting

We compare the classification procedures theoretically by evaluating their relative efficiency for various degrees of class separation \( \Delta \). To contrast model-based classification methods with algorithmic methods in a simple theoretical framework, we focus on the balanced case of \( \pi_+ = \pi_- \) only in this section, where all the methods in consideration are proven to be consistent.

4.1 Theoretical Comparison with ARE

To cover scenarios with different degree of overlap between the two classes, we vary \( \Delta \) from 1 to 4. This range of \( \Delta \) corresponds to the Bayes error rates from 31\% to 2\% approximately. Table 2 gives the ARE values of the various methods considered in the foregoing section. First of all, the ARE values are less than one for each method compared to the LDA as a plug-in rule with the maximum likelihood estimators of the model parameters. So, the main focus of comparison in this normal setting is how much efficiency is lost in reducing the error rate when we bypass modeling of the underlying probability distribution in full.

The SVM and boosting, as large margin classifiers widely used in applications, are shown to be less efficient than logistic regression across the range of \( \Delta \) values. In other words, modeling at least the conditional probability helps use data more efficiently than maximizing classification margins under the hinge loss or the exponential loss. The efficiency of both methods relative to LDA diminishes quickly when the two classes become more separable. Between the two, the SVM is slightly more efficient than boosting as the latter heavily focuses on outlying observations near the classification boundary. Especially when two classes are nearly separable, boosting becomes very ineffective in using data. When the Bayes error is less than 6\%, boosting requires more than twice the data needed for the SVM to attain the same accuracy asymptotically.

Among the SVM and its variants, surprisingly, the smooth SVM turns out to be very efficient, even better than logistic regression and the vanilla SVM for each value of \( \Delta \). Probably, it can be, in part, explained by the analogue that regression with the squared error loss is often more efficient than its counterpart with the absolute deviation loss in estimating the mean especially in such situations as the normal setting. More explicitly, we note that there is a close connection between Fisher’s LDA and a naive regression approach to classification with class labels as the response. It can be shown that the least squares coefficient \( \hat{\beta} \) is identical up to a scalar multiple to the LDA coefficient, that is, \( \hat{\beta} \propto \hat{\Sigma}^{-1}(\hat{\mu}_+ - \hat{\mu}_-); \) see, for example, an exercise in Chapter 4 of Hastie et al. (2001). From the relation

\[
\sum_{i=1}^{n} (y_i - \beta_0 - \beta' x_i)^2 = \sum_{i=1}^{n} (1 - y_i (\beta_0 + \beta' x_i))^2,
\]
we see that squaring the hinge loss has a similar effect as the squared error loss. Moreover, the asymptotic analysis with the squared error loss confirms that the naive regression approach to classification is equivalent to the LDA in the limit under the canonical LDA setting with equal proportions. Raising the power of the hinge loss further to three did not improve the Smooth SVM in terms of ARE values. The cubed hinge loss was comparable to logistic regression (the results not shown in the table).

As an intermediate method, the Huberized SVM lies generally between the SVM and the smooth SVM in terms of the relative efficiency. As the bending constant \( k \) decreases, the Huberized SVM approaches the smooth SVM and its relative efficiency converges to that of the smooth SVM. When \( k \) is as small as \(-1.5\) as shown in Table 2, the Huberized SVM is virtually as efficient as the smooth SVM.

<table>
<thead>
<tr>
<th>( \Delta )</th>
<th>Bayes Error</th>
<th>Logistic Regression</th>
<th>SVM</th>
<th>Boosting</th>
<th>Smooth SVM</th>
<th>Huberized SVM</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( k = -1.5 )</td>
<td>( k = -1 )</td>
</tr>
<tr>
<td>1.0</td>
<td>0.3085</td>
<td>0.995</td>
<td>0.872</td>
<td>0.974</td>
<td>0.999</td>
<td>0.999</td>
</tr>
<tr>
<td>1.5</td>
<td>0.2266</td>
<td>0.968</td>
<td>0.829</td>
<td>0.890</td>
<td>0.981</td>
<td>0.981</td>
</tr>
<tr>
<td>2.0</td>
<td>0.1587</td>
<td>0.899</td>
<td>0.762</td>
<td>0.736</td>
<td>0.925</td>
<td>0.925</td>
</tr>
<tr>
<td>2.5</td>
<td>0.1056</td>
<td>0.786</td>
<td>0.664</td>
<td>0.537</td>
<td>0.820</td>
<td>0.820</td>
</tr>
<tr>
<td>3.0</td>
<td>0.0668</td>
<td>0.641</td>
<td>0.541</td>
<td>0.343</td>
<td>0.678</td>
<td>0.678</td>
</tr>
<tr>
<td>3.5</td>
<td>0.0401</td>
<td>0.486</td>
<td>0.411</td>
<td>0.190</td>
<td>0.521</td>
<td>0.520</td>
</tr>
<tr>
<td>4.0</td>
<td>0.0228</td>
<td>0.343</td>
<td>0.290</td>
<td>0.092</td>
<td>0.371</td>
<td>0.371</td>
</tr>
</tbody>
</table>

NOTE: The column for logistic regression has been taken from Efron (1975).

### 4.2 Numerical Comparison with Finite-Sample Excess Error

To complement the theoretical comparison for large sample case, we carried out numerical comparisons of the expected excess error rates of the procedures for finite samples by varying the sample sizes from small to large (50 to 1000).

Given sample size \( n \), we generated training data from the canonical LDA setting with five covariates and equal class proportions. Two values of \( \Delta \) were considered for simulation: \( \Delta = 2 \) with the Bayes error of 15.87%, and \( \Delta = 3 \) with the Bayes error of 6.68%. Then we applied the classification methods in Table 2 to each simulated data set, and calculated the excess error of each method analytically. We repeated this process 1000 times for each sample size, and estimated the expected excess error rate by using the average of the data-specific error rates over the 1000 replicates. To reduce the variance of the mean excess error estimate due to different data realization along the sequence of sample sizes, we generated nested training data; training data with smaller sizes are always included in the training data with larger sizes.

Figure 1 shows the mean excess error rates of the classification methods estimated for finite samples. The scale on the \( x \)-axis is \( 1/n \). The estimated mean excess error curves show strong linear relationship with \( 1/n \) as the asymptotic theory suggests. Overall the excess
error decreases to 0 at the rate of $1/n$. The LDA has the smallest slope (fastest reduction in error) followed by the Smooth SVM, logistic regression, the SVM, and boosting in the respective order as implied by the ARE comparison. This result suggests that the asymptotic comparisons are relevant even in moderate sample size cases. Table 2 indicates that as two classes become more separable, the efficiency of the other classification methods relative to the LDA drops. Figure 1 confirms that the increasing loss of efficiency occurs with the larger value of $\Delta$ for all the other methods in finite-sample cases.

5 Comparisons Under Model Mis-specification or Data Contamination

The analysis so far is under the LDA setting, expectedly yielding favorable results for the LDA. In practice, there are many factors that may complicate proper modeling of data. For instance, a model could be misspecified or part of data may not follow the specified model even when it is correctly specified. By taking into account such realistic constraints in data modeling, we consider two scenarios different from the LDA setting for more comprehensive comparisons.

5.1 Mislabling in LDA Setting

In the first scenario, we compare the robustness of the SVM and its variants when there is class label noise. To generate mislabeled data, we first simulate data from the canonical
Figure 2: Mean excess error rates of SVM and its variants from 400 replicates as the mislabeling proportion varies when $\Delta = 2.7$, $p = 5$, and $\pi_+ = \pi_-\text{ with the Bayes error rate of 8.851\%}$, and $n = 100$. The grey band indicates one standard error bound around the mean estimate for Huberized SVM from the replicates.

LDA setting and flip the class labels of a certain proportion of cases selected at random.

For simulation, the proportions of $\pm 1$ were set to equal, $p = 5$, and $\Delta = 2.7$, which yields the Bayes error rate of 8.851%. The sample size was $n = 100$, and 400 replicates of mislabeled samples with varying perturbation fractions were generated. Estimated discriminant functions were then evaluated in terms of the excess error rate from the Bayes error.

Figure 2 displays the mean excess error rates of the SVM, smooth SVM and Huberized SVM with $k = -0.5$ over the replicates as the perturbation fraction increases. When the mislabeling rate is small, the smooth SVM remains to be better than the SVM. However, as the mislabeling rate increases, the SVM results in lower error rate than the smooth SVM due to its robustness, analogous to the sample median and mean comparison in location parameter estimation. The Huberized SVM as a hybrid method strikes a balance between the two by combining the squared hinge loss and the plain hinge loss. The result indicates a trade-off between efficiency and robustness.

5.2 QDA Setting

The second scenario is when the Bayes error rate is not attainable due to model misspecification for model-based procedures and limitation in the family of discriminant functions for algorithmic procedures. As a scenario closely related to but different from the LDA setting, we consider a quadratic discriminant analysis (QDA) setting, where the covariance of one class is a scalar multiple of that of the other class:

\[
\begin{align*}
X & \sim N_p(\mu_+, \Sigma) \quad \text{with probability } \pi_+ = P(Y = 1) \quad \text{and} \\
X & \sim N_p(\mu_-, C\Sigma) \quad \text{with probability } \pi_- = P(Y = -1)
\end{align*}
\]  

(20)
with a constant $C$ greater than 1. Under this setting with $C > 1$, the Bayes boundary is no longer linear. Hence all linear classification methods compared here can not be consistent, and we need to take into account the inconsistency of the procedures in comparison.

For more meaningful comparison, consider the following decomposition of the excess error of a rule $\phi_n \in \mathcal{F}$ (a restricted class of discriminant functions, for example, linear functions in our case) based on a sample of size $n$:

$$R(\phi_n) - R(\mathcal{B}) = \{R(\phi_n) - R(\phi_\infty)\} + \{R(\phi_\infty) - R(\phi_\mathcal{F})\} + \{R(\phi_\mathcal{F}) - R(\phi_B)\},$$

where $\phi_\mathcal{F} = \arg \min_{\phi \in \mathcal{F}} R(\phi)$, and $\phi_\infty$ is the limiting rule of $\phi_n$ as $n$ goes to $\infty$. The first error difference on the right hand side is called the estimation error in the machine learning literature. It is due to finite sample and converges to zero as $n$ increases. The third difference is known as the approximation error, which is due to the restriction of $\mathcal{F}$ and common to all the linear procedures. It indicates the non-ignorable gap between the smallest error rate attainable within the class $\mathcal{F}$ and the Bayes error rate. Since the limiting rule $\phi_\infty$ depends on the method used to choose $\phi_n$ from $\mathcal{F}$, we call the first term a method-specific estimation error and the second term a method-specific approximation error. The method-specific approximation error is the key to capturing differences among the linear procedures in this QDA setting, providing the first order comparison.

For a linear classifier $\phi \in \mathcal{F}$ with discriminant coefficients $\underline{\beta}$ in the QDA setting, the error rate of $\phi$ is given by

$$R(\phi) \equiv R(\underline{\beta}) = \pi_+ \Phi \left( -\frac{\underline{\beta}' \mu_+ + \beta_0}{\sigma} \right) + \pi_- \left[ 1 - \Phi \left( -\frac{\underline{\beta}' \mu_- + \beta_0}{\sqrt{C} \sigma} \right) \right],$$

where $\sigma \equiv \sqrt{\underline{\beta}' \Sigma \underline{\beta}}$. Then the optimal linear classifier $\phi_\mathcal{F}$ can be identified with the minimizer $\underline{\beta}^*$ of $R(\underline{\beta})$:

$$\beta^* = \Sigma^{-1}(\mu_+ - \mu_-),$$

$$\beta_0^* = \sqrt{\frac{C \{(\mu_+ - \mu_-)' \beta^*\}^2}{(C - 1)^2}} + \frac{C \sigma^2 (2 \log \frac{\pi_+}{\pi_-} + \log C)}{C - 1} - \frac{C}{C - 1} (\mu_+ - \mu_-)' \beta^*.$$

To compute the method-specific approximation error of each method under consideration, we first obtain the limiting classification rule $\phi_\infty$ within $\mathcal{F}$ by applying large sample theory to the sample discriminant coefficients. Application of the standard asymptotics to the LDA and Theorem 1 to the rest of the methods yields the desired limiting rules. Due to page limitations, the results are omitted.

For numerical illustration, suppose that $p = 10$, $\pi_+ = 0.5$, $\Sigma = I$, $\mu_+ = (-1, 0, \ldots, 0)'$, and $\mu_- = (1, 0, \ldots, 0)'$ (hence with $\Delta \equiv \{(\mu_+ - \mu_-)' \Sigma^{-1} (\mu_+ - \mu_-)\}^2 = 2$) in the QDA setting of (20). The Bayes error rate is achieved by the theoretical quadratic discriminant analysis and can be expressed as

$$R(\phi_B) = \pi_+ P(\chi^2_{p, \lambda_1} > M) + \pi_- P(\chi^2_{p, \lambda_2} < \frac{M}{C}),$$

where

$$M = \frac{C}{(1 - C)^2} \Delta^2 - \frac{C}{1 - C} (2 \log \frac{\pi_+}{\pi_-} + p \log C),$$

and $\chi^2_{p, \lambda_1}$ and $\chi^2_{p, \lambda_2}$ are the chi-square random variables with degrees of freedom $p$ and non-centrality parameters $\lambda_1 = \frac{\Delta^2}{(1 - C)^2}$, and $\lambda_2 = \frac{C \Delta^2}{(1 - C)^2}$, respectively.
Figure 3: (a) Decomposition of the minimum linear classification error into the Bayes error and the approximation error; (b) Method-specific approximation error of linear classifiers in the QDA setting with $\Delta = 2$, $\Sigma = I$, $p = 10$, and $\pi_+ = \pi_-$. 

Figure 3(a) depicts the decomposition of the minimum linear classification error $R(\phi_f)$ into the Bayes error $R(\phi_B)$ and the approximation error, $R(\phi_f) - R(\phi_B)$, as we vary $C$ from 1 to 4. The height of the dark grey area shows the Bayes error rate, and that of the light grey region indicates the approximation error when $\mathcal{F}$ is restricted to linear classifiers in the QDA setting. Figure 3(b) shows the method-specific approximation errors for comparison as $C$ varies. When $C > 1$, the limiting error rates of the methods are greater than the smallest linear classification error in general. However, the effect of “model misspecification” or restriction to linear classifiers when, in fact, quadratic discriminant functions are needed, differs among the methods in terms of the increased error, $R(\phi_\infty) - R(\phi_f)$. As the extent of misspecification increases, the linear SVM turns out to be most robust to the change of $C$, followed by the LDA and smooth SVM. The approximation error of boosting grows more substantially than the other methods as $C$ increases.

6 Conclusion

This paper has shown that many popular classification methods can be compared analytically in terms of the efficiency in reducing error rates, using standard asymptotic techniques. Though the results are obtained under a special setting where clean analysis is feasible, they lead to interesting theoretical comparisons of the methods and shed light on their relative merits and drawbacks. When modeling approach is compared with algorithmic approach under the normal setting, it is found that modeling generally leads to more efficient use of data. In particular, the SVM is shown to be between 40% and 67% as effective as LDA while boosting is between 20% and 54% as effective as LDA, when the Bayes error rate ranges from 4% to 10%. However, a loss function plays an important role in determining the efficiency
of the corresponding procedure. The smooth SVM with squared hinge loss turns out to be more effective than logistic regression under the normal setting.

Since the correct form of a model is not known a priori in practice, it is important to understand the impact of model misspecification on the error rate. The comparisons under the QDA setting and the LDA setting with label noise indicate that there is a trade-off between efficiency and robustness.

The theoretical comparisons presented in this paper can be extended in many directions. To extend the scope of comparison to more complex settings with a nonlinear boundary, various probability models for two classes can be considered together with expanding families for discriminant functions. Possible models include the QDA setting with quadratic discriminant functions as an immediate extension and a mixture of several Gaussian components for each class. Further nonparametric generalization can be achieved via expansion of discriminant features, either by basis expansion or feature mapping through a kernel. Undoubtedly, analytical comparisons will become increasingly complex for nonparametric setting.

Another direction of extension is to allow the dimension $p$ to grow with sample size $n$. In the current analysis, the dimension of the attributes $p$ is assumed fixed, and the limiting behavior of a discriminant function is examined as $n$ goes to $\infty$. In the classical asymptotics setting, a probability model of modest complexity can be estimated reasonably well with a sufficient number of observations. However, one of the main challenges faced in modern data analysis is high dimensionality of data. Practical successes of such prediction-oriented classification procedures as the SVM and boosting partly lie in their ability to handle high dimensional features. In one of the earlier references of the SVM, Cortes and Vapnik (1995) noted how quickly the number of parameters to estimate increases in Fisher’s normal discriminant paradigm as the dimension of the feature space increases, and proposed to aim at classification boundary directly, instead of probability model parameters. Empirical evidence from numerical studies also points to potential advantages of non model-based methods for high dimensional data. To cope with the dimensionality, it is necessary to cast the procedures in a regularization framework for both technical and computational reasons. It would be interesting to extend the current analysis to high dimensional setting with proper regularization of discriminant coefficients and to study the effect of a different style of regularization on the error rate and efficiency. Theory of penalized $M$-estimators will be useful for comparisons of relative merits of the competing procedures; see, for example, Bühlmann and Van De Geer (2011), and see also Bickel and Levina (2004) and Rocha et al. (2009) for related results.

Appendix

This appendix contains derivations of the optimal discriminant coefficients and the asymptotic distribution of a coefficient vector for variants of the SVM and boosting in Section 3.
Smooth SVM

The risk of $\beta$ under the squared hinge loss in the LDA setting is given by

$$L(\beta) = \pi_+ \sigma^2 \left[ (a_p^2 + 1) \Phi(a_p) + a_p \phi(a_p) \right] + \pi_- \sigma^2 \left[ (a_m^2 + 1) \Phi(a_m) + a_m \phi(a_m) \right],$$

where $\sigma \equiv \sqrt{\beta^T \Sigma \beta}$, and $a_p$ and $a_m$ are defined in (9).

To identify the optimal coefficients $\beta^*$, we take the derivatives of $L(\beta)$ and equate them to zero:

$$\frac{\partial L(\beta)}{\partial \beta_0} = -2\pi_+ \sigma \left[ a_p \Phi(a_p) + \phi(a_p) \right] + 2\pi_- \sigma \left[ a_m \Phi(a_m) + \phi(a_m) \right] = 0$$

$$\frac{\partial L(\beta)}{\partial \beta} = -2\pi_+ \sigma \left[ a_p \Phi(a_p) + \phi(a_p) \right] \mu_+ + 2\pi_+ \Phi(a_p) \Sigma \beta + 2\pi_- \sigma \left[ a_m \Phi(a_m) + \phi(a_m) \right] \mu_- + 2\pi_- \Phi(a_m) \Sigma \beta = 0.$$

Letting $\Theta(z) \equiv z \Phi(z) + \phi(z)$ and $\omega^* \equiv \frac{\Sigma \frac{1}{\| \Sigma \beta^* \|}}{\Sigma \frac{1}{\| \Sigma \beta^* \|}}$, we can simplify the above equations to

$$\pi_+ \Theta(a_p) = \pi_- \Theta(a_m)$$

$$[\pi_+ \Phi(a_p) + \pi_- \Phi(a_m)] \Sigma \frac{1}{\| \Sigma \beta^* \|} \omega^* = \pi_+ \Theta(a_p) \mu_+ - \pi_- \Theta(a_m) \mu_-.$$ (22)

By solving the equations for $\beta^*$, we have the optimal parameters

$$\beta^*_0 = \frac{a_m - a_p}{a_p + a_m + \Delta} - \frac{1}{2} (\mu_+ + \mu_-) \| \beta^* \|^2$$

and $\beta^* = \frac{2}{a_p + a_m + \Delta} \Sigma^{-1} (\mu_+ - \mu_-)$, where $a_p$ and $a_m$ are the constants that solve the following equations:

$$\pi_+ \Theta(a_p) = \pi_- \Theta(a_m)$$

$$\pi_+ \Theta(a_p) \Delta = \pi_+ \Phi(a_p) + \pi_- \Phi(a_m).$$

The second equation comes from the fact that $\omega^*$ in (23) is a unit vector.

In the canonical LDA setting with equal probabilities, we can verify that

$$H(\beta^*) = \begin{pmatrix} 2 \Phi(a^*) & 0 \\ 0 & 2 \Phi(a^*) \mathbf{I}_p + M \mathbf{J}_p \end{pmatrix},$$

where $\mathbf{J}_p = \mathbf{e}_1 \mathbf{e}_1'$ and $M = \frac{\Delta^2}{2} \Phi(a^*) - 2(a^* + \Delta) \phi(a^*)$, and

$$G(\beta^*) = c_{\text{SSVM}} \Phi(a^*) \begin{pmatrix} 1 & 0 \\ 0 & \mathbf{I}_p + \frac{\Delta^2}{4} \mathbf{J}_p - c_{\text{SSVM}} \Delta^2 \mathbf{J}_p \end{pmatrix}.$$ (24)

Hence the limiting covariance matrix is

$$H(\beta^*)^{-1} G(\beta^*) H(\beta^*)^{-1} = c_{\text{SSVM}}^2 \begin{pmatrix} \kappa_1 & 0 & \cdots & 0 \\ 0 & \kappa_2 & \cdots & 0 \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & \kappa_1 & 0 \end{pmatrix}.$$
where \( \kappa_1 = \frac{(2a^* + \Delta) \Delta}{\Phi(a^*)} \) and \( \kappa_2 = \frac{2}{c_{\text{SSVM}} \Phi(a^*)} \) and \( \kappa_2 = \frac{8}{c_{\text{SSVM}} [2\Phi(a^*) + M]^2} \).

**Huberized SVM**

With some additional definition of constants depending on \( k \), we have the true risk of \( \beta_0 \) and \( \beta \) under the \( \rho_k \) in the LDA setting expressed as

\[
L(\beta) = \pi^+ \sigma^2 [(a_p + 1) \Phi(a_p) + a_p \phi(a_p)] + \pi^- \sigma^2 [(a_m + 1) \Phi(a_m) + a_m \phi(a_m)]
\]

\[
+ \pi^+ \Phi(a_p^k) [(1-k)(a_p + a_p^k)\sigma - (a_p^2 + 1)\sigma^2] + \pi^- \Phi(a_m^k) [(1-k)(a_m + a_m^k)\sigma - (a_m^2 + 1)\sigma^2]
\]

\[-\pi^+ \phi(a_p^k) a_p^k \sigma^2 - \pi^- \phi(a_m^k) a_m^k \sigma^2,
\]

where \( a_p^k \equiv \frac{k - \beta_0 - \beta' \mu_+}{\|\Sigma^+ \beta\|} \), and \( a_m^k \equiv \frac{k + \beta_0 + \beta' \mu_-}{\|\Sigma^- \beta\|} \). Then

\[
\frac{\partial L(\beta)}{\partial \beta_0} = -2\pi^+ \sigma [a_p \Phi(a_p) + \phi(a_p) - a_p^k \Phi(a_p^k) - \phi(a_p^k)] + 2\pi^- \sigma [a_m \Phi(a_m) + \phi(a_m) - a_m^k \Phi(a_m^k) - \phi(a_m^k)],
\]

and

\[
\frac{\partial L(\beta)}{\partial \beta} = -2\pi^+ \sigma [a_p \Phi(a_p) + \phi(a_p) - a_p^k \Phi(a_p^k) - \phi(a_p^k)] \mu_+ + 2\pi^+ [\Phi(a_p) - \Phi(a_p^k)] \Sigma \beta + 2\pi^- [\Phi(a_m) - \Phi(a_m^k)] \mu_- + 2\pi^- [\Phi(a_m) - \Phi(a_m^k)] \Sigma \beta.
\]

With the earlier definition of \( \Theta(z) = z \Phi(z) + \phi(z) \) and \( \omega^* \equiv \frac{\Sigma^+ \beta^*}{\|\Sigma^+ \beta^*\|} \), we can show that the optimality equation \( S(\beta) = 0 \) becomes

\[
\pi^+ [\Theta(a_p) - \Theta(a_p^k)] = \pi^- [\Theta(a_m) - \Theta(a_m^k)]
\]

\[
[\pi^+ \{\Phi(a_p) - \Phi(a_p^k)\} + \pi^- \{\Phi(a_m) - \Phi(a_m^k)\}] \Sigma^\frac{1}{2} \omega^* = \pi^+ [\Theta(a_p) - \Theta(a_p^k)] \mu_+ - \pi^- [\Theta(a_m) - \Theta(a_m^k)] \mu_-.
\]

Similar to the smooth SVM, the optimal parameters are expressed as

\[
\beta_0^* = \frac{a_m - a_p}{a_p + a_m + \Delta} - \frac{1}{2} \mu_+ + \mu_- \right)^' \beta^* \text{ and } \beta^* = \frac{2}{[a_p + a_m + \Delta] \Delta} \Sigma^{-1}(\mu_+ - \mu_-),
\]

where \( a_p \) and \( a_m \) are now defined as the constants that solve the following equations:

\[
\pi^+ [\Theta(a_p) - \Theta(a_p^k)] = \pi^- [\Theta(a_m) - \Theta(a_m^k)]
\]

\[
\pi^+ [\Theta(a_p) - \Theta(a_p^k)] \Delta = \pi^+ [\Phi(a_p) - \Phi(a_p^k)] + \pi^- [\Phi(a_m) - \Phi(a_m^k)].
\]

Note the relations that

\[
a_p^k = a_p - \frac{1 - k}{\|\Sigma^+ \beta^*\|}, \quad a_m^k = a_m - \frac{1 - k}{\|\Sigma^- \beta^*\|}, \quad \text{and } \|\Sigma^\frac{1}{2} \beta^*\| = \frac{2}{a_p + a_m + \Delta}.
\]
Under the balanced canonical LDA setting, the Hessian matrix $H$ is given by

$$H(\beta^*) = \begin{pmatrix}
2[\Phi(a^*) - \Phi(a_k^*)] & 0 \\
0 & 2[\Phi(a^*) - \Phi(a_k^*)]I_p + M_kJ_p
\end{pmatrix},$$

where $M_k = \frac{\Delta^2}{2} [\Phi(a^*) - \Phi(a_k^*)] - 2\Delta [\phi(a^*) - \phi(a_k^*)] - 2[a^*\phi(a^*) - a_k^*\phi(a_k^*)]$. Having the hybrid of a quadratic loss in the interval from $k$ to 1 and a linear loss below $k$ brings a slight change in the form of the $H$ as compared to the $H$ matrix of the smooth SVM. With similar changes in the elements, $G$ matrix is given by

$$G(\beta^*) = 8c_{\text{HSVM}} [\Phi(a^*) - \Phi(a_k^*)] + \frac{\Delta^2}{2} (k-1)\Theta(a_k^*) \begin{pmatrix}
1 & 0 \\
0 & I_p + \frac{1}{4}\Delta^2J_p
\end{pmatrix} - 8c_{\text{HSVM}} D_k \begin{pmatrix}
0 & 0 \\
0 & J_p
\end{pmatrix},$$

where

$$D_k = c_{\text{HSVM}}\Delta^2 [\Delta\{a^*(\Phi(a^*) - \Phi(a_k^*)) - (\phi(a^*) - \phi(a_k^*))\} - (\Phi(a^*) - \Phi(a_k^*))] - \Delta(k - 1)\phi(a_k^*).$$

Note that when $k$ goes to $-\infty$, $H(\beta^*)$ and $G(\beta^*)$ for the Huberized SVM above reduce to those for the smooth SVM. The limiting covariance matrix is

$$H(\beta^*)^{-1}G(\beta^*)H(\beta^*)^{-1} = c_{\text{HSVM}}^2 \begin{pmatrix}
\kappa_1 & 0 & \cdots & 0 \\
0 & \kappa_2 & \cdots & \vdots \\
\vdots & \ddots & \ddots & \vdots \\
0 & \cdots & 0 & \kappa_1
\end{pmatrix},$$

where

$$\kappa_1 = \frac{2[\Phi(a^*) - \Phi(a_k^*)] + \frac{\Delta^2}{2}(k-1)\Theta(a_k^*)}{c_{\text{HSVM}}[\Phi(a^*) - \Phi(a_k^*)]^2}$$

and

$$\kappa_2 = \frac{8 \left(1 + \frac{1}{4}\Delta^2\{\Phi(a^*) - \Phi(a_k^*)] + \frac{\Delta^2}{2}(k-1)\Theta(a_k^*)\} - D_k\right)}{c_{\text{HSVM}}[2(\Phi(a^*) - \Phi(a_k^*)] + M_k]^2}.$$

**Boosting**

Under the LDA setting in (1), the true risk is given by

$$L(\beta) = \pi_+ \exp \left(-\beta_0 - \beta'\mu_+ + \frac{1}{2}\beta'\Sigma\beta\right) + \pi_- \exp \left(\beta_0 + \beta'\mu_- + \frac{1}{2}\beta'\Sigma\beta\right).$$
Equating the gradient of $L(\beta)$ to 0 for the population minimizer $\beta^*$, we have

$$S(\beta) = \pi_+ \exp(-\beta_0 - \beta'\mu_+ + \frac{1}{2}\beta'\Sigma\beta) \left( -\mu_+^T \Sigma^{-1} \right) + \pi_- \exp(\beta_0 + \beta'\mu_- + \frac{1}{2}\beta'\Sigma\beta) \left( \mu_-^T \Sigma^{-1} \right) = 0.$$ 

By solving the equation for $\beta$, we have

$$\beta_0^* = \frac{1}{2} \left( \log \frac{\pi_+}{\pi_-} - \frac{1}{2}(\mu_+ - \mu_-)'\Sigma^{-1}(\mu_+ - \mu_-) \right) \quad \text{and} \quad \beta^* = \frac{1}{2}\Sigma^{-1}(\mu_+ - \mu_-).$$

The $H$ and $G$ matrices under the exponential loss in the general LDA setting are given by

$$H(\beta^*) = \sqrt{\frac{\pi_+}{\pi_-}} \exp \left\{ -\frac{1}{8}(\mu_+ - \mu_-)'\Sigma^{-1}(\mu_+ - \mu_-) \right\} \begin{pmatrix} 2 & (\mu_+ + \mu_-)' \\ \mu_+ + \mu_- & 2\Sigma + (\mu_+ + \mu_-)(\mu_+ + \mu_-)' \end{pmatrix}$$

and

$$G(\beta^*) = \begin{pmatrix} 1 & (\pi_+\mu_+ + \pi_-\mu_-)' \\ \pi_+\mu_+ + \pi_-\mu_- & \Sigma + \pi_+\mu_+\mu_+' + \pi_-\mu_-\mu_-' \end{pmatrix}.$$ 

Under the canonical LDA setting (2) with equal class proportions, they are simplified to

$$H(\beta^*) = \exp \left( -\frac{\Delta^2}{8} \right) I_{p+1}, \quad \text{and} \quad G(\beta^*) = \begin{pmatrix} 1 & 0 \\ 0 & I_p + \frac{1}{4}J_p \end{pmatrix},$$

where $J_p = e_1e_1'$. Hence the limiting covariance matrix of the discriminant coefficient vector is

$$H(\beta^*)^{-1}G(\beta^*)H(\beta^*)^{-1} = \exp \left( -\frac{\Delta^2}{4} \right) \begin{pmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 + \frac{1}{4} & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots \\ 0 & \cdots & 1 & 1 \end{pmatrix}.$$ 

References


